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Numerical investigation of bubble dynamics using tabulated data

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Abstract

An explicit density-based solver of the compressible Euler equations suitable for cavitation simulations is presented, using the full Helmholtz energy Equation of State (EoS) for n-Dodecane. Tabulated data are derived from this EoS in order to calculate the thermodynamic properties of the liquid, vapour and mixture composition during cavitation. For determining thermodynamic properties from the conservative variable set, bilinear interpolation is employed; this results to significantly reduced computational cost despite the complex thermodynamics model incorporated. The latter is able to predict the temperature variation of both the liquid and the vapour phases. The methodology uses a Mach number consistent numerical flux, suitable for subsonic up to supersonic flow conditions. Finite volume discretization is employed in conjunction with a second order Runge-Kutta time integration scheme. The numerical method is validated against the Riemann problem, comparing it with the exact solution which has been derived in the present work for an arbitrary EoS. Further validation is performed against the well-known Rayleigh collapse of a pure vapour bubble. It is then used for the simulation of a 2-D axisymmetric n-Dodecane vapour bubble collapsing in the proximity of a flat wall placed at different locations from the centre of the bubble. The predictive capability of the incorporated Helmholtz EoS is assessed against the widely used barotropic EoS and the non-isothermal Homogeneous Equilibrium Mixture (HEM).

Keywords: Bubble dynamics, cavitation, Helmholtz equation of state, exact Riemann solver

Nomenclature

U	Conservative variable vector
F	r-flux vector
G	z-flux vector
S	Geometric source vector
ρ	Density (kg/m^3)
u_r	Velocity in the r-direction (m/s)
u_z	Velocity in the z-direction (m/s)
p	Pressure (Pa)
e	Internal energy (J/kg)
e_{liq}	Internal energy of the liquid (J/kg)
e_{vap}	Internal energy of the vapour (J/kg)
E	Total energy (J/kg)
s	Geometric source term, unity for cylindrical symmetry and two for spherical symmetry (-)

r	Distance from the axis/point of symmetry, needed in the geometric source term (m)
n	Normal surface vector
a	Molar Helmholtz energy (J)
a^0	Ideal gas contribution to the Helmholtz energy (J)
a^r	Residual Helmholtz energy, responsible for the influence of Intermolecular forces (J)
α^0	Dimensionless ideal gas contribution to the Helmholtz energy (-)
α^r	Dimensionless residual Helmholtz energy (-)
p_c	Critical pressure (Pa)
ρ_c	Critical density (kg/m^3)
p_{sat}	Saturation pressure (Pa)
$\rho_{sat,L}$	Liquid density at saturation (kg/m^3)
$\rho_{sat,V}$	Vapour density at saturation (kg/m^3)
B	Liquid bulk modulus (Pa)
C	Speed parameter (Pa·kg/m^3)
n	Tait equation parameter, equal to 7.15 for weakly compressible liquids (-)
T_0	Initial temperature (K)
C_{vl}	Specific heat at constant volume for the liquid (J/(kg·K))
C_{vv}	Specific heat at constant volume for the vapour (J/(kg·K))
e_{l0}	Internal energy at reference temperature T_0 (J/kg)
L_v	Latent heat (J/(kg·K))
R	Specific gas constant (J/(kg·K))
γ	Ratio of specific heats (-)
N_{mn}	Finite element nodal shape function of node n, evaluated at node m (-)

1. Introduction

Many studies deal with the dynamics of vapour bubbles, both computationally and experimentally, due to the implications they have in a number of physical conditions and technological applications. Up to now, different approaches have been proposed for simulating bubble collapse dynamics, such as potential flow solvers with dynamic boundary conditions on the bubble surface, homogeneous mixture models and interface tracking/capturing methods.

Methodologies based on potential flow solvers have been among the first employed to simulate the collapse of bubbles. For example, Plesset and Chapman (1971) were the first to study cavitation bubble collapse close to a solid surface. A potential flow solver was used for the liquid phase and a Marker-and-Cell technique was developed for tracking the bubble interface. A similar flow solver was employed by Zhang et al. (1993), (1994) but a Boundary Element Method was incorporated for predicting the shape of the bubble and the pressure profile on the wall. In an extension of the BEM method, Wang (2014) employed a combination of compressible and incompressible potential flow for the simulation of a bubble collapse in the vicinity of a wall, aiming to describe the energy loss due to pressure waves radiated during the bubble collapse. The advantage of the BEM methodology is that only the bubble interface is discretized and resolved, transforming the 3D problem to a 2D one. However, mesh handling is problematic when topological changes of the bubble interface have to be taken into consideration, e.g. during bubble jet formation or impact on walls. For that reason, Chahine (2014) used a coupling between an incompressible BEM potential flow solver and a multiphase compressible flow solver based on the Euler equations for simulating the growth and collapse of a bubble in the vicinity of (deformable) walls. Each solution strategy was employed at different stages of the bubble development; for the violent growth

and collapse of the simulated bubble the compressible multiphase approach was used, whereas the BEM method was employed at intermediate stages where flow velocities are small.

Adams and Schmidt (2013) used a single fluid model and simulated the collapse of a bubble cluster consisting of 125 bubbles. The model was based on the Equation of State (EoS) for the pure phases, and thus, no empirical parameters and tuning were needed. The main assumption in this model is that the two-phase regime is in thermodynamic and mechanical equilibrium. Although this assumption may not be valid in metastable thermodynamic states, the model is accurate enough for medium and large scale simulations of cavitating flows. A similar work by Schmidt et al. (2008) emphasized on the detection of the shock formation and propagation in three dimensional cloud cavitation. Despite the limitation of not explicitly defining the bubble interface, such models are still widely used due to their simplicity; this limitation has been proved not to be important, since the bubble interface can be estimated by the density variation when using an adequate cell resolution. Since the bubble interface may be somewhat diffuse, surface tension is commonly neglected. In any case the effect of this assumption is minor, since surface tension plays a minor role during bubble collapse, which is mainly governed by inertia.

Overcoming the limitation of the previous methods, front tracking methods, which have been originally developed by Glimm et al. (1985) and a follow-up study by Unverdi and Tryggvason (1992), offer higher accuracy in resolving the exact bubble shape. For example, the Lagrangian method of Hawker and Ventikos (2009), (2012) used a marker to track the liquid-gas interface; the computational mesh was divided in two regions, with different EoS applied for the two phases. In addition, Popinet et al. (2002) used a front-tracking approach while free surface boundary conditions were imposed for simulating bubble flows near solid boundaries. The main advantage of this methodology is that it allows for smear-free interfaces, resulting in sharp interfaces for large scale problems and can model diffuse interfaces in smaller scales. Another feature of the front-tracking method is that it can be applied to complex geometries while it allows for large deformations of the surface to be simulated. The main drawback of front-tracking methods is their complexity, since the interface grid must be dynamically reconstructed, either adding or removing nodes in areas of stretched or compressed cells, respectively (Unverdi and Tryggvason, 1992).

Interface capturing schemes based on the VOF methodology have been also employed to the simulation of cavitation bubbles. For example, Li et al. (2014) investigated the bubble collapse near a conical rigid boundary, formulating an extension to the classical Rayleigh collapse time, incorporating the wall stand-off distance and the cone angle. Koukouvinis et al. (2016b), (2016c) investigated the effect of asymmetries (e.g. pressure gradient and free surfaces) affecting the bubble collapse, using the VOF technique, and demonstrating jetting effects and bubble shape at collapse stages. Hu et al. (2006) developed a conservative interface method based on the level set technique for solving compressible multiphase flows, maintaining a sharp liquid-gas interface. The methodology was tested in fundamental shock tube cases, bubble-shock wave interactions and underwater explosions. In connection to the previous work, Lauer et al. (2012) used a Level-Set method for bubble dynamics, including non-equilibrium thermodynamic effects and finite mass transfer based on the Hertz-Knudsen relation, while exploring the effect of the wall distance on the bubble shape during collapse; this methodology is also discussed in Adams and Schmidt (2013). While admittedly the discussed interface capturing methodologies can provide a sharp interface, the concept of "interface capturing" is questionable when pressures reach close to the critical point, since

liquid and vapour densities become similar and surface tension diminishes, preventing a clear distinction between the two phases.

In the previous studies, thermal effects are typically ignored or are considered utilising simplified EoS. In two-fluid models that utilise interface capturing methods, the common assumption is to prescribe a finite mass transfer rate across the bubble interface, describing the evaporation and condensation processes. On the other hand, in single-fluid models mechanical and thermal equilibrium is assumed and the mass transfer is assumed to be infinite. A subcategory of the latter is the barotropic cavitation model, where the pressure is linked to density only, ignoring the effect of temperature; such models have been successfully used for the prediction of cavitation either on macroscopic (e.g. hydrofoils (Dular and Coutier-Delgosha, 2009), venturi (Decaix and Goncalvès, 2013), or high pressure throttle flows (Koukouvinis and Gavaises, 2015)), or single bubble collapses (Koukouvinis et al., 2016a).

The current study expands the previous work of Koukouvinis et al. (2016a) where central upwind schemes were used for bubble dynamics simulations, following an isentropic process assumption and using a 2 step barotropic EoS. Comparing with the aforementioned study, in the current work we aim to examine heating effects during the collapse of a vaporous bubble, which have been omitted or simplified in previous studies. The thermodynamic closure used is based on the Helmholtz energy EoS from NIST Refprop databases (Lemmon and Huber, 2004), which can provide thermodynamic properties at subcritical and supercritical conditions in a consistent framework. It is highlighted that in reality bubbles contain an amount of non-condensable gases, which in the present study has been omitted. However, our interest is to examine the temperature changes of the dodecane liquid, due to the extreme pressurisation during bubble collapse.

The homogeneous equilibrium model (HEM) approach is used, where each thermodynamic property can be expressed as a function of density and internal energy. Following the methodology of Dumbser et al. (2013), tabulated EoS are employed in the present explicit density-based algorithm; the low Mach number problem is tackled by the hybrid flux model of Schmidt et al. (2008). By using the Helmholtz EoS, a complex thermodynamic model is incorporated in the finite volume solver, while the tabulated data algorithm is proved to be more efficient than using iterative property calculation methods for each time step. To the author's best knowledge, this is the first work implementing the Mach consistent numerical flux in connection with real fluid properties for n-Dodecane, demonstrating heating effects in bubble collapse cases; the only relevant work is that of Dumbser et al. (2013), who focused instead on water/vapour behaviour in benchmark (e.g. shock tube, explosion/implosion, forward step) and macroscopic (e.g. hydrofoil) cases.

The paper is organized as follows. In section 2 the numerical method is presented, including the EoS representing the thermodynamic properties of n-Dodecane and time/space discretization methods employed. In section 3 the results are presented and discussed. Validation of the numerical method is performed against the exact solution of the Riemann problem for the EoS under consideration. Further validation is performed against the benchmark Rayleigh vapour bubble collapse. Then several bubble configurations of vapour bubble collapse near a solid boundary are examined utilizing three different thermodynamic models (barotropic, non isothermal HEM and Helmholtz EoS). The most important conclusions are summarised in section 4. Finally, in the Appendix section, the methodology for deriving the exact solution for an arbitrary EoS where pressure is a function of both density and internal energy is discussed. This methodology was used to obtain the exact

solution for the benchmark Riemann problem; however it may be applied in general for any applicable EoS.

2. Numerical Method

Since bubble growth and collapse is an inertial phenomenon, the viscosity and surface tension are neglected in the present study (Zhang et al., 1993). The 2D Euler equations in *r*-*z* cylindrical coordinates with a geometric source term in order to take into account cylindrical symmetry (Toro, 2009) are:

$$\mathbf{U}_t + \mathbf{F}(\mathbf{U})_r + \mathbf{G}(\mathbf{U})_z = \mathbf{S}(\mathbf{U}), in\ \Omega \tag{1}$$

where *t, r, z* subscripts indicate differentiation with respect to time, *r* direction and *z* direction respectively. **U** is the conserved variable vector, **F**(**U**) and **G**(**U**) are the fluxes at the radial (*r*) and axial (*z*) directions respectively and **S**(**U**) is the geometric source term, to take into account axial symmetry. Ω represents the volume of the computational domain, while $\partial\Omega$ the boundary of the domain. The vectors of eq. 1 are:

$$\mathbf{U} = \begin{bmatrix} \rho \\ \rho u_r \\ \rho u_z \\ \rho E \end{bmatrix}, \mathbf{F}(\mathbf{U}) = \begin{bmatrix} \rho u_r \\ \rho u_r^2 + p \\ \rho u_r u_z \\ (\rho E + p) u_r \end{bmatrix}, \mathbf{G}(\mathbf{U}) = \begin{bmatrix} \rho u_z \\ \rho u_r u_z \\ \rho u_z^2 + p \\ (\rho E + p) u_z \end{bmatrix}, \mathbf{S}(\mathbf{U}) = -\frac{s}{r} \begin{bmatrix} \rho u_r \\ \rho u_r^2 \\ \rho u_r u_z \\ u_r (\rho E + p) \end{bmatrix} \tag{2}$$

where ρ is the fluid density, u_r and u_z the radial and axial velocity components respectively, p is the pressure, E is the total internal energy, equal to $\frac{1}{2}\left(u_r^2 + u_z^2\right) + e$, e is the internal energy of the fluid and s is the geometric source term. For cylindrical symmetry, s is equal to unity.

The following initial and boundary conditions are used for the PDE system:

Initial condition: $\mathbf{U}(r,z,t=0) = \mathbf{U}_0(r,z),\ in\ \Omega$ (3)

Dirichlet type boundary condition: $\mathbf{U} = \mathbf{U}_D,\ on\ \partial\Omega_D$ (4)

Neumann type boundary condition: $\frac{\partial \mathbf{U}}{\partial \mathbf{n}} = \mathbf{U}_N,\ on\ \partial\Omega_N$ (5)

2a.Helmholtz energy equation of state for n-Dodecane

In this section, the derivation of properties of n-Dodecane from the Helmholtz energy, is discussed. The Helmholtz energy is calibrated within the temperature range $263.6 \le T \le 700\,K$, for maximum pressure $p_{max} = 700\,MPa$ and maximum density $\rho_{max} = 771.62\ kg/m^3$ (Lemmon and Huber, 2004). Due to the violent bubble collapses to be examined later on, local conditions may exceed the aforementioned limits. Thus, the Helmholtz equation was applied to derive thermodynamic properties beyond the aforementioned calibration; even though there is no guarantee that the calibration of the Helmholtz equation is valid in this regime, the derived properties have been checked for consistency (e.g. increasing density as pressure increases, for given temperature) and were found to behave in a reasonable manner, i.e. no inflexion or stationary points were found, indicating a monotonic behaviour of the property functions.

The EoS for calculating the thermodynamic properties of n-Dodecane fuel can be expressed using the Helmholtz energy, having as independent variables density and temperature (Lemmon and Huber, 2004):

$$a(\rho,T) = a^0(\rho,T) + a^r(\rho,T) \tag{6}$$

The above in dimensionless form becomes:

$$\frac{a(\rho,T)}{RT} = \alpha(\delta,\tau) = \alpha^0(\delta,\tau) + \alpha^r(\delta,\tau) \tag{7}$$

where $\delta = \rho / \rho_c$, $\tau = T_c / T$.

The dimensionless Helmholtz energy of the ideal gas can be written in the form:

$$\alpha^0 = a_1 + a_2\tau + ln\delta + (c_0 - 1)ln\tau + \sum_{k=1}^{5} c_k ln\left[1 - exp\left(-\frac{u_k\tau}{T_c}\right)\right] \tag{8}$$

where a_1, a_2 are arbitrary values set by the reference state. The residual Helmholtz energy is written in the following non-dimensional form:

$$\begin{aligned}\alpha^r(\delta,\tau) = {} & n_1\delta\tau^{0.32} + n_2\delta\tau^{1.23} + n_3\delta\tau^{1.5} + n_4\delta^2\tau^{1.4} + n_5\delta^3\tau^{0.07} + n_6\delta^7\tau^{0.8} \\ & + n_7\delta^2\tau^{2.16}exp^{-\delta} + n_8\delta^5\tau^{1.1}exp^{-\delta} + n_9\delta\tau^{4.1}exp^{-\delta^2} + n_{10}\delta^4\tau^{5.6}exp^{-\delta^2} \\ & + n_{11}\delta^3\tau^{14.5}exp^{-\delta^3} + n_{12}\delta^4\tau^{12.0}exp^{-\delta^3}\end{aligned} \tag{9}$$

Equation 7 may be manipulated to obtain all important thermodynamic properties, like pressure *p*, internal energy *e*, enthalpy *h*, entropy *s* and speed of sound *c* as a function of density ρ and temperature *T*; the interested reader is addressed to (Lemmon and Huber, 2004) for the manipulations needed and the coefficients of eq. 9. Saturation conditions are identified using the Maxwell criterion, i.e. the pressure for which the Gibbs free energy of the liquid and vapour phases are equal. Upon identifying the saturation pressure as a function of temperature, the saturation dome may be identified; within the saturation dome fluid properties are determined using the mixture assumption based on the volume fraction *a*, i.e.:

$$\begin{aligned}\rho &= (1-a)\rho_{sat,L} + a\rho_{sat,V} \\ \rho e &= (1-a)e_{sat,L}\rho_{sat,L} + ae_{sat,V}\rho_{sat,V} \\ \rho h &= (1-a)h_{sat,L}\rho_{sat,L} + ah_{sat,V}\rho_{sat,V} \\ \rho s &= (1-a)s_{sat,L}\rho_{sat,L} + as_{sat,V}\rho_{sat,V}\end{aligned} \tag{10}$$

Mixture speed of sound is determined using the Wallis speed of sound formula (Brennen, 1995):

$$\frac{1}{\rho c^2} = \frac{1-a}{\rho_{sat,L}c_{sat,L}^{\ 2}} + \frac{a}{\rho_{sat,V}c_{sat,V}^{\ 2}} \tag{11}$$

In eq. 10 and 11, the *sat,L* index indicates the relevant property at saturation conditions for liquid and *sat,V* for vapour.

The aforementioned procedure can be performed on the fly, during code execution. However, in practice it requires root finding of non-linear equations, since the Helmholtz equation (and consequently all derived properties) is naturally expressed as a function of

density ρ and temperature T, whereas the flow solver calculates density ρ and internal energy e. In other words, at each time step the conservative variables $(\rho, \rho E)$ must be transformed to (ρ, T) and then used to derive pressure and speed of sound for the next calculation step. This can be done, using e.g. the Newton Raphson method, however it is very time consuming and inefficient.

Instead of solving the aforementioned EoS for each time step (using for example the Newton-Raphson method or similar), a similar technique as the one employed by Dumbser et al. (2013) has been used. In the present work, an unstructured thermodynamic table has been used (instead of the Cartesian used in Dumbser's work et al. (2013)), constructed prior to the simulations andcontaining the thermodynamic properties derived from the Helmholtz EoS. Static linked lists have been used in order to split the thermodynamic table into smaller groups of data and search only the group that has the desired values within its range. The resulting algorithm is much more efficient than the on-the-fly calculation of the Helmholtz EoS, by almost one order of magnitude of the computational time.

The unstructured thermodynamic table is built by selecting an appropriate range for the density and the internal energy: $\rho_{min} \le \rho \le \rho_{max}$ and $e_{min} \le e \le e_{max}$ that define a 2-D table $\Sigma = [\rho_{min}, \rho_{max}] \times [e_{min}, e_{max}]$, which should enclose the expected conditions of the simulation. Then this table Σ is discretized with quadrilateral elements. An unstructured grid of approximately 40,000 elements was created (Figure 1). The grid was refined around the saturation line in order to accurately capture the large variation of the thermodynamic properties in this area (e.g. for speed of sound or internal energy). Indicatively, the three dimensional phase diagram derived from the above Helmholtz energy EoS for the n-Dodecane, expressing pressure, internal energy and speed of sound as a function of density and temperature, is shown in Figure 2.

During the algorithm execution, after calculating the conservative vector in the time loop, and hence the density and the internal energy are known, the element of the thermodynamic table in which each cell of the computational domain belongs may be determined, using the linked list algorithm. Then using a Finite Element bilinear interpolation, any thermodynamic property φ in the space Σ can be calculated as:

$$\varphi(\rho, e) = \sum_{n}^{nodes} N_n(\rho, e) b_n \tag{12}$$

where φ can either be pressure, temperature or speed of sound, which are needed for the calculation of the fluxes (see section 2d) or post-processing results. The unknown coefficients of φ are notated by b and N is the shape function of node n:

$$N_n(\rho, e) = 1 + (e - e_n) + (\rho - \rho_n) + (e - e_n)(\rho - \rho_n) \tag{13}$$

The b coefficients of the property φ for each element are calculated by solving the following equation:

$$[\mathrm{N}]\mathbf{b} = \boldsymbol{\varphi} \rightarrow \begin{bmatrix} N_{11} & N_{12} & N_{13} & N_{14} \\ N_{21} & N_{22} & N_{23} & N_{24} \\ N_{31} & N_{32} & N_{33} & N_{34} \\ N_{41} & N_{42} & N_{43} & N_{44} \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} = \begin{bmatrix} \varphi_1 \\ \varphi_2 \\ \varphi_3 \\ \varphi_4 \end{bmatrix} \tag{14}$$

where φ are the values of the property at the nodes of the quadrilateral element and N_{mn} is:

$$N_{mn} = 1 + (e_m - e_n) + (\rho_m - \rho_n) + (e_m - e_n)(\rho_m - \rho_n) \quad (15)$$

The most efficient way to find the coefficients ***b***, is to calculate in advance and store the inverse of the mass matrix [N] for all elements before time advancement begins. That way, the coefficients ***b*** for each property φ can be found:

$$\mathbf{b} = [\mathrm{N}]^{-1} \boldsymbol{\varphi} \quad (16)$$

After finding the conservative vector in the time loop, each thermodynamic property φ can be approximated from equation (12).

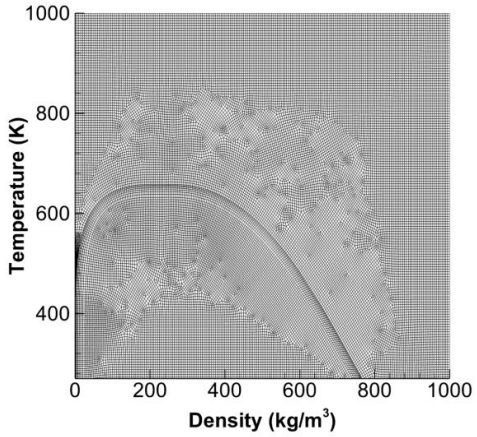


Figure 1: Unstructured thermodynamic grid of 40,000 finite elements, refined near the saturation line.

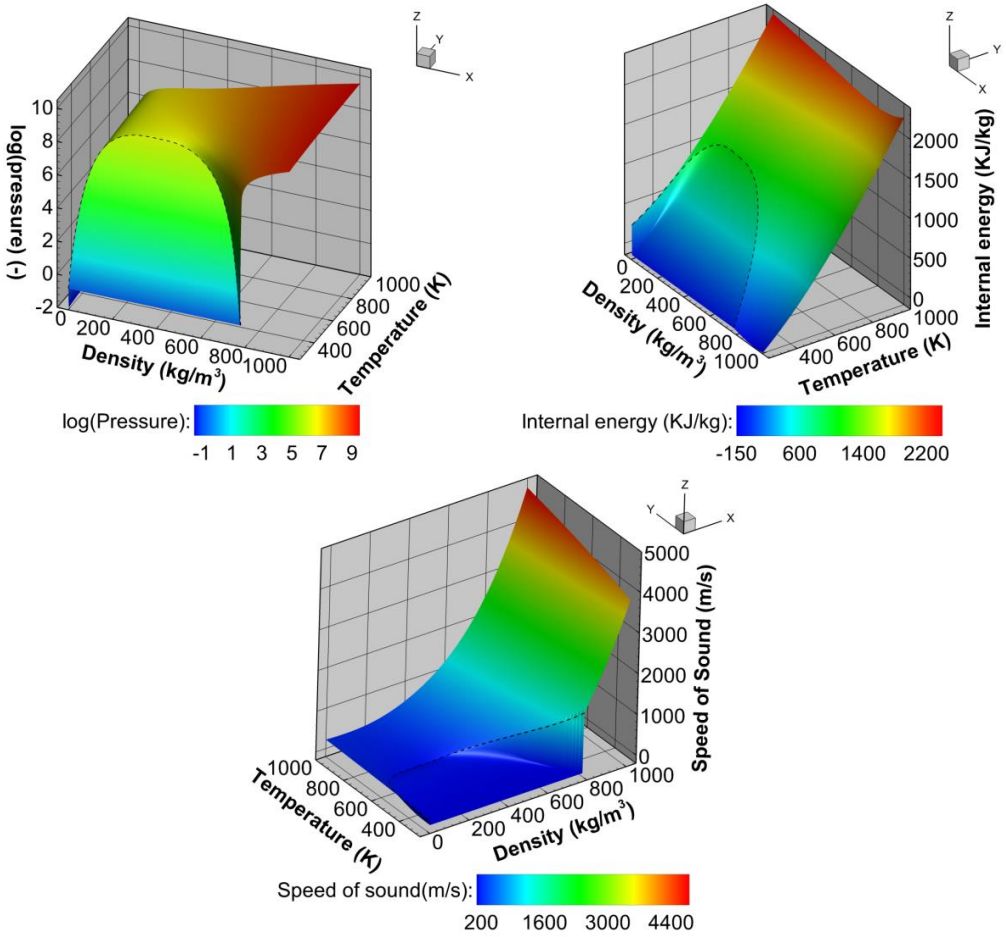


Figure 2: Three dimensional phase diagrams for the n-Dodecane, where the dashed line is the saturation line. The properties have been derived from the Helmholtz energy EoS.

2b. Barotropic approach

A two-step barotropic equation of state, which has been validated and used in previous studies (Koukouvinis et al., 2016a), has been used for comparison with the Helmholtz equation of state. In the former, the modified Tait equation of state for the liquid part and an isentropic-resembling relation (Egerer et al., 2014) for the mixture are given:

$$p(\rho)=\begin{cases} B\left[\left(\dfrac{\rho}{\rho_{sat,L}}\right)^{n}-1\right]+p_{sat}, & \rho \geq \rho_{sat,L} \\ p_{sat}+C\left(\dfrac{1}{\rho_{sat,L}}-\dfrac{1}{\rho}\right), & \rho < \rho_{sat,L} \end{cases} \tag{17}$$

In this approach, the saturation properties have been calculated assuming constant temperature at 300 K. The energy equation is not solved and thus, after solving the continuity and momentum equations, the above formula is used for calculating the pressure. This method is robust and efficient but it lacks in the prediction of the temperature field.

2c. Homogeneous equilibrium mixture with temperature effects

Finally, the third thermodynamic model which has been utilized, is a more sophisticated extension of the previous barotropic model, since the saturation properties depend on temperature (Koop, 2008; Schmidt et al., 2006). In this case, the modified Tait equation is used for the liquid, the ideal gas EoS for the vapour and the Wallis formula for the mixture. This model is based on the assumption that the latent heat is constant and it is calculated based on the initial temperature $T_0=300\ K$, which is valid only for a small variation of the temperature. Moreover, it cannot predict transcritical to supercritical transitions. The pressure is given by the following three-step equation as a function of density and temperature:

$$p(\rho,T)=\begin{cases} B\left[\left(\rho/\rho_{sat,L}(T)\right)^{n}-1\right]+p_{sat}(T), & \rho \geq \rho_{sat,L}(T) \\ p_{sat}(T), & \rho_{sat,V}(T) < \rho < \rho_{sat,L}(T) \\ \rho RT, & \rho < \rho_{sat,V}(T) \end{cases} \tag{18}$$

and the internal energy is given by the following equation:

$$e(T)=\begin{cases} C_{vl}(T-T_0)+e_{l0}, & \rho \geq \rho_{sat,L}(T) \\ \left(\alpha\rho_{sat,V}(T)e_{vap}(T)+(1-\alpha)\rho_{sat,L}(T)e_{liq}(T)\right)/\rho, & \rho_{sat,V}(T) < \rho < \rho_{sat,L}(T) \\ C_{vv}(T-T_0)+L_v(T_0)+e_{l0}, & \rho < \rho_{sat,V}(T) \end{cases} \tag{19}$$

where e_{vap} and e_{liq} stand for the internal energy of the vapour and liquid from the third or the first step of the equation respectively. After calculating the solution vector and thus the total energy is known, the Newton-Raphson method has been employed for the following function in order to calculate the temperature:

$$F(T)=e(T)-E(T)+\frac{1}{2}\left(u^2+v^2\right)=0 \tag{20}$$

Once the Newton-Raphson algorithm has converged, the pressure and the volume fraction are calculated and then the algorithm advances to the next time step.

For each Newton-Raphson iteration, the saturation properties are calculated since they depend on the temperature and they are given by the following formulas:

$$ln\left(\frac{p_{sat}(T)}{p_c}\right)=\frac{T_c}{T}\sum_{i=1}^{7}a_i\theta^{\hat{a}_i} \quad (21)$$

$$\frac{\rho_{sat,L}(T)}{\rho_c}=\sum_{i=1}^{7}b_i\theta^{\hat{b}_i} \quad (22)$$

$$ln\left(\frac{\rho_{sat,V}(T)}{\rho_c}\right)=\sum_{i=1}^{7}c_i\theta^{\hat{c}_i} \quad (23)$$

where $\theta = T / T_c$ and the coefficients are given in Table 1 and ρ_c=*226.55 kg/m*^{3}, p_c=*1817000 Pa*, γ=*1.03*. It must be mentioned here that the previous equations are valid as long as the temperature is within the range: $T \in [T_r = 273.15, T_c = 658.1]$. The coefficients in equations 21-23 have been calculated in order to give the same saturation conditions as the Helmholtz energy EoS.

Table 1: Parameters needed in Equations 19, 20 and 21 for the n-Dodecane.

Index	a_i	$\hat{a}_i$	b_i	$\hat{b}_i$	c_i	$\hat{c}_i$
1	-0.03359	0	1.37610	0	-0.39275	0
2	-8.54218	1	11.88513	1	-19.73929	1
3	3.20579	3	-69.63935	2	78.72869	2
4	11.27780	4	297.58733	3	-361.4296	3
5	7.66350	5	-717.4947	4	779.84876	4
6	-7.09773	6	888.91121	5	-899.4366	5
7	0	0	-438.5464	6	331.66738	6

This method is efficient but not so robust as the barotropic model and it suffers from limitations in the temperature range relative to the Helmholtz EoS.

2d. Space and time discretization

In cavitation phenomena there is large variation in the speed of sound and thus in the Mach number, making it difficult to apply a unified discretization method. The flow can be considered incompressible in the liquid regime and the Mach number can even be of the order of 10^{-2}. On the other hand, in the vapour regime and during the collapse of the cavity structures where shock waves are created, the flow is highly compressible and Mach number can be of the order of 10^2 or even higher, due to the small speed of sound of the two-phase mixture (Van der Heul et al., 2000). When using density-based solvers for low Mach number flows, slow convergence and incorrect solutions have been noticed (Guillard and Viozat, 1999; Meister, 1999; Munz et al., 2003). To overcome this, the Mach consistent numerical flux of Schmidt et al. (2008) has been implemented, which is based on the HLLC flux and the AUSM flux (Meng-Sing, 2006). The numerical flux in the x direction at the i+1/2 interface takes the following form:

$$\mathbf{F}_{i+1/2}^{\text{hybrid}}=\rho_{L/R}u_{face}\begin{pmatrix}1\\u_{L/R}\\v_{L/R}\\E_{L/R}\end{pmatrix}+\mathrm{p}_{\text{face}}\begin{pmatrix}0\\1\\0\\u_{face}\end{pmatrix} \quad (24)$$

where

$$u_{face} = \frac{1}{\rho_L + \rho_R}\left(\rho_L u_L + \rho_R u_R + \frac{p_L - p_R}{c_{face}} \right),\ p_{face} = \frac{p_L + p_R}{2},\ c_{face} = max(c_L, c_R) \quad (25)$$

and $\rho_{L/R}$, $u_{L/R}$, $v_{L/R}$ and $E_{L/R}$ depend on the sign of u_{face}, the value of the left cell is taken when the sign of u_{face} is positive and vice versa. In order to achieve 2nd order of accuracy in space, the MUSCL-Hancock (Toro, 2009) reconstruction is employed to determine conservative variables at cell interfaces, which in turn are used for the flux estimation (eq. 24).

Since the cavitation phenomena which are simulated are unsteady, a four stage Runge-Kutta (RK) method, 2nd order in time has been implemented. Let an initial value problem be defined by the following differential equation and its initial condition:

$$\frac{\partial \mathbf{U}}{\partial t} = \mathbf{R}(t, \mathbf{U}),\ \mathbf{U}(t_0) = \mathbf{U}_0 \quad (26)$$

The numerical solution of this differential equation is given by the following steps, where the coefficients were chosen in order to improve stability (Schmidt, 2005):

$$\mathbf{U}^1 = \mathbf{U}^n + 0.11\mathbf{R}(\mathbf{U}^n) \quad (27)$$

$$\mathbf{U}^2 = \mathbf{U}^n + 0.2766\mathbf{R}(\mathbf{U}^1) \quad (28)$$

$$\mathbf{U}^3 = \mathbf{U}^n + 0.5\mathbf{R}(\mathbf{U}^2) \quad (29)$$

$$\mathbf{U}^{n+1} = \mathbf{U}^n + \mathbf{R}(\mathbf{U}^3) \quad (30)$$

This specific RK method was selected since it has low storage requirements and only the solution vectors from time n and n+1 need to be stored, which is important for large scale simulations.

3. Results

In this section, the numerical model is firstly validated against the exact solution of the Riemann problem and the Rayleigh collapse test case and then a numerical experiment of bubble collapse is performed. The Riemann problem was chosen in order to validate the spatial accuracy of the algorithm and to examine if it is feasible to capture the correct wave pattern. On the other hand, the Rayleigh collapse test case was chosen to investigate the time advancement of the Runge-Kutta implementation, as well as the source terms. Once the algorithm is validated with these cases that exact or semi-analytical solutions exist, bubble collapse simulations in the vicinity of a wall have been performed for various configurations. It has to be mentioned here that although in the literature many bubble collapse simulations have been made, there has not been an investigation on the effect of accurate thermodynamics of the fluid involved. Therefore, the present model is accessed against the barotropic model and the HEM with temperature effects.

3a. Riemann problem

The first benchmark case is the Riemann problem in the computational domain $x \in [-2,2]$ with initial conditions for the left state: $\rho_L = 752.5\ kg/m^3$, $T_L = 289\ K$ and for the right state: $\rho_R = 717.5\ kg/m^3$, $T_R = 350\ K$. Comparison between the exact and the numerical solution is shown in Figure 3 at time $t = 0.5\ \mu s$. First order of spatial accuracy with 800 equally spaced cells in the x direction was used. Wave transmissive boundary conditions have been used for the left and the right side of the shock tube, that is $\mathbf{U}^{n+1}(x=L) = \mathbf{U}^n(x=L)$ and $\mathbf{U}^{n+1}(x=0) = \mathbf{U}^n(x=0)$. As it can be seen in Figure 3, the exact solution of the Riemann problem

and the computed one are in satisfactory agreement and the wave pattern has been correctly captured. The exact solution of the Riemann problem is not trivial for an arbitrary EoS and it has been derived following the Appendix section of the present paper.

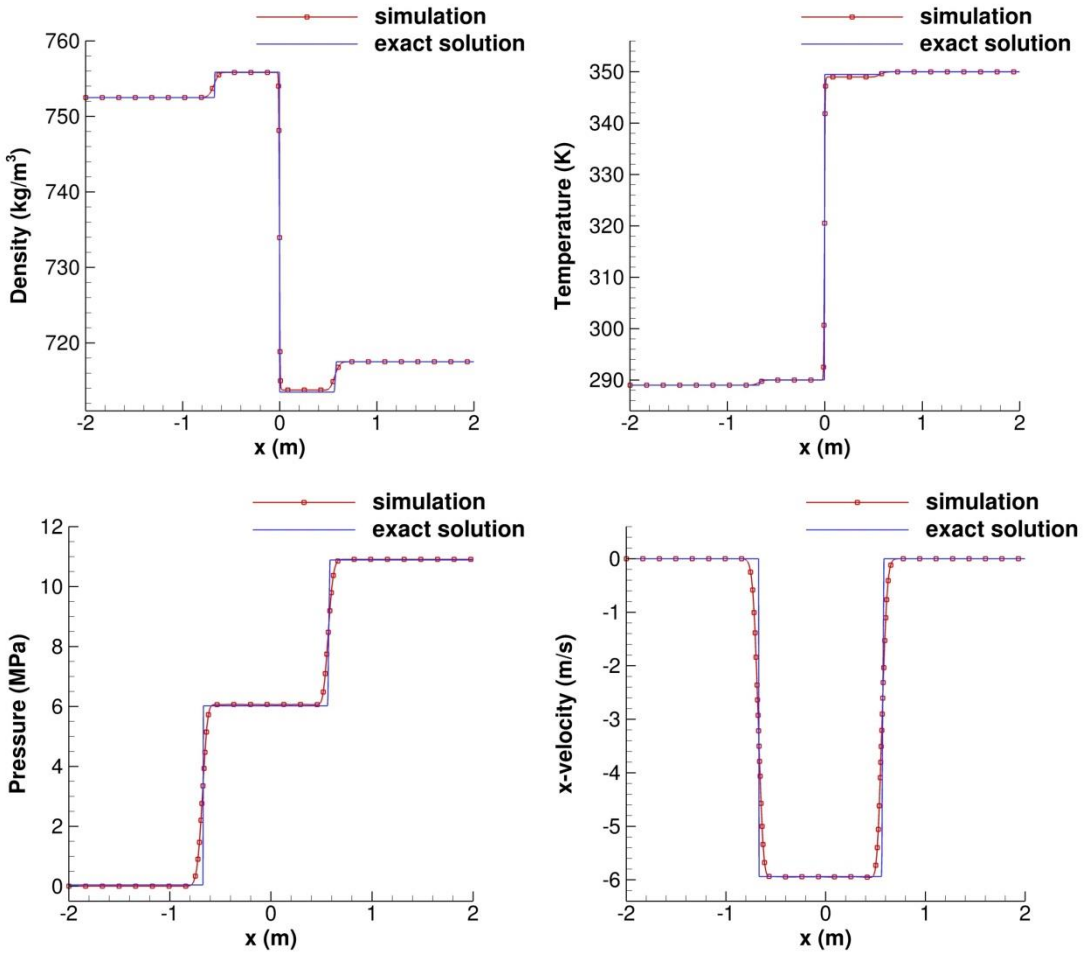


Figure 3: Validation of the solver in the Riemann problem. Comparison of the density (upper left), temperature (upper right), pressure (lower left) and x-velocity (lower right) between the exact and the numerical solution.

3b. Rayleigh bubble collapse

The second test case examined is the Rayleigh bubble collapse, where a vapour sphere of radius $R = 400\,\mu$m is under compression owing to the higher pressure of the surrounding liquid. The bubble collapse velocity is given by Franc and Michel (2005):

$$\frac{dR}{dt} = -\sqrt{\frac{2}{3}\frac{p_\infty - p_{vap}}{\rho_{liq}}\left[\left(\frac{R_0}{R}\right)^3 - 1\right]} \tag{31}$$

and the characteristic Rayleigh time τ of the bubble is:

$$\tau = 0.915 R_0 \sqrt{\frac{\rho_{\mathrm{liq}}}{p_\infty - p_{vap}}} \tag{32}$$

Here, the vapour pressure is $p_{vap} = 19.64\,Pa$, the liquid density is $\rho_{liq} = 744.36\,kg/m^3$ and the far-field pressure is $p_\infty = 0.1\,MPa$.

An one-dimensional solver was employed for this simulation, taking advantage of the spherical symmetry. The total computational domain is 20 times the size of the initial vapour radius in order to minimize the interference of the boundaries. The mesh is refined in the bubble region, where 1000 equally spaced cells have been used and a stretching ratio of 1.05 with 150 cells has been used outside the bubble. Wave transmissive boundary condition has been used on the far-field right side and symmetry condition was selected for the left side. Comparison with the semi-analytical solution gives satisfactory results (Figure 4), since the current methodology is able to predict the correct curve of the bubble radius with respect to time. In Figure 4, the radius has been divided by the initial radius R_0 and the time has been non-dimensionalized by the Rayleigh time which is $\tau=31.5\ \mu s$ for the current configuration.

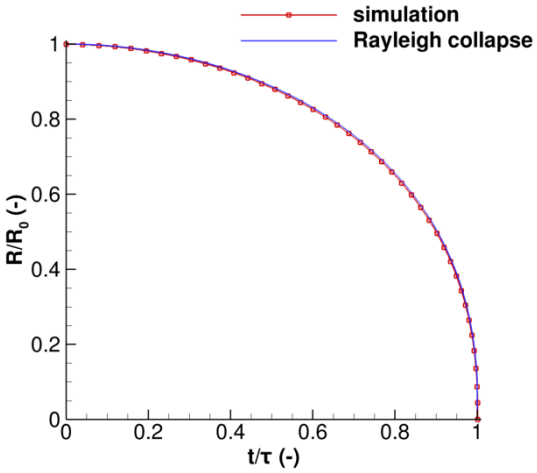


Figure 4: Comparison between the Rayleigh collapse solution and the numerical one. The bubble radius and the time are expressed in non-dimensional form, in reference to the initial radius R_0 and Rayleigh collapse time τ respectively.

3c.n-Dodecane bubble collapse

The collapse of a n-Dodecane vapour bubble in the vicinity of a wall has been investigated next. Following Lauer et al. (2012) and Koukouvinis et al. (2016a), the same configuration is tested for the numerical scheme presented in section 2, which takes into account temperature effects. The radius of the bubble is $R=400\ \mu m$ and its centre has been placed at distance $d=416,\ 140$ and $-140\ \mu m$ from the horizontal wall (x-axis) and on the axis of symmetry (y-axis), as it can be seen in Figure 5. The properties of the n-Dodecane in liquid form which is surrounding the bubble are $p_l=12.144\ MPa$, $T_l\approx300\ K$ and the vapour bubble properties are $p_v=19.64\ Pa$, $T_v\approx300\ K$. The computational domain is 20 times the bubble radius; 200 equally spaced cells were used for describing the initial radius of the bubble. After distance 2.5R from the origin, the mesh is coarsened with ratio 1.05 in both directions. Zero gradient boundary condition has been used for the right and the upper side, slip wall for the lower side, whereas for the y-axis of symmetry, the normal velocity component is zero.

In Figures 6, 7 and 8 there are two columns of images. In the first column the pressure field is shown on the left and the velocity field on the right. Similarly, in the second column the temperature field is shown on the left and Schlieren is depicted on the right. In all images, iso-lines of density 380 kg/m^3 are shown as well. In Figures 9, 10 and 11 wall pressure (left) and wall temperature (right) combined with the density iso-surface of 380 kg/m^3 are shown. The units are in SI or their submultiples and multiples of the SI units. The simulation time

indicated in the next Figures is non-dimensional and it is divided by the Rayleigh collapse time $\tau=2.88\ \mu s$.

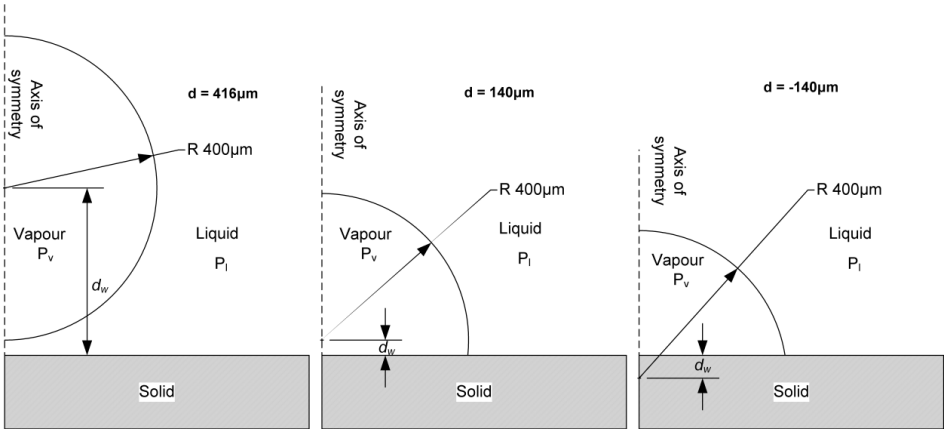


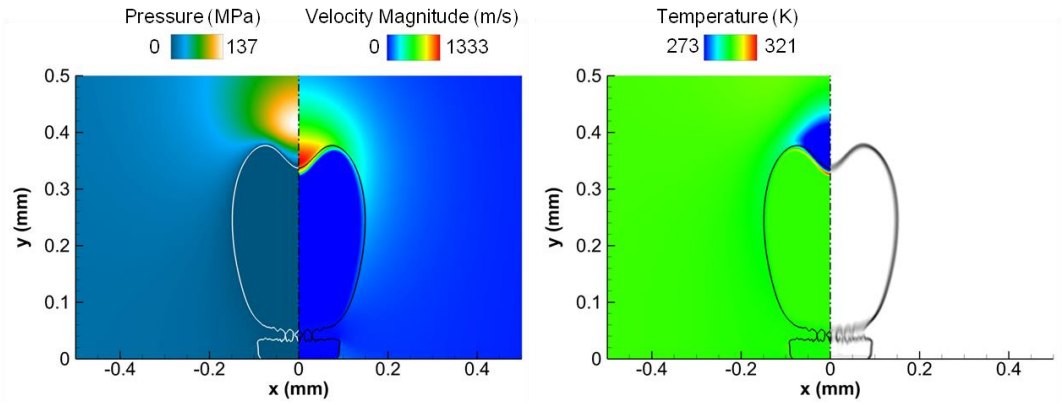
Figure 5: Bubble configurations for the three different positions.

In all three configurations, there is slow shrinking of the bubble initially, until the jet is formed and after that the bubble is collapsing rapidly. Of course, the direction of the jet depends on the configuration, as it will be explained below.

In Figure 6 the evolution of the bubble collapse is shown for the configuration where its initial centre is placed at $d=416\ \mu m$ from the x-axis. At the beginning of the collapse, a rarefaction wave expands from the bubble. The interaction of the rarefaction wave with the wall causes local depressurisation and vaporisation in the vicinity of the wall (Koukouvinis et al., 2016a). As the collapse proceeds, the bubble shape departs from spherical, due to the interaction with the wall boundary (x-axis). A micro-jet is formed on the top of the bubble and the heart-like-shape is noticed, which is in accordance with previous results reported (Koukouvinis et al., 2016a; Lauer et al., 2012). In addition, the propagating pressure wave after collapse is shown at time 1.18 in Figure 6. There is a significant rise in the temperature of the liquid, up to 1000 K, after the collapse of the bubble, due to vapor condensation and liquid compression, while there is a significant drop in the temperature above the bubble, to 273 K, due to the large acceleration of the flow which causes a reduction in the internal energy. We highlight here, that the critical point for n-dodecane is T_c~$658K$ and p_c~$18bar$; this implies that in areas of collapse the fluid may transition to supercritical state.

In Figure 7 instances of the bubble having initially its centre at $d=140\ \mu m$ from the x-axis are shown. Again, a non-symmetric shape for the bubble and a micro-jet are created. A torus which is attached to the wall is formed and it collapses creating a pressure wave. In both cases, that is for $d=416\ \mu m$ and $d=140\ \mu m$, the jet's and the bubble collapse direction are towards the wall. In this specific case, a secondary jet is created when the primary jet, which is normal to the wall, is deflected at the wall and interacts with the remaining ring (time=1.09 in Figure 7).

In Figure 8 snapshots of the bubble having its centre in the lowest position ($d=-140\ \mu m$) are demonstrated. In comparison with the two previous positions, the shape of the bubble looks like a pin and the collapse direction is tangential to the wall. The jet which is formed is towards to the axis of symmetry, which was not the case in the previous positions. A propagating pressure wave at time 0.77 is shown in Figure 8.



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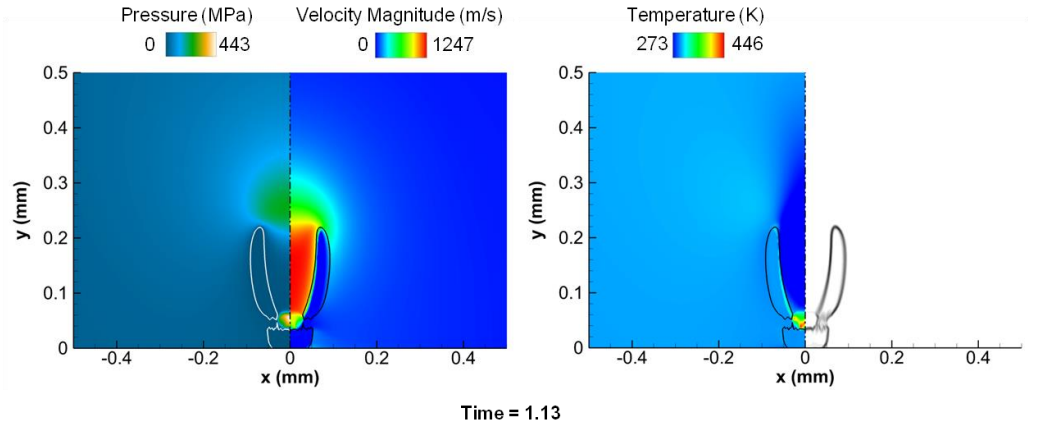

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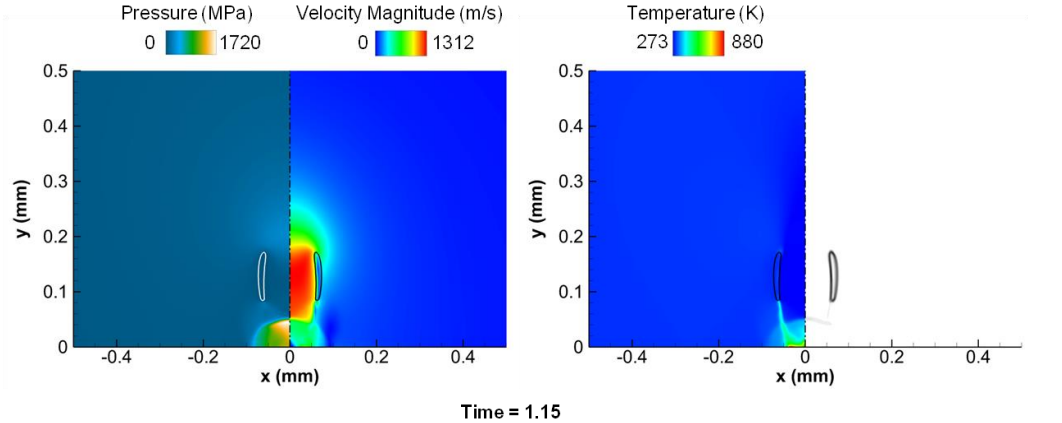

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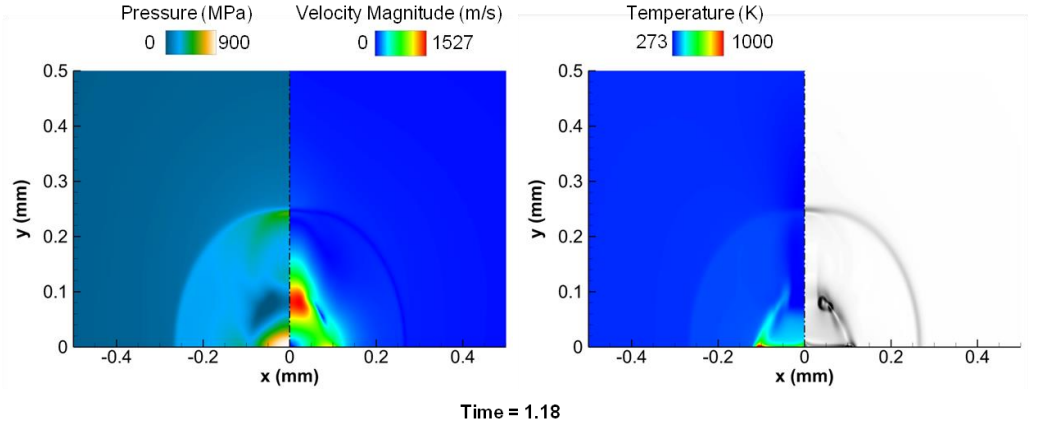

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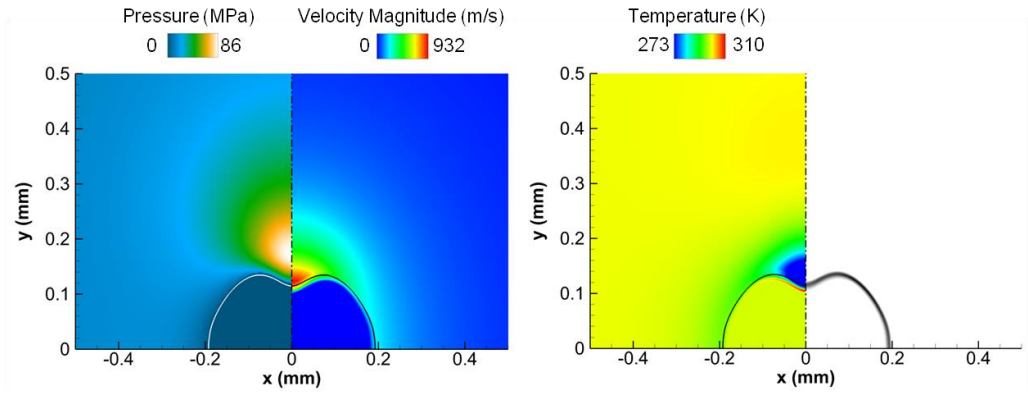
520 **Figure 6:** Instances during the vapour bubble collapse for d=416 μm. Time has been non-
521 dimensionalized with Rayleigh collapse time τ=2.88 μs.



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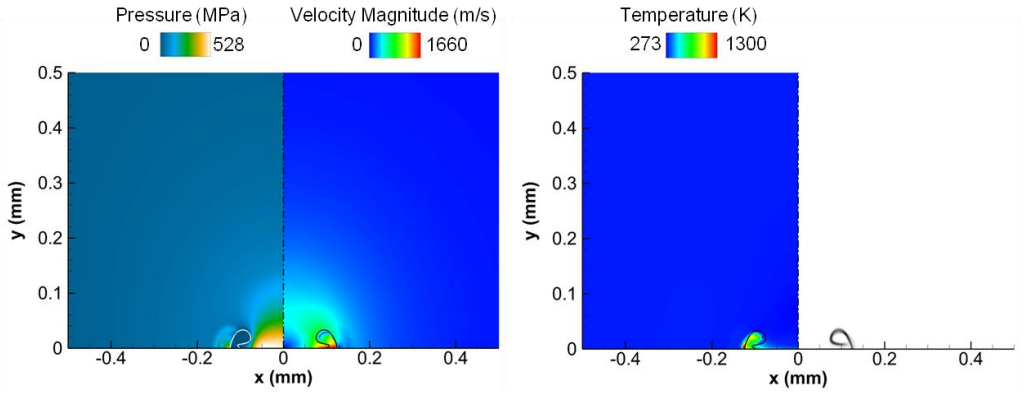

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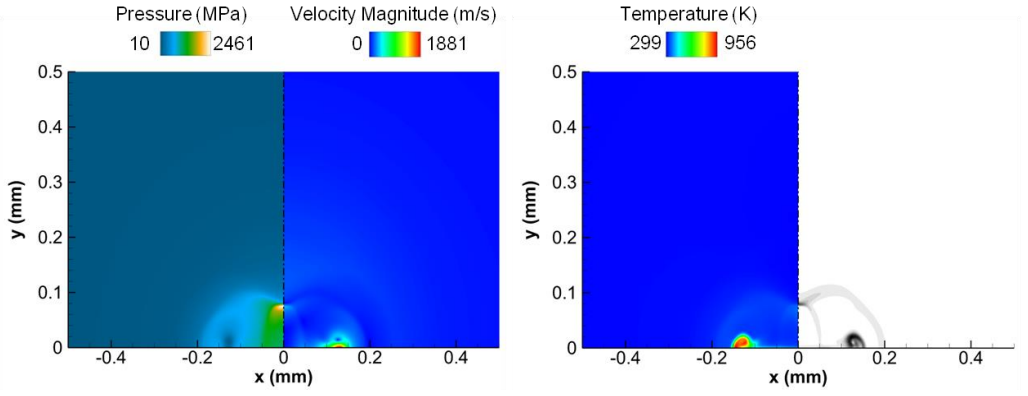

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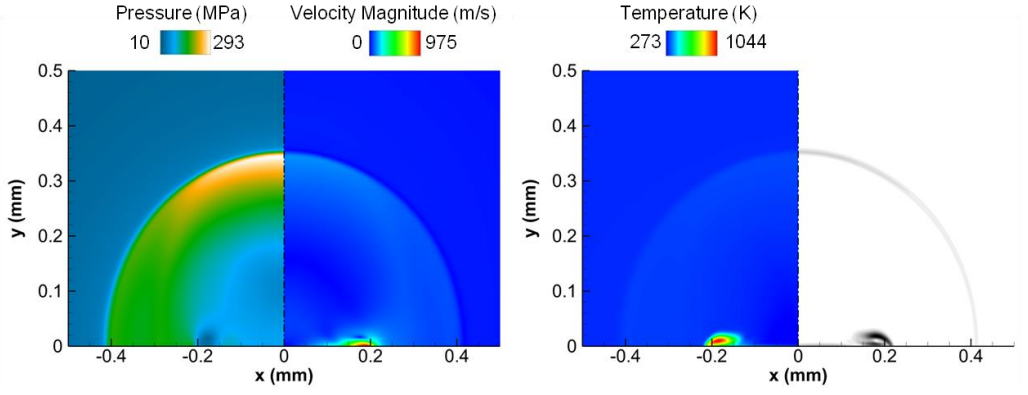

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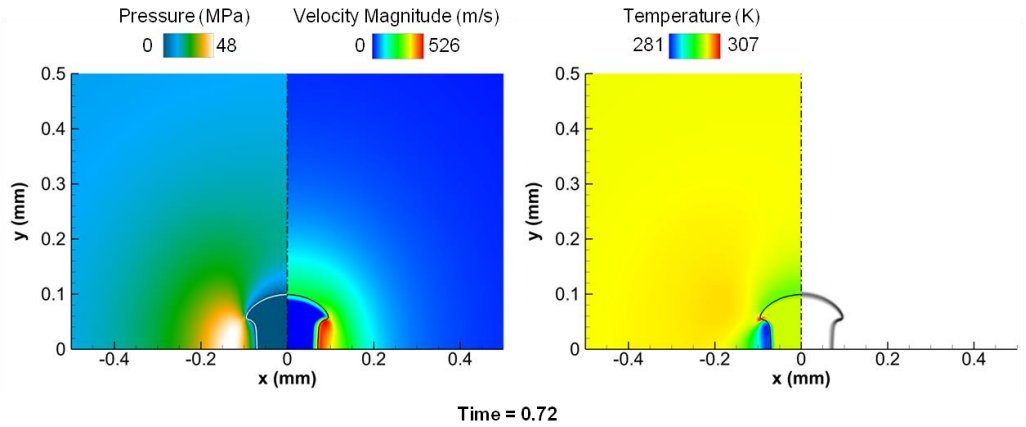
526 **Figure 7:** Instances during the vapour bubble collapse for d=140 μm. Time has been non-
527 dimensionalized with Rayleigh collapse time τ=2.88 μs.



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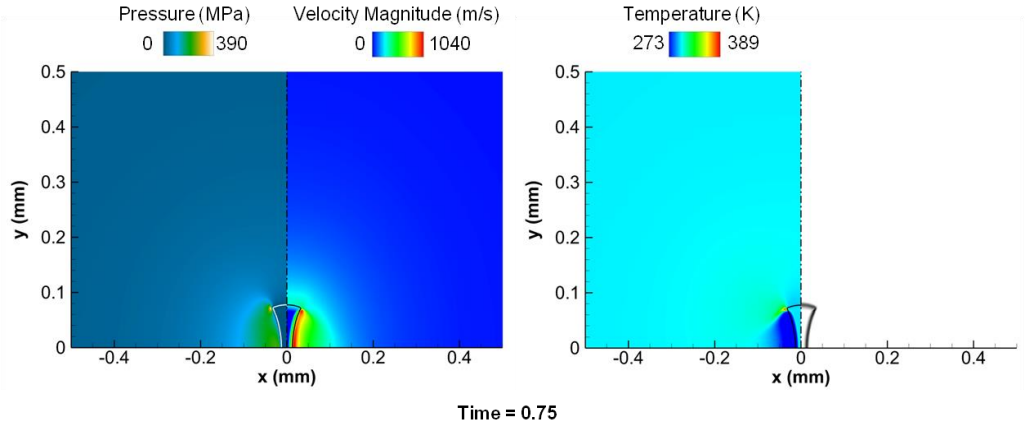

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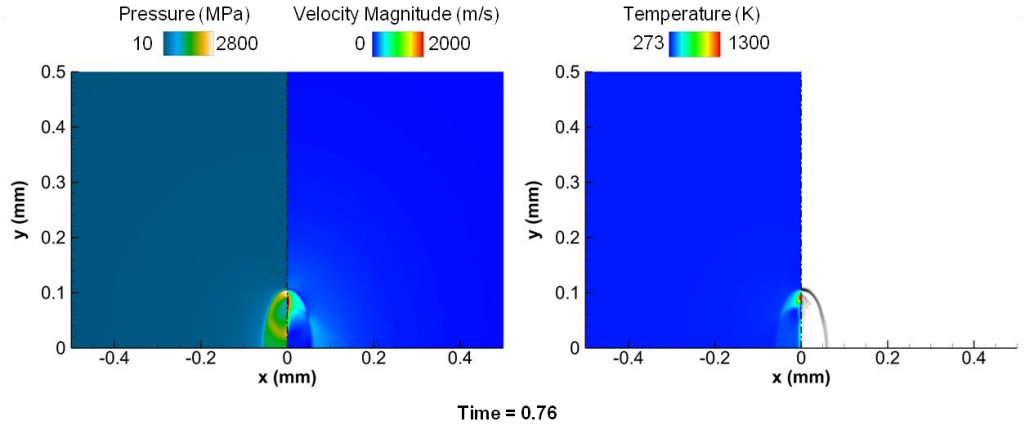

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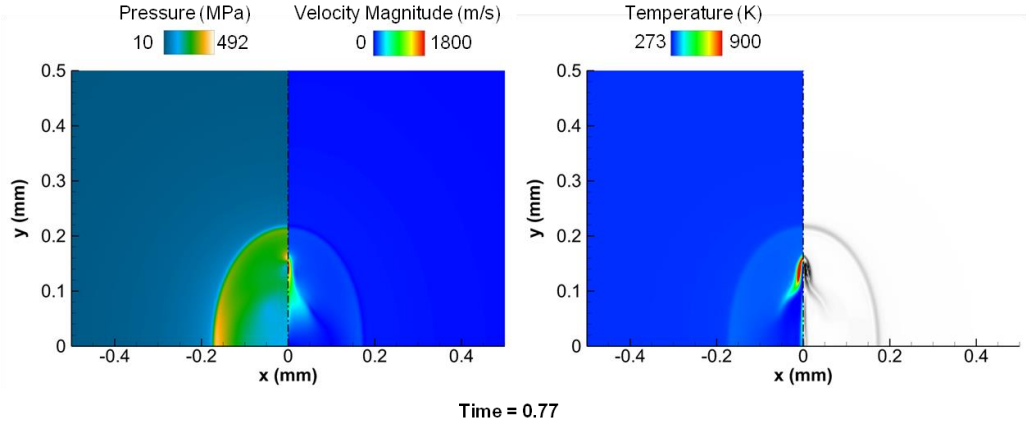

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532 **Figure 8:** Instances during the vapour bubble collapse for d=-140 μm. Time has been non-
533 dimensionalized with Rayleigh collapse time τ=2.88 μs.

Focusing on the iso-surfaces of Figures 9, 10 and 11, the different collapse pattern is clearly visible. The justification for the collapse shape is related to the local angle between the liquid/vapour interface and wall, at the closest point or point of contact to the wall; this has been discussed in more detail in (Koukouvinis et al., 2016a), but the main mechanism will be briefly discussed here as well. When the local angle is below 90^o, flow in the vicinity of the wall tends to detach, reducing the pressure and preventing further acceleration of the collapse, thus near wall velocities are small and the collapse is mainly directed in the form of a micro-jet towards the wall on the axis-of-symmetry. On the other hand, when the local angle is higher than 90^o the flow tends to move towards the wall, leading to pressurization and further acceleration of the collapse. These effects underline the influence of boundary presence and pressure gradients to the bubble collapse, as demonstrated also in experimental (Obreschkow et al., 2006; Obreschkow et al., 2013) and numerical work (Hawker and Ventikos, 2009; Lauer et al., 2012; Plesset and Chapman, 1971).

The collapse time of the bubbles is reasonable and comparable to the Rayleigh collapse time. In the previous configurations the collapse time is also proportional to the initial volume of the vapour which exists in the bubble. A more thorough study of the collapse times for the previous configurations and other thermodynamic models is shown next, where two different homogeneous equilibrium methods are implemented and compared to the above technique. The model parameters and the initial conditions have been chosen accordingly to match the conditions of the Helmholtz EoS bubble collapse, for consistency reasons.

The configuration of the barotropic model was made using the following values: $B=125.956\ MPa$, $p_{sat}=40\ Pa$, $\rho_{sat}=744.29\ kg/m^3$, $C=1100\ Pa\ kg/\ m^3$ and $n=7.15$. The initial density of the liquid was set to $\rho_{liq}=753.91\ kg/m^3$ and the density in the bubble was set to $\rho_{liq}=74.0\ kg/m^3$.

For the HEM model with temperature effects, the initial density of the liquid was set to $\rho_{liq}=752.3\ kg/m^3$, the density in the bubble was $\rho_{liq}=3.95\ kg/m^3$ and the initial temperature was $T_0=300\ K$. In addition, $B=168.638\ MPa$, $n=7.15$, $R=48.9\ J/(kg\ K)$, $C_{vl}=1823\ J/(kg\ K)$, $C_{vv}=1593.3\ J/(kg\ K)$, $L_v=345739.0\ J/(kg\ K)$ and $e_{l0}=9450\ J/kg$ have been set.

In Figure 12 (left), vapour volume fraction with respect to time is shown for the three different thermodynamic models. It is obvious that the barotropic model predicts slightly earlier collapse time for all three positions of the bubble, because the pressure is expressed only as a function of the density, and the temperature effect is not taken into account. The other two models considering the temperature effects, predict the same collapse time and their curves coincide for all three positions of the bubble. However, for the highest position after the collapse, rebound is noticed for all three models but for the Helmholtz EoS this is more dominant. This rebound is caused due to the conservation of angular momentum; even if the solver employed is based on the Euler equations, the asymmetric near wall bubble collapse induces vorticity. This vorticity causes centrifugal force, which prevents the total collapse and disappearance of the bubble, at least until vorticity is dissipated by numerical diffusion. For more information on the rebound of cavitating vortices the interested reader is addressed to (Franc and Michel, 2005). In addition, if the EoS is expressed as a function of density and internal energy, baroclinic torque is predicted, due to the misalignment of pressure and density gradient vectors and as a result, more vorticity is generated (Pozrikidis, 2009). This is the case for the Helmholtz EoS, where the rebound is more dominant than the barotropic model. The HEM with temperature effects is weakly dependent on the temperature and thus, the rebound is the same as the barotropic model.

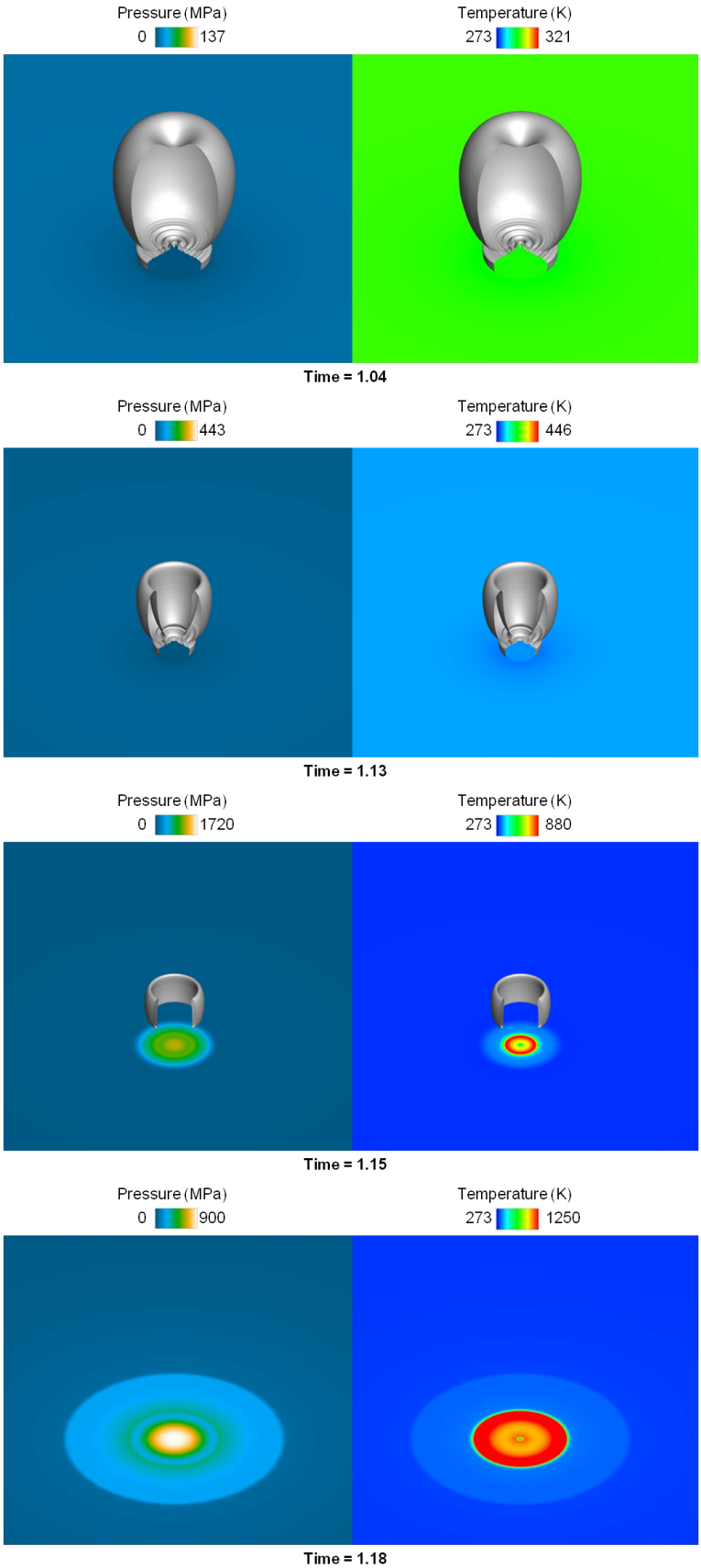
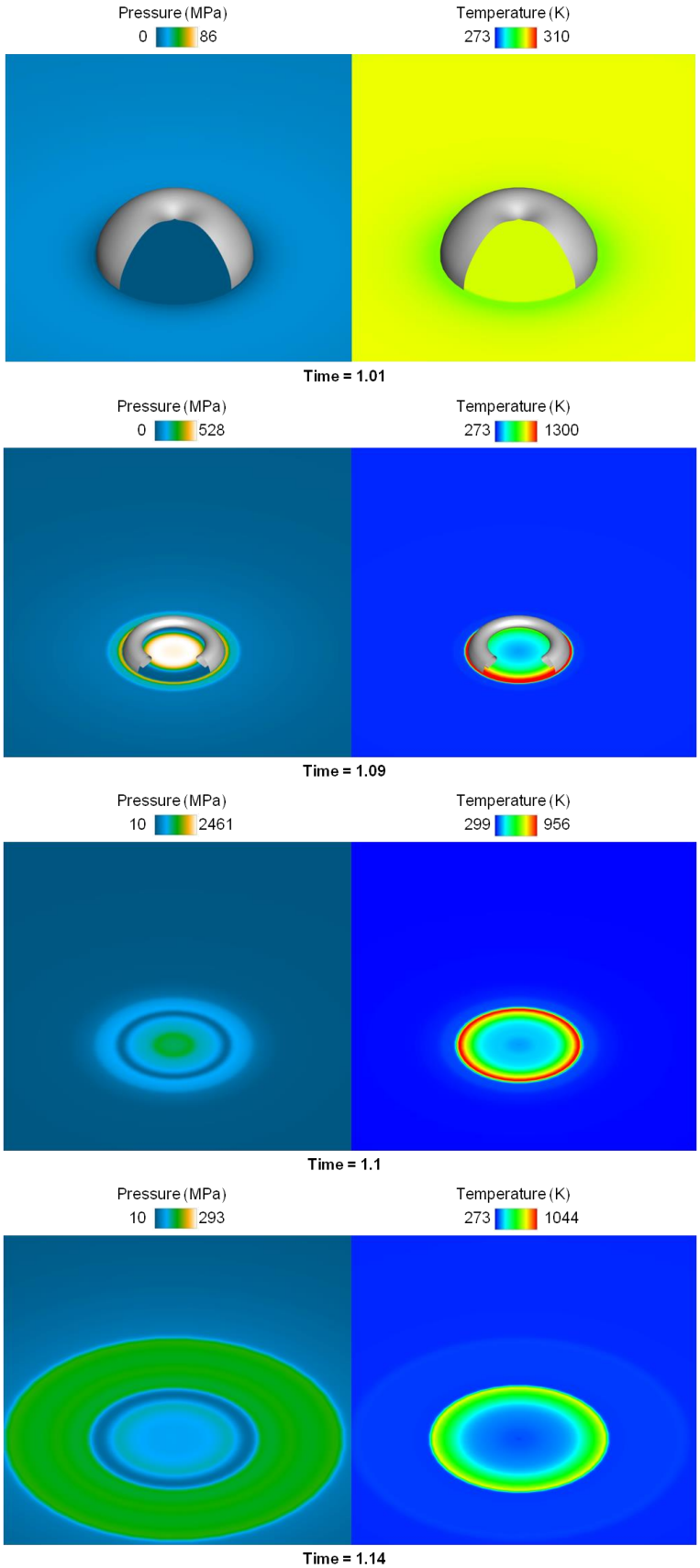


Figure 9: Wall pressure (left) and temperature (right) combined with density iso-surfaces of 380 kg/m^3 during the vapour bubble collapse for d=416 μm. Time has been non-dimensionalized with Rayleigh collapse time τ=2.88 μs.



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592 **Figure 10:** Wall pressure (left) and temperature (right) combined with density iso-surfaces of 380
593 kg/m^3 during the vapour bubble collapse for d=140 μm. Time has been non-dimensionalized with
594 Rayleigh collapse time τ=2.88 μs.

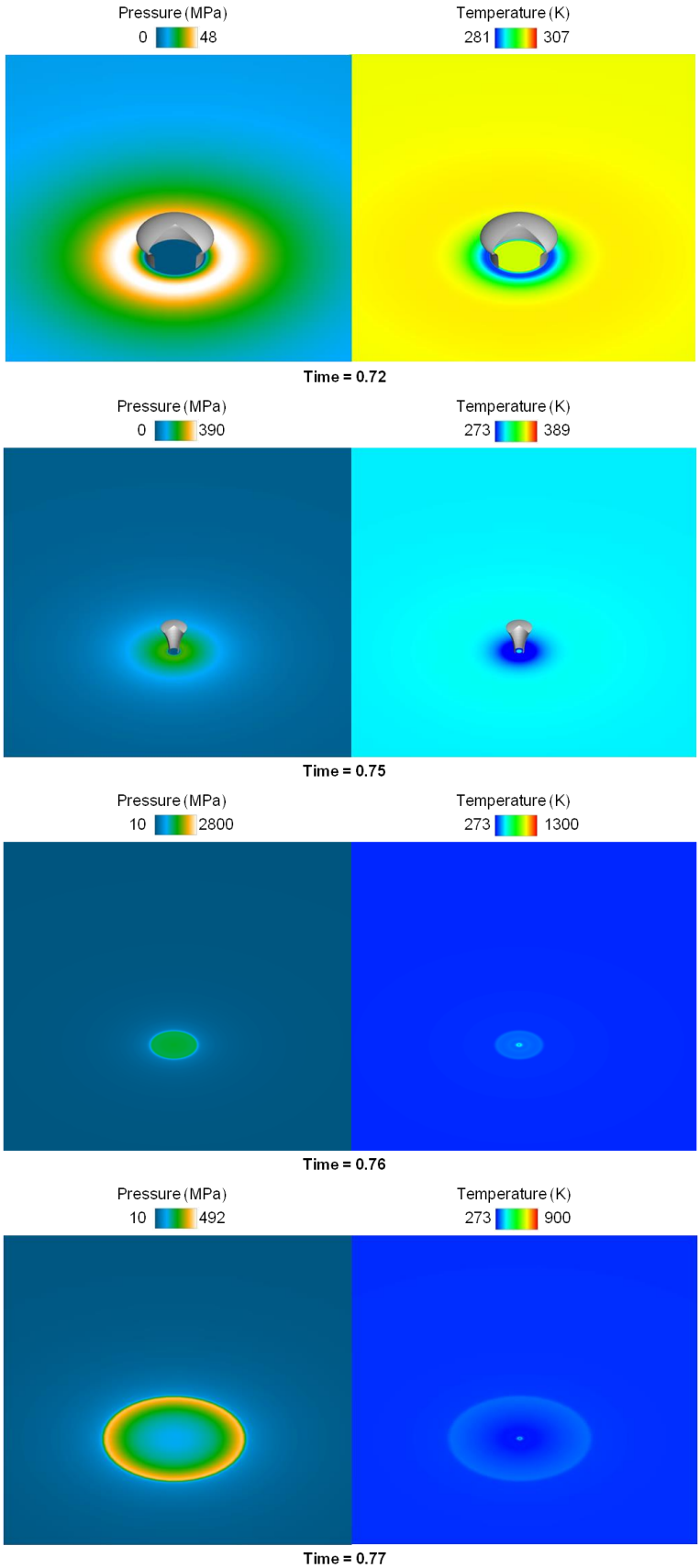

Figure 11: Wall pressure (left) and temperature (right) combined with density iso-surfaces of 380 kg/m^3 during the vapour bubble collapse for d=-140 μm. Time has been non-dimensionalized with Rayleigh collapse time τ=2.88 μs.

During the grid independence study, higher maximum pressure and temperature for the finer mesh have been noticed. This is reasonable in a way that more scales can be captured with the finer mesh. For example, if the vapour bubble size is smaller than the cell size, then it cannot be captured with the coarse mesh and neither can the collapse. Similar observations have been reached by Adams and Schmidt (2013). Furthermore, the collapse time was the same, regardless the resolution of the mesh that has been used.

In Figure 12 (right) the maximum wall pressure is shown with respect to time, which is due to the impact of the jet to the wall. It can be noticed that all the models predict similar patterns for each position of the bubble and the wall pressure can even be of the order of 10^{10} for the lowest position of the bubble, as it has also been shown by Koukouvinis et al. (2016a). The maximum wall pressure is predicted slightly earlier in the barotropic model, as a result of the earlier collapse time which was also noticed in this model. This pressure increase which is due to the re-entrant jet and the shock wave after the collapse of the bubble, can lead to erosion damage of materials.

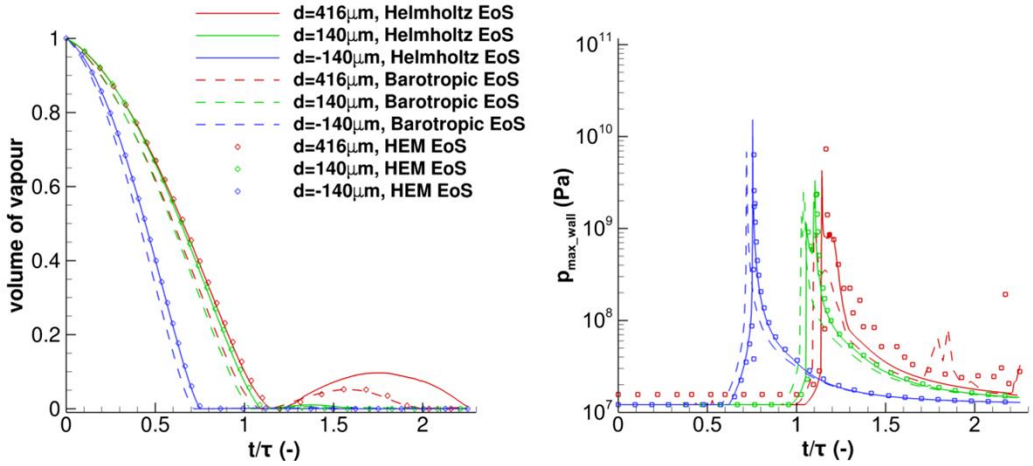

Figure 12: Volume of vapour decrease with respect to time (left) and maximum pressure on the wall (right) for the three different thermodynamic models.

In Table 2, the number of the cells where extrapolation was used beyond the applicability range of the Helmholtz EoS is shown, as a percentage of the grid size. In addition, the minimum and maximum values of density are also shown in order to get an estimation of how extrapolation affects its value. As it can be seen, a small percentage of the total cells has been calculated beyond the calibration range of the Helmholtz EoS. In Figures 13-15 the velocity vectors are shown and the supercritical cells (T_c=658.1 K, p_c=1.817 MPa) are coloured in black, whereas the vapour (white) and liquid (grey) regions are distinguished by a red iso-line of density 380 kg/m^3.

Table 2: Percentage of the cells where the thermodynamic properties have been calculated using the Helmholtz EoS beyond its calibration limit for indicative time instances.

d=416 μm			d=140 μm			d= -140 μm		
t/τ	Cells beyond calibration	min-max ρ (kg/m^3)	t/τ	Cells beyond calibration	min-max ρ (kg/m^3)	t/τ	Cells beyond calibration	min-max ρ (kg/m^3)
1.04	1.8 %	4-826	1.01	0.5 %	4-807	0.72	0	4-777
1.13	4.2 %	3-864	1.09	0.1 %	2-890	0.75	1.2 %	4-852
1.15	3.3 %	5-994	1.10	0.1 %	553-1014	0.76	0.7 %	751-1011
1.18	1.9 %	550-916	1.14	0.9 %	388-843	0.77	0.5 %	554-868

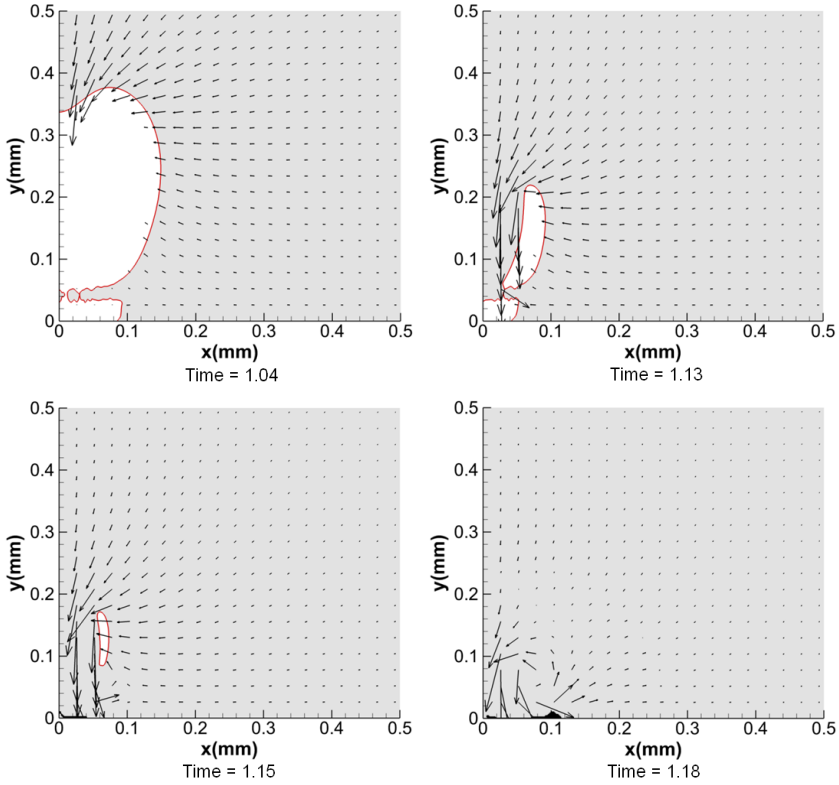

Figure 13: Depiction of the supercritical (black), vapour (white) and liquid (grey) regions, combined with velocity vectors for d=416 μm. Time has been non-dimensionalized with Rayleigh collapse time τ=2.88 μs.

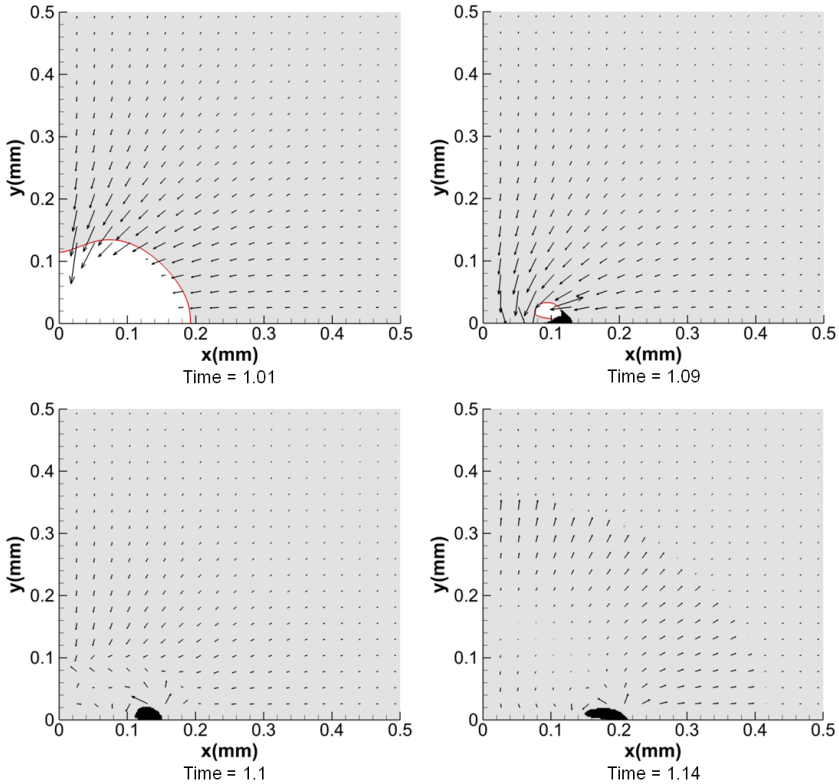

Figure 14: Depiction of the supercritical (black), vapour (white) and liquid (grey) regions, combined with velocity vectors for d=140 μm. Time has been non-dimensionalized with Rayleigh collapse time τ=2.88 μs.

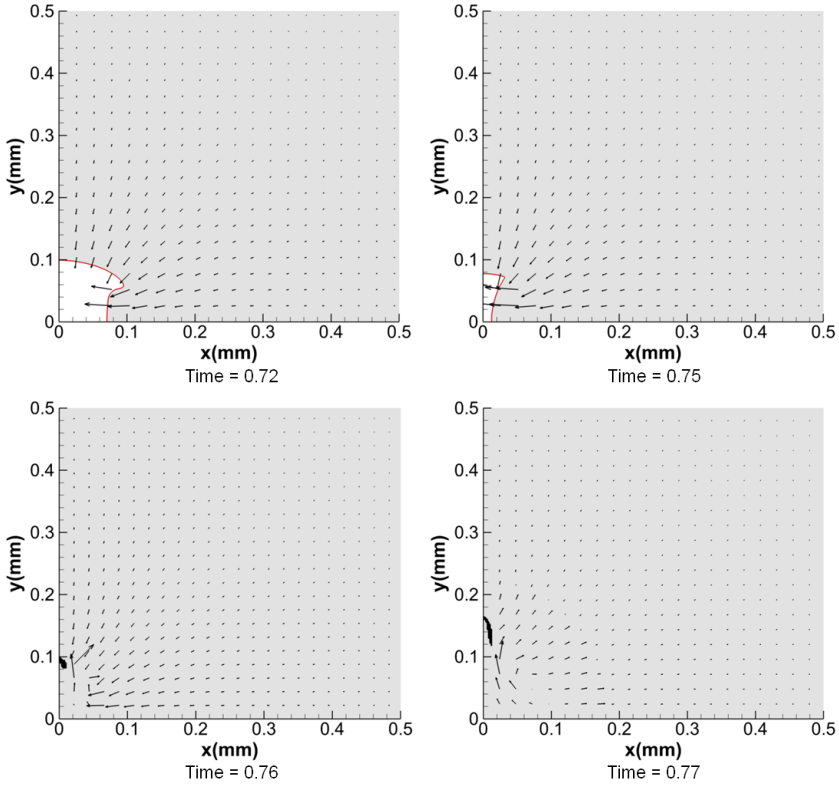

Figure 15: Depiction of the supercritical (black), vapour (white) and liquid (grey) regions, combined with velocity vectors for d=-140 μm. Time has been non-dimensionalized with Rayleigh collapse time τ=2.88 μs.

The system-cpu time required for each thermodynamic model is compared for simulating the bubble collapse case until time 6.5 μs. The user-cpu time for the Helmholtz model is almost 3.7 times the HEM time, whereas the barotropic simulations are computationally the most efficient, as the execution time is almost 52 times smaller than the HEM time. The main reason for the increased cpu-time of the HEM model is the iterative calculation of the temperature using Newton-Raphson method, which necessitates complex expressions, especially in the mixture regime. The energy equation, which is not solved in the barotropic model, has a minor effect on the computational cost of the HEM with temperature effects.

4. Conclusions

In the present work, an explicit density-based solver with real fuel thermodynamics using the Helmholtz energy EoS has been presented. A Mach consistent numerical flux has been implemented, able to handle low as well as high Mach number flows. The numerical scheme has been validated against two benchmark test cases (Riemann problem, Rayleigh collapse); following numerical experiments for a vapour collapsing bubble near the vicinity of a wall have been performed. Since there is no analytical solution for this case or any other reference, comparison with other models has been made and areas where the fluid transitions to supercritical state have been identified. The results are satisfactory and encouraging enough in order to further expand this methodology to more realistic geometries, such as injector nozzles and expand the formulation to include non-condensable gases. The temperature variation of the fuel inside the injector can dramatically change its properties and thus affect

the flow field, which is not feasible in barotropic models, where no temperature effects exist. The bilinear finite element interpolation which was chosen, is a good compromise between complexity and accuracy. A posteriori error estimation was performed and error was found to be less than 1% in all thermodynamic properties.

Although no gas phase is included in the current model and thus the heating in the inner of the bubble cannot be predicted, real fluid thermodynamics are incorporated in the algorithm, with the potential of predicting supercritical transitions. The barotropic model is robust and can be used as a reference, but temperature effects are ignored. The HEM with simplified thermodynamics, is only applicable for a small range of temperatures. On the other hand, Helmholtz EoS is applicable for a wider range, as long as experimental data exist to calibrate the equation. While the trend of all thermodynamic models employed is similar, supercritical transitions are only possible to capture using the Helmholtz (or equivalent cubic/high order EoS, such as Peng-Robinson, see (Lacaze et al., 2015)), showing the importance of accurate thermodynamic modelling.

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Appendix

Derivation of the exact Riemann Problem solution for an arbitrary equation of state of the form $p=f(\rho,e)$.

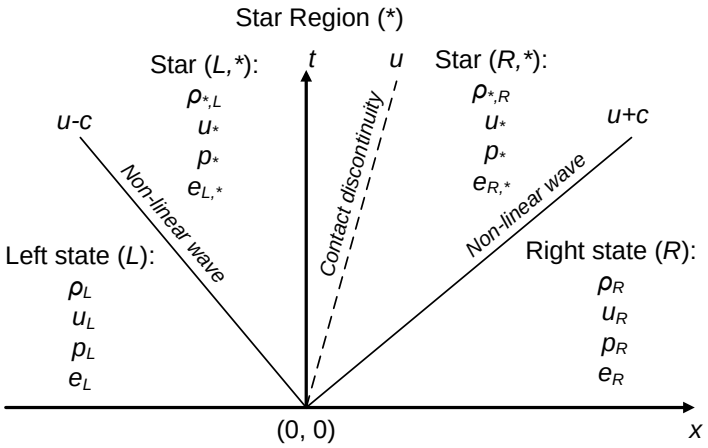

Figure A.1. Wave structure of the Riemann problem for the Euler equations for a general equation of state $p=f(\rho,e)$.

In this section, the methodology for finding the exact solution to the Riemann problem for the Euler equations, for an arbitrary equation of state of the form $p=f(\rho,e)$ is derived. The equation of state may be provided in closed form, where simplifications as in Toro (2009) may be done, or in a general tabular form. The interested reader is also addressed to (Le Métayer et al., 2005; Menikoff and Plohr, 1989; Müller et al., 2009; Müller and Voss, 2006; Petitpas et al., 2009; Saurel et al., 2008; Saurel and Lemetayer, 2001). The form of the Riemann problem solved is:

$$\begin{cases} \dfrac{\partial \mathbf{U}}{\partial t} + \dfrac{\partial \mathbf{F}(\mathbf{U})}{\partial x} = 0 \\ \mathbf{U}(x,0) = \begin{cases} \mathbf{U_L} & x < 0 \\ \mathbf{U_R} & x \geq 0 \end{cases} \end{cases} \tag{A.1}$$

where **U**(x,t) is the vector of conservative variables and **F**(**U**) is the flux vector, as shown below:

$$\mathrm{U} = \begin{bmatrix} \rho \\ \rho u \\ \rho E \end{bmatrix} \qquad \mathrm{F}(\mathrm{U}) = \begin{bmatrix} \rho u \\ \rho u^2 + p \\ u(\rho E + p) \end{bmatrix}$$

where $E = \frac{1}{2}u^2 + e$, with *e* the internal energy. The Jacobian matrix, **A**(**U**) is:

$$\mathbf{A}(\mathbf{U}) = \begin{bmatrix} 0 & 1 & 0 \\ \dfrac{\partial p}{\partial \rho} + \dfrac{\dfrac{\partial p}{\partial e}\left(u^2 - 2e\right) - 2\rho u^2}{2\rho} & u\left(2 - \dfrac{\partial p}{\partial e}\right) & \dfrac{1}{\rho}\dfrac{\partial p}{\partial e} \\ -\dfrac{u\left[2p + \dfrac{\partial p}{\partial e}\left(2e - u^2\right) + \rho\left(u^2 - 2\dfrac{\partial p}{\partial \rho} + 2e\right)\right]}{2\rho} & \dfrac{\left(\rho - 2\dfrac{\partial p}{\partial e}\right)u^2 + 2p + 2e\rho}{2\rho} & \dfrac{\left(\dfrac{\partial p}{\partial e} + \rho\right)u}{\rho} \end{bmatrix}$$

and the eigenvalues [λ_1, λ_2, λ_3] are

$$\lambda_1 = u - \sqrt{\frac{\partial p}{\partial \rho} + \frac{\partial p}{\partial e}\frac{p}{\rho^2}}$$

$$\lambda_2 = u$$

$$\lambda_3 = u + \sqrt{\frac{\partial p}{\partial \rho} + \frac{\partial p}{\partial e}\frac{p}{\rho^2}}$$

The solution of the Euler equations (A.1) is self similar, with two genuinely non-linear waves, corresponding to λ_1 and λ_3 eigenvalues, that can be either shock waves or rarefaction waves (Figure A.1). These waves separate the solution of the Riemann problem to the Left state, the Right state and the Star state (denoted with '$_*$' from now on) which is unknown; note that in the star region pressure and *u* velocity are the same, but density and internal energy are not. Density and internal energy change not only across the non-linear waves, but also along the contact discontinuity (corresponding to λ_2).

To find the solution to the Riemann problem, one needs to solve a non-linear algebraic equation for pressure:

$$g(p_*) = g_L(p_*) + g_R(p_*) + u_R - u_L = 0 \tag{A.2}$$

Functions g_L and g_R depend on the type of non-linear wave. For shock wave the Rankine-Hugoniot conditions are employed, eventually leading to:

$$g_{K,shock} = \left[\frac{(p_* - p_K)(\rho_{*,K} - \rho_K)}{\rho_{*,K}\,\rho_K}\right]^{1/2} \tag{A.3}$$

for *K*=*L* or *R* state. Apart from A.3, energy conservation applies across the shock wave, thus:

$$e_{*,K} = \frac{1}{2}\left(p_* + p_K\right)\left(\frac{\rho_{*,K} - \rho_K}{\rho_{*,K}\ \rho_K}\right) + e_K \tag{A.4}$$

To solve A.4 and A.3 an iterative procedure is required; initially one assumes an initial internal energy $e'_{*,K}$ (e.g. equal to e_K) which, combined with pressure p_*, corresponds to a density $\rho_{*,K}$. This density can be used to obtain the $g_{K,shock}$ function and the internal energy from the energy balance (A.4). Since $e_{*,K}$ from (A.4) and $e'_{*,K}$ are not necessarily the same, due to the guessed value of the latter, $e'_{*,K}$ is corrected and the process is repeated till convergence.

For the rarefaction wave, the calculation is more complicated, since it involves the Riemann invariants across an isentropic path. The Riemann invariants are shown below for the left rarefaction wave:

$$du + \frac{c}{\rho}d\rho = 0 \ \text{ for } s=s_L \tag{A.4}$$

and for right rarefaction wave

$$du - \frac{c}{\rho}d\rho = 0 \ \text{ for } s=s_R \tag{A.5}$$

Integration of these relations is not convenient to be done analytically for a general equation of state, which might be expressed in tabular form. It is rather convenient to perform the integration numerically on an isentropic path across the rarefaction wave, as follows for e.g. the left rarefaction wave:

$$u_* - u_L + \int_L^* \left(\frac{c}{\rho}\right)_{s=s_L} d\rho = 0 \tag{A.6}$$

One can split the integral as follows:

$$u_* + \int_{ref}^* \left(\frac{c}{\rho}\right)_{s=s_L} d\rho = u_L + \int_{ref}^L \left(\frac{c}{\rho}\right)_{s=s_L} d\rho \tag{A.7}$$

where *ref* is a reference state at e.g. at the minimum allowable density of the equation of state. In a similar manner one may derive the relation for the right rarefaction wave:

$$u_* - \int_{ref}^* \left(\frac{c}{\rho}\right)_{s=s_R} d\rho = u_R - \int_{ref}^R \left(\frac{c}{\rho}\right)_{s=s_R} d\rho \tag{A.8}$$

and eventually, the function

$$g_{K,rarefaction} = \int_{ref}^* \left(\frac{c}{\rho}\right)_{s=s_K} d\rho - \int_{ref}^K \left(\frac{c}{\rho}\right)_{s=s_R} d\rho \tag{A.9}$$

Hereafter the integral $\int_{ref}^K \left(\frac{c}{\rho}\right)_{s=s_K} d\rho$ will be referred to as $I_K(p_K)$.

Calculation of the isentropic integral $I_K(p_K)$ may be done numerically. At first, one needs to calculate the states that have the same entropy, s, as the right (R) and left (L) state. Assuming that the thermodynamic properties are expressed in the form of $f(\rho,e)$, the isentropic path may be calculated as follows:

1. determine the entropy of the K state (K can be either L or R), as $s_K=s(\rho_K,e_K)$

2. starting from a low reference density, ρ_{ref}, and increasing by intervals $d\rho$, the point that corresponds to s_K is found by iteratively correcting internal energy, e, for the given path point

i. Internal energy correction may be done with the Newton-Raphson method, till a specified tolerance is reached.

3. after reaching the tolerance, the rest thermodynamic properties (e.g. pressure, speed of sound etc.) for (ρ_i, e_i) may be found. Speed of sound, *c*, is needed to evaluate the term inside the integral *I*. Pressure is needed in order to express the integral as a function of pressure; this is preferable, because pressure at the whole star region is the same. The integral may be calculated by using the trapezoid rule, or a more accurate Simpson method. Care should be taken in areas of large changes in the speed of sound, as e.g. near saturation lines.

4. the procedure may be done till a high pressure p_{max} which should be greater than the pressure expected to appear in the rest calculations.

Switching between rarefaction and shock wave is done based on pressure:

$$g_K = \begin{cases} g_{K,rarefaction} & p_K < p_* \\ g_{K,shock} & p_K \geq p_* \end{cases} \tag{A.10}$$

The solution for the star region can be achieved with the Newton-Raphson method:

$$p_n = p_{n-1} - \frac{g(p_{n-1})}{g'(p_{n-1})} urf \tag{A.11}$$

where *n* is the number of the iteration, *urf* is an under-relaxation factor to enhance stability in case of highly non-linear EOS and g' is the derivative of eq. A.2. Note that for such equations it is preferable to resort to a numerically approximated value of the derivative, as:

$$g'(\rho) = \frac{g(\rho+\varepsilon) - g(\rho)}{\varepsilon} \tag{A.12}$$

where ε is a small positive number.

For highly non-linear EOS, it might be preferable also to bound the maximum change of pressure from iteration to iteration, in order to prevent overshoots/undershoots and enhance stability, i.e.:

$$p_n = \max(\min(p_n, p_{\max}), p_{\min})$$

where p_{max}, p_{min} can be a percentage of density during the previous iteration, e.g. 120% and 80% of p_{n-1} respectively. After determining p_* within sufficient tolerance, determining velocity u_* is trivial, though the following equation:

$$u_* = 0.5(u_L + u_R) + 0.5[g_R(p_*) - g_L(p_*)] \tag{A.13}$$

Identification of the type of waves is done depending on pressure at the star region comparing to the left and right states: if $p_* > p_K$ then the wave between the star and *K* region is a shock wave, else it is a rarefaction wave. The type of wave determines the wave speed and the transition between the two states. For a shock wave the transition is sharp and the wave speed is given by:

$$\text{Left shock: } S_L = u_L - \frac{Q_L}{\rho_L}, \text{ right shock } S_R = u_R + \frac{Q_R}{\rho_R} \tag{A.14}$$

with

$$Q_K = \left[\frac{(p_* - p_K)\rho_{*,K}\rho_*}{\rho_{*,K} - \rho_K} \right]^{1/2} \tag{A.15}$$

Rarefactions, contrary to shocks, are gradual changes in density, pressure and velocity. Thus, they are associated with two speeds, one for the head of the rarefaction and one for the tail:

$$\text{Left rarefaction, head: } S_{LH} = u_L - c_L \text{ tail: } S_{LT} = u_* - c_{*,L} \tag{A.16}$$

$$\text{Right rarefaction, head: } S_{RH} = u_R + c_R \text{ tail: } S_{RT} = u_* + c_{*,R} \tag{A.17}$$

In order to find the conditions inside the rarefaction wave, the Riemann invariants shall be used. For a left rarefaction, one has to solve the following equation for the point *i* inside the rarefaction:

$$\frac{x_i}{t} + c(p_i) + I_L(p_i) = u_L + I_L(p_L) \tag{A.18}$$

Similarly, for the right rarefaction

$$\frac{x_i}{t} - c(p_i) - I_R(p_i) = u_R - I_R(p_R) \tag{A.19}$$

Solution of eq. A.18 and A.19 can be done numerically, solving for density, using Newton-Raphson method, applying under-relaxation and taking care during the updating of the density values. Experience has shown that it is better to apply a low under-relaxation factor of even 0.02.

Assuming the dodecane Helmholtz EOS and assuming an initial discontinuity of the form ρ_L=752.5kg/m^3 and temperature T_L=289K for x<0, ρ_R=717.5kg/m^3 and T_R=350K for x≥0 (which corresponds to p_L~44330Pa and p_R~109bar), one obtains that the solution of the Riemann problem at the star region is:

p_*= 6017572Pa, u_*= -5.94m/s

$\rho_{*,L}$= 755.86kg/m^3, $\rho_{*,R}$= 713.48kg/m^3

$T_{*,L}$= 290.02K, $T_{*,R}$= 349.47K

With rarefaction wave to the right S_{TR}=1125.13m/s, S_{HR}=1162.62m/s and shock wave to left S_L=-1336.49m/s.

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