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Framework for studying Spatially Ordered Treemaps

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Abstract. We propose a comprehensive research framework to empirically investigate complex *visual inference tasks, support mechanisms* (animated transition using morphing or vector overlay), and how *spatial ability* affects people's learning and knowledge construction process from Spatially Ordered Treemaps (SOTs) as compared to conventional choropleth maps. This effort is inspired by the call of the new International Cartographic Association commission on Cognitive Visualization (CogVis), which proposes "*developing a sound theoretical framework based upon cognition and perception discipline*" (Fabrikant, 2011). The framework aims to explore SOTs in the context of both '*in-vitro*' and '*in-vivo*' settings. This study is grounded in cartography but also conforms to experimental design standards in perception and cognitive sciences.

Keywords: Spatially Ordered Treemaps, Geovisualization, Visual Tasks, Spatial Ability

1. Introduction

We now live in an era of data deluge, where our ability to generate data outstrips our ability to analyse it. Organizations collect and have access to large amounts of data with the aim of getting some benefit from it. Whilst organizations acknowledge the value and importance of their data, many do not know how to make sense of the information or what to do with it (Few, 2011). Maps have a long tradition of being used to make sense of information. However, in this data dense era, conventional methods and traditional GIS tools do not support or meet the constant emerging user needs (Andrienko *et al.*, 2007). Spatially Ordered Treemaps (SOTs) are designed to address some of these needs (Wood & Dykes, 2008). SOTs are space-filling graphics that show hierarchical geographic information in a space efficient way, using one rectangle per data item in an iterative manner through the hierarchy. Unlike the conventional choropleth maps (usually sized by geo-

graphical area), SOTs can be sized according to need – for example by population (number of people living in an area) to result in a space filling hierarchical cartogram (Wood & Dykes, 2008a; 2008b). Although, SOTs have been used in various applications e.g. in local government (Figure 1) to manage and allocate resources (LCC, 2010), we lack empirical evidence on how effective the technique is in communicating spatio-temporal data either for educational purposes or for knowledge discovery.

1.1. Theory

Treemaps are space-filling graphics that show hierarchical data in a space efficient way using one rectangle per data item in an iterative manner through the hierarchy (Shneiderman, 1992). Most treemap layout algorithms use one-dimensional ordering of rectangles. With SOTs, two-dimensional ordering is used and rectangles corresponding to geographical areas are arranged in an approximate spatial layout to produce “a space filling cartogram” (Wood & Dykes, 2008a; 2008b) that distorts spatial geometry to reflect thematic information. A cartogram is a map that distorts spatial geometry to correspond to a theme (Tobler, 2004). In light of these spatial distortions, support mechanisms such as morphing, overlay vectors and colour have been designed in SOTs to aid the user in understanding the topology after transformation (Wood & Dykes, 2008b).

Research efforts on treemaps can be broadly divided into two: development of effective treemap algorithms and evaluation of use of the outputs (Kong *et al.*, 2010). But none of these efforts deal with the kinds of complex spatial tasks for which maps are so effective (MacEachren, 1995).

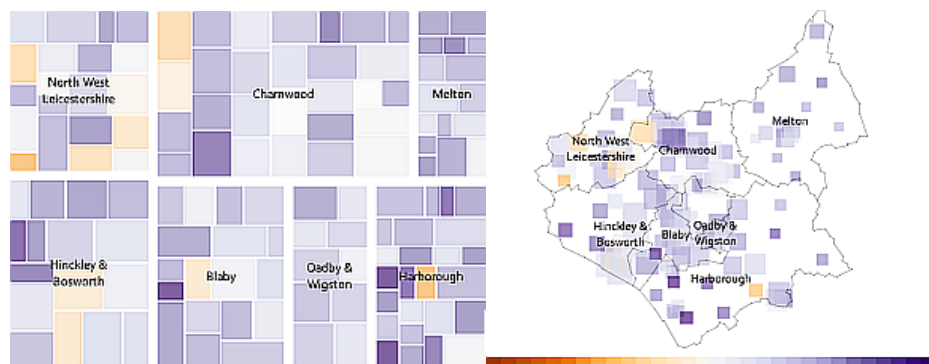


Figure 1. A SOT (left) and a conventional geographical map (right) of Leicestershire showing satisfaction (purple) and dissatisfaction (orange) with public services. Population and hierarchy are emphasized and local dissatisfaction in Hinckley & Bosworth is more evident in the population sized SOT when compared to the geographic map.

2. Research Framework

Our framework aims to formally evaluate the effectiveness of treemaps in the geographic context for the first time. Our aim is to increase our understanding of graphical perception with regards to SOTs. This will in turn inform us on the strengths and limitations of SOTs for communicating and exploring geographic information. Table 1 gives an overview and characteristics of the study at different stages. The specific tasks for stages Ia, Ib & Ic are further elaborated in Tables 2, 3 & 4. The tasks for stage II are discussed in section 3.

Context	'in-vitro'			'in-vivo'
Stages	Stage Ia	Stage Ib	Stage Ic	Stage II
Tasks	Locate	Compare	Distribution	Distribution, Interaction
Data collection	Online Questionnaires			Questionnaires, Interview & Observation
Data type	Quantitative			Qualitative
Participants' characteristics	Our target population are numerate information seekers with experience of using data and graphics			Experts
Sample size	Many			Few
Study design	Between- subject			Case study

Table 1. An overview of the proposed study

2.1. Stage I: Identifying suitable tasks for SOT

Under the '*in-vitro*' setting, the key question under consideration is: "*to what extent are people able to interpret data and geography in a SOT as they would in choropleth maps*". This will be evaluated through spatial graphical perception tasks that require regional comparison and the interpretation of general spatial distributions. Our independent experimental factors are *map type* and *task*.

2.1.1. Map type

Informationally equivalent stimuli (Figure 2) using the choropleth and SOT techniques will be generated. Numeric calculation of distance, angle displacement and adjacency will be used to establish the degree to which the SOT reflects the conventional mapping. Choropleth will be sized by land area, while SOTs will be sized by attribute i.e. population. Characteristics to be held constant between the two displays include colour, padding, outlines and the depth of hierarchy. The geometry of regions, number of enumerati-

on units and spatial characteristics of the mapped distribution will be varied systematically. Spatial characteristics of the distribution (data) will be varied according to established spatial statistics.

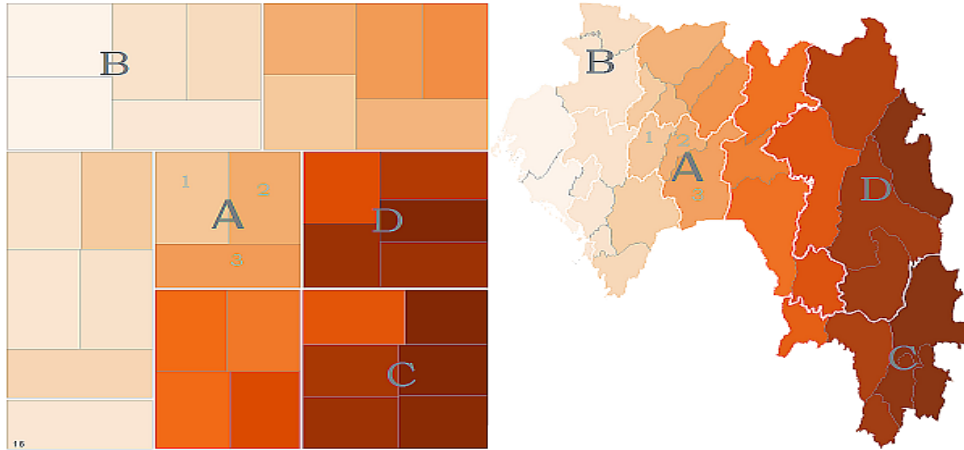


Figure 2. A SOT and equivalent Choropleth map showing the geographic hierarchy: the whole *area*, *regions* (A,B,C,D) and *districts* (1,2,3) .

2.1.2. Tasks

Tasks types are informed by a comprehensive review of the literature (e.g. Bertin, 1967; Andrienko & Andrienko, 2006). Tasks have been designed to reflect the multiple and complex ways in which maps are used and the hierarchical emphasis for which SOTs were proposed. Thus, we separated tasks that require participants to only use spatial thinking (*Geographical*), tasks that do not require spatial thinking (*Statistical*) and tasks requiring both forms of (*Statistical Geographical*) thinking. These latter tasks are those for which SOTs were designed, but they rely upon performing the individual task types effectively. Each task is further divided into direct or inverse, according to (Andrienko & Andrienko, 2006): When reading maps we are either interested in the characteristic that correspond to a given target (*direct*) or what target corresponds to a given characteristics *inverse*. Hierarchical tasks (marked {H}) are also integrated in this framework with individual spatial units (*districts*) considered in the context of groups of such units (*regions*). These tasks demand varying cognitive effort. It is hypothesized that statistical and statistical geographical tasks may be performed more effectively using SOTs - particularly when these involve hierarchy – at the expense of some geographic accuracy.

Statistical	Direct	Find the value of a specific district/region <i>What is the value of district A /region 1?</i> <i>Describe (What is) the value (of population) within region 1 {H}</i>
	Inverse	Restricted by a value (high/low) find a district or a region. <i>List 5 districts with high values</i> <i>List 5 districts with high values within region 1{H}</i>
Statistical/Geographical	Direct	Find districts/regions restricted by value relations then by geographical location. <i>List 5 districts with high values that are to south of region 1</i> <i>List 5 districts with high values that are north of district A and within region 1 {H}</i>
	Inverse	Find districts/regions restricted by geographical location then by value relation <i>Find 5 districts that are north of district A that have high values.</i> <i>Find 5 districts within the same region as district A and south of district B (or C) that have high values {H}</i>

Table 2. Locate tasks: requiring value estimation for individual spatial units or regions.

Statistical	Direct	Find and compare value of a specific district with others. <i>Between districts A, B, C & D, which one has the lowest value</i> <i>Between regions 1, 2, 3 & 4, which one has the highest value? {H}</i>
	Inverse	Restricted by value (high to low) districts should be ordered in this sequence. <i>From high to low, arrange districts A, B, C & D in order of overall population</i> <i>From high to low, arrange regions 1,2,3 & 4 in order of overall population {H}</i>
Geographical	Direct	Judge distance and find the location between districts/regions <i>Between districts A, B and C, which district is closer to district D?</i> <i>Between districts A, B and C, which district is [either within region 1 within the same region as district D within a different region to district D]?{H}</i>
	Inverse	A district is restricted by location, then judging by distance to a specific district/region <i>Between districts A, B, C & D, which district is closest to both regions 1 and 2?</i> <i>Between districts A, B, C & D, which district are in the same region as district 1 and 2?{H}</i>
Statistical/Geographical	Direct	Find districts restricted by value relations then by geographical locations. <i>Are the districts with high values closer to A or B?</i> <i>Are the districts with higher values within region 1 or 2?{H} or</i> <i>In which direction are the districts with high values from A?</i> <i>Are the districts with high values within the same region as district 1 or 2? {H}</i>
	Inverse	Find districts restricted by geographical location then by value relations <i>Are more districts with values like C closer to A or B?</i> <i>Are more districts with higher values than C within region A or B?{H}</i>

Table 3. Comparison tasks: requiring geographical (distance) or value estimation judgment between spatial units or regions.

Flat : Identify similarity between maps (SOTs or Choropleth) by looking at spatial distribution. For example, participants are presented with a SOT, next to it there are 5 choropleths.
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<i>Which map looks most similar to the one presented?</i>

Table 4. Distribution tasks: requiring overall area assessment of the map.

3. Stage II: Identifying support mechanisms and metaphors for supporting data exploration when using SOTs.

The *'in-vivo'* setting in which we will be working involves epidemiologists who use maps frequently. The key question under consideration is: *"to what extent are support mechanisms useful during data exploration and interpretation of general spatial distributions?"* Cartograms have been found to be difficult to interpret without some kind of support (Tobler, 2004). Similarly, since SOTs distort locations and result in new layouts that are sensitive to aspect ratio, somewhat arbitrary and non-linear in their transformation of space. We intend to evaluate how various support mechanisms may help establish their geography. Firstly, we are considering animated transitions (e.g. morphing) for comparing one layout to another so that geographic and SOT locations can be compared (Heer & Robertson, 2007). This is because there is some evidence animated transition aids in understanding statistical graphics. Secondly we are considering linked views with displacement vectors (Wood & Dykes, 2008b) that visually indicate the topologic distortion: the length of the vector indicates distance while curvature indicates the direction of distortion from the element's original location.

4. Investigating the effects of spatial ability on tasks

Data exploration and map reading is more than a perceptual comparison of symbols, it is a cognitive process (MacEachren *et al.*, 1992). There is evidence that cognitive skills such as spatial ability have an effect on visualiza-

tion tasks and can be used to identify individual differences (Hegarty & Waller, 2006). Identifying individual differences is key because once a group is known, tools or educational training can be customized towards their needs (Slocum *et al.*, 2001). However, very few studies in cartography and geovisualization have studied individual spatial ability differences (Wilkening & Fabrikant, 2011). Two forms of spatial ability test, *paper folding* and *mental rotation* will investigate how subjects' task performance (with respect to SOTs) is modulated by their spatial ability to give us insights into *why* and *for whom* this spatial transformation may be effective (Fabrikant, 2011).

5. Work plan

In the coming months we intend to run several experiments using the tasks identified in section 2.1.2. The target sample is numerate information seekers with experience of using data and graphics who are also potential users of SOTs. We are currently recruiting participants having received ethical approval to undertake the tests from our institution.

6. Conclusion

We propose a research framework for empirically assessing the effectiveness of SOTs for communicating and exploring geographic information through relative complex tasks involving geography, statistics and hierarchy. The proposed study is grounded in cartography and it is informed by experimental design standards from perceptual and cognitive disciplines. We first approached this research by systematically identifying and designing complex perception tasks for which SOTs are designed. We specifically focused on tasks that require regional comparison and the interpretation of general distributions. We will also measure subjects' cognitive abilities using spatial abilities test such as *mental rotation* and *paper folding* to validate their performance. The experimental setting will include both *in-vitro* and *in-vivo* settings. With these studies we hope to increase our knowledge of graphical perception and better understand how people make inferences and interpret, use and learn the abstract semi-geographic layouts produced by the SOT during data exploration for knowledge discovery and construction.

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