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A new rolling tachyon solution of cubic string field theory

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ABSTRACT: We present a new analytic time dependent solution of cubic string field theory at the lowest order in the level truncation scheme. The tachyon profile we have found is a bounce in time, a C^∞ function which represents an almost exact solution, with an extremely good degree of accuracy, of the classical equations of motion of the truncated string field theory. Such a finite energy solution describes a tachyon which at $x^0 = -\infty$ is at the maximum of the potential, at later times rolls toward the stable minimum and then up to the other side of the potential toward the inversion point and then back to the unstable maximum for $x^0 \rightarrow +\infty$. The energy-momentum tensor associated with this rolling tachyon solution can be explicitly computed. The energy density is constant, the pressure is an even function of time which can change sign while the tachyon rolls toward the minimum of its potential. A new form of tachyon matter is realized which might be relevant for cosmological applications.

KEYWORDS: Tachyon Condensation, String Field Theory.

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1. Introduction

In recent years there has been great progress, particularly due to Sen, in our understanding of the role of the tachyon in string theory (see [1] with references to earlier works). The basic idea is that the perturbative open string vacuum is unstable but there exists a stable vacuum toward which a tachyon field naturally moves.

String theory must eventually address cosmological issues and hence it is crucial to understand the role of time dependent solutions of the theory. The rolling tachyon [2] is an example of such a solution and in fact it has been applied to the study of tachyon driven cosmology, cosmological solutions describing the decaying of unstable space filling D-branes [3, 4]. In the decay, the energy density remains constant and the pressure approaches zero from negative values as the tachyon rolls toward its stable minimum. This form of tachyon matter could have astrophysical consequences and it then seems of utmost importance to confirm its existence using string field theory.

The boundary states approach to the rolling tachyon is the one that initiated the new investigation on time dependent solutions in string theory [2]. However, the understanding of the final fate of the unstable D-brane and the description of the time evolution of the boundary state are still far from being complete. These conformal field theory methods provide an indirect way of constructing solutions of the classical equations of motion without knowing the effective action. A more direct derivation of the classical solutions can be realized by explicitly constructing the tachyon effective action. Namely one starts from a string field theory in which, in principle, the coupling of the tachyon to the infinite tower of other fields associated with massive open string states could be taken into account. String field theory should then be a natural setting for the study of time dependent rolling tachyon solutions. In the boundary string field theory (BSFT) approach to string field theory [5] a rolling tachyon solution has been found and can be directly associated with a given two dimensional conformal field theory [6–8]. The relationship between the boundary state and the boundary string field theory approaches is in fact very explicit.

The direct approach based on the analysis of the classical equations of motion of bosonic open string field theory (cubic string field theory, CSFT [9]) is generally believed to be equivalent to the approach based on two dimensional conformal field theory. This equivalence is however less than manifest also because it is not yet known a satisfactory rolling tachyon solution of the cubic string field theory equations of motion even at the classical level and at the lowest order, the $(0, 0)$, in the level truncation scheme [10, 11]. In this paper we solve this problem providing a well behaved (almost exact) time dependent solution of the lowest order equations of motion of cubic string field theory. At this order one considers only the tachyon field and the cubic string field theory action becomes

$$S = \frac{1}{g_0^2} \int d^{26}x \left(\frac{1}{2} t(x) (\square + 1) t(x) - \frac{1}{3} \lambda_c \left(\lambda_c^{(1/3)\square} t(x) \right)^3 \right), \quad (1.1)$$

where the coupling λ_c has the value

$$\lambda_c = \frac{3^{9/2}}{2^6} = 2.19213. \quad (1.2)$$

Considering spatially homogeneous profiles of the form $t(x^0)$, where x^0 is time, the equation of motion derived from (1.1) is

$$(\partial_0^2 - 1)t(x^0) + \lambda_c^{1-\partial_0^2/3} \left(\lambda_c^{-\partial_0^2/3} t(x^0) \right)^2 = 0. \quad (1.3)$$

We have found an almost exact analytic solution of this equation, which is given by the following well defined integral ¹

$$t(x^0) = \frac{9\lambda_c^{-5/3}}{4\sqrt{\pi} \log \lambda_c} \int_0^\infty d\tau (1 - 2\tau^2) e^{-\tau^2} \log \left[\cosh x^0 + \cos(4\tau \sqrt{\log \lambda_c/3}) \right]. \quad (1.4)$$

Being the equation of motion time reversal invariant, the solution (1.4) is a symmetric bounce in x^0 , a C^∞ function with the appropriate boundary conditions to describe a rolling tachyon. Such a constant energy density solution, in fact, describes a tachyon which at $x^0 = -\infty$ is at the maximum of the potential, at later times rolls toward the stable minimum and then up to the other side of the potential toward the inversion point and then back to the unstable maximum for $x^0 \rightarrow \infty$.

If the decaying D-brane is coupled to closed strings it will act as a source for closed string modes [12–14]. A rolling tachyon is a time dependent source which will produce closed string radiation. All the energy of the D-brane will eventually be radiated away into closed strings. In the classical rolling tachyon picture described above this would correspond to the introduction of a friction that would eventually stop the rolling tachyon at the minimum of its potential.

The profile (1.4) does not present all the cumbersome features found in previous works on rolling tachyons in cubic string field theory, like ever growing oscillations with time and an energy-momentum tensor that cannot be derived [15, 16, 11, 17]. For the tachyon profile (1.4) in fact the associated energy-momentum tensor can be computed explicitly.

¹In what sense this is an “almost” exact solution will be explained in section 2.

The energy density \mathcal{E} is constant while the pressure $p(x^0)$ is an even function of time. Pressure and energy density depend on an arbitrary constant (the constant up to which the action is defined) and they can be chosen for example in such a way that the Dominant Energy Condition, $\mathcal{E} \geq |p(x^0)|$, holds at any instant of time. In this case the pressure $p(x^0)$ starts negative when the tachyon is at the unstable maximum of the potential, at later times becomes positive, while the tachyon reaches the minimum of the potential, and finally it goes back to its negative starting value at $x^0 = +\infty$. By choosing the initial energy density to be higher, however, one might even realize the situation in which the tachyon reaches the minimum of its potential when its pressure vanishes. The rolling tachyon matter associated to the solution has in this case an interesting equation of state $p(x^0) = w\mathcal{E}$, with w that smoothly interpolates between -1 and 0 , while the tachyon moves from the maximum of its potential to the minimum [18]. Passed this time, however, the pressure becomes positive until the tachyon goes again through its minimum. This form of tachyon matter is thus different to the one described in [18, 8, 19].

In boundary string field theory and in most of the models used to study tachyon driven cosmology, the stable minimum of the potential is taken at infinite values of the tachyon field [20–22, 18, 8, 19]. The tachyon thus cannot roll beyond its minimum. One of the main objections to the rolling tachyon as a mechanism for inflation is that reheating and creation of matter in models where the minimum of the potential is at $T \rightarrow \infty$ is problematic because the tachyon field in such theory does not oscillate [23, 3]. In cubic string field theory the naive value of the minimum of the potential is at finite values of the tachyon field ². Therefore, the coupling of the free theory to a Friedman-Robertson-Walker metric [3], and the consequent inclusion of a Hubble friction term, might lead from the classical solution (1.4) to damped oscillations around the stable minimum of the potential well. Cubic string field theory might then open new perspectives in tachyon cosmology.

It is also possible, however, that a true solution of the complete cubic string field theory without the level approximation would be non-oscillating, like Sen’s rolling tachyon solution. In fact the inclusion of higher level fields might change the interactions in such a way that even if the minimum of the potential would stay at finite values of the tachyon field the rolling tachyon solution would not have oscillations about it, but would just reach the minimum of the potential at infinite times. As we shall show also for the solution (1.4) the tachyon rolls from the top of the potential towards the stable minimum and then up to the other side, but the inversion point is lower than the maximum of the potential. This is because the cubic term in the interaction is dressed by a kinematical factor depending on the tachyon field derivatives.

The paper is organized as follows. In section 2 we derive the solution (1.4) and discuss its analytical properties. In section 3 we compute the associated energy momentum tensor, study its time dependence and discuss the tachyon matter it describes. In the conclusions we outlook some possible checks and applications of the new rolling tachyon solution of cubic string field theory.

²By “naive” we mean that a field redefinition could always map the minimum of the potential at infinity, the kinetic term might however assume a non standard form [24].

2. The rolling tachyon solution in cubic string field theory

The action of cubic open string field theory reads [9]

$$S = -\frac{1}{g_0^2} \int \left(\frac{1}{2} \Phi \cdot Q_B \Phi + \frac{1}{3} \Phi \cdot (\Phi * \Phi) \right), \quad (2.1)$$

where Q_B is the BRST operator, $*$ is the star product between two string fields and Φ is the open string field containing component fields which correspond to all the states in the string Fock space. If we consider only the tachyon field $t(x)$ in Φ , $|\Phi\rangle = b_0|0\rangle t(x)$, the action (2.1) becomes (1.1). For profiles that only depend on the time x^0 the equation of motion derived from (2.1) is (1.3) and we shall now look for a solution to that equation. Our procedure is based on the idea that eq. (1.3) can be generalized to become a non-linear differential equation with an arbitrary parameter λ which substitutes the fixed value (1.2)

$$(\partial_0^2 - 1)t(x^0) + \lambda^{1-\partial_0^2/3} \left(\lambda^{-\partial_0^2/3} t(x^0) \right)^2 = 0. \quad (2.2)$$

Then λ can be treated as an *evolution* parameter. Fixing the initial value $\lambda = 1$ one can easily find an exact solution to (2.2) and then one can study how this solution evolves to different values of λ keeping its property of being a solution of (2.2). We shall find that the equation governing the evolution in λ is extremely simple and we shall look for a solution of (2.2) for generic λ , setting eventually $\lambda = \lambda_c$ as in (1.2).

When $\lambda = 1$, eq. (1.3) admits a particularly simple exact solution, the following bounce

$$t(\log \lambda = 0, x^0) = \frac{3}{2 \cosh^2(x^0/2)} = 6 \int_0^\infty \frac{\tau \cos(\tau x^0)}{\sinh(\pi \tau)} d\tau. \quad (2.3)$$

The boundary conditions of (2.3) are such that $\partial t(0, x^0)/\partial x^0 = 0$ at $x^0 = \pm\infty$.

Now we shall interpret the solution (2.3) as the “initial” condition of an “evolution” equation with respect to the “time” $\log \lambda$. To find how the solution evolves we shall have to provide a careful treatment of infinite derivative operators of the type

$$q^{\partial^2} = e^{\log q \partial^2} \equiv \sum_{n=0}^{\infty} \frac{(\log q)^n}{n!} \partial^{2n}, \quad (2.4)$$

which act on the function $t(x^0)$ in (2.2) when $\lambda \neq 1$. These operators play a crucial role in string field theories and related models. We shall thus provide a possible solution to the long standing problem of how to treat this infinite derivative operators in string field theory.

A particularly convenient redefinition of the tachyon field that leaves invariant the initial condition (2.3) is

$$T(\log \lambda, x^0) = \lambda^{5/3+\partial_0^2/3} t(\log \lambda, x^0). \quad (2.5)$$

With this field redefinition eq. (1.3) transforms into the following

$$(\partial_0^2 - 1)T(\log \lambda, x^0) + \lambda^{-2/3} \left(\lambda^{-2\partial_0^2/3} T(\log \lambda, x^0) \right)^2 = 0. \quad (2.6)$$

Since the operator $\lambda^{-2\partial_0^2/3}$ is defined as a power series of $\log \lambda$ through eq. (2.4), it is natural to look for solutions of eq. (2.6) of the form

$$T(\log \lambda, x^0) = \sum_{n=0}^{\infty} \frac{(\log \lambda)^n}{n!} t_n(x^0). \quad (2.7)$$

It is not difficult to check that at any desired order n in (2.7) the functions $t_n(x^0)$ can *always* be written as finite sums of the form

$$t_n(x^0) = \sum_{k=0}^n \frac{a_k^{(n)}}{\cosh^{2k+2}(x^0/2)}, \quad (2.8)$$

and the differential equation for the tachyon field becomes an algebraic equation for the unknown coefficients $a_k^{(n)}$. Thus, an exact solution of (2.6) can always be obtained as a series representation. However, in order to obtain solutions preserving the correct boundary conditions, it is mandatory to look for solutions that, although approximate, sum the *whole* series (2.7) rather than to find the exact coefficients $a_k^{(n)}$ at any fixed truncation n of the sum (2.7). In fact, it is easy to show that any truncation of the sum (2.7) leads to solutions with wild oscillatory behavior with increasing amplitudes, whose physical meaning is difficult to interpret. Only the resummation of the whole series smoothens such oscillations.

A more convenient representation of $t_n(x^0)$ alternative to (2.8) is given by

$$t_n(x^0) = 6 \int_0^{\infty} \frac{\tau \cos(\tau x^0)}{\sinh(\pi\tau)} P_n(\tau) d\tau, \quad (2.9)$$

$P_n(\tau)$ being a polynomial of even powers of τ of degree $2n$. This representation is particularly useful since it provides the $t_n(x^0)$ in terms of eigenfunction of the operator ∂_0^2 . The field redefinition (2.5) was chosen in such a way that the form of the coefficients (2.9) becomes particularly simple, so simple that the series (2.7) can be resummed. Requiring that the profile (2.7) satisfies the boundary conditions $\partial T(0, x^0)/\partial x^0 = 0$ at $x^0 = \pm\infty$ as in (2.3) and that it is a very accurate approximate solution of the equation of motion (2.6), fixes the polynomials $P_n(\tau)$ to be of the form

$$P_n(\tau) \simeq \tau^{2n}. \quad (2.10)$$

This leads to the following approximate solution of eq. (2.6)

$$T(\log \lambda, x^0) = 6 \int_0^{\infty} \frac{\tau \cos(\tau x^0)}{\sinh(\pi\tau)} e^{\log \lambda \tau^2} d\tau = 6\lambda^{-\partial_0^2} \int_0^{\infty} \frac{\tau \cos(\tau x^0)}{\sinh(\pi\tau)} d\tau, \quad \lambda < 1. \quad (2.11)$$

Note that all the λ -dependence in (2.11) is encoded in the operator $\lambda^{-\partial_0^2}$ acting on the solution of eq. (2.6) with $\lambda = 1$. In fact $T(\log \lambda = 0, x^0) \equiv t(\log \lambda = 0, x^0)$ and $\lambda^{-\partial_0^2}$ plays the role of the “evolution” operator (with respect to the “time” $\log \lambda$) acting on the initial condition $T(\log \lambda = 0, x^0)$,

$$T(\log \lambda, x^0) = \lambda^{-\partial_0^2} T(\log \lambda = 0, x^0). \quad (2.12)$$

Clearly, the representation (2.11) of the solution $T(\log \lambda, x^0)$ is valid only for $\lambda \in (0, 1]$. In our case the physically relevant value of λ is the one given in (1.2), which is greater than one. Consequently, we need an analytical continuation of the representation (2.11) to positive values of $\log \lambda$.

Eq. (2.11) shows that the evolution of the tachyon field with respect to the parameter $\log \lambda$ is simply driven by the diffusion equation with (negative) unitary coefficient. In fact (2.11) satisfies the diffusion equation

$$\frac{\partial T(\log \lambda, x^0)}{\partial \log \lambda} = -\frac{\partial^2 T(\log \lambda, x^0)}{\partial (x^0)^2} \tag{2.13}$$

with respect to the “time” variable $\log \lambda$ and the “space” variable x^0 , with “initial” and “boundary” conditions $T(0, x^0) = 3/[2\cosh^2(x^0/2)]$, $T(\log \lambda, \pm\infty) = 0$.

Now we face the problem of the analytical continuation of the representation (2.11) to positive values of $\log \lambda$. Setting $\tau = -is$ in eq. (2.11), we rewrite T as

$$T(\log \lambda, x^0) = \frac{3}{i} \lambda^{-\partial_0^2} \int_{-i\infty}^{+i\infty} \frac{s e^{sx^0}}{\sin(\pi s)} ds. \tag{2.14}$$

In eq. (2.14) the integral can be closed with semi-circles at infinity to the right or to the left depending on the sign of x^0 . Let us choose for instance $x^0 < 0$. Then (2.14) reads

$$T(\log \lambda, x^0 < 0) = -6\lambda^{-\partial_0^2} \sum_{n=1}^{\infty} (-1)^n n e^{nx^0}. \tag{2.15}$$

In eq. (2.15) one would be tempted to replace the operator $\lambda^{-\partial_0^2}$ with its eigenvalue λ^{-n^2} inside the series, namely

$$-6 \sum_{n=1}^{\infty} (-1)^n \lambda^{-n^2} n e^{nx^0}, \quad \lambda > 1, \tag{2.16}$$

thus providing very easily the required analytical continuation to the region $\lambda > 1$. However this procedure is incorrect. This is an important point, as the solutions in cubic string field theory (CSFT) analyzed in the recent literature [11] have precisely the form (2.16). A cavalier treatment of the infinite derivative operator $\lambda^{-\partial_0^2}$, however, might lead to the wrong conclusion that no rolling tachyon solutions exist in CSFT.

To understand why the procedure leading to (2.16) is incorrect, note that it would correspond to replace the operator $\lambda^{-\partial_0^2}$ with λ^{-s^2} in the integrand of eq. (2.14), and then closing the integral with a semicircle at infinity in the half-plane $\text{Re } s > 0$. This cannot be done when the factor λ^{-s^2} is inserted in the integrand. The path of integration in fact, cannot be closed by *any* curve at infinity, for any sign of $\log \lambda$: if $\lambda < 1$ the integral would diverge at $s = \pm\infty$, whereas if $\lambda > 1$ it would diverge at $s = \pm i\infty$ and the integral (2.14) could never be computed as sum of residues. Thus, in spite of the fact that the series in (2.16) has infinite convergence radius for $\lambda > 1$, it does *not* provide the analytical continuation of (2.11).

Another argument which can be given to understand why (2.16) does not reproduce the tachyon field for $\lambda > 1$ is the following. Eq. (2.11) is manifestly even, and then all its odd derivatives must vanish at the origin $x^0 = 0$ ³. This is not true for the representation (2.16).

A possible way to overcome these difficulties, and thus to solve the problem of how infinite derivative operators of the type $\lambda^{-\partial_0^2}$ can be treated, is through a Mellin-Barnes representation for the operator $\lambda^{-\partial_0^2}$,

$$\lambda^{-\partial_0^2} = \sum_{n=0}^{\infty} \frac{(-\log \lambda)^n}{n!} \partial_0^{2n} = \frac{1}{2\pi i} \int_{\gamma-i\infty}^{\gamma+i\infty} ds \Gamma(-s) (\log \lambda)^s \partial_0^{2s}, \quad \text{Re } \gamma < 0. \quad (2.17)$$

Acting with (2.17) in (2.15), we find

$$\begin{aligned} T(\log \lambda, x^0 < 0) &= -\frac{3}{\pi i} \int_{\gamma-i\infty}^{\gamma+i\infty} ds \Gamma(-s) (\log \lambda)^s \sum_{n=1}^{\infty} (-1)^n n^{2s+1} e^{nx^0} \\ &= \frac{3e^{x^0}}{\pi i} \int_{\gamma-i\infty}^{\gamma+i\infty} ds \Gamma(-s) (\log \lambda)^s \Phi(-e^{x^0}, -2s-1, 1) \\ &= \frac{12e^{x^0}}{\sqrt{\pi}i} \int_{\gamma-i\infty}^{\gamma+i\infty} ds \frac{(4 \log \lambda)^s}{\Gamma(-s-1/2)} \int_0^{\infty} \frac{dt}{t^2} \frac{t^{-2s}}{e^{x^0} + e^t}, \end{aligned} \quad (2.18)$$

where Φ is the Lerch Transcendent defined as

$$\begin{aligned} \Phi(z, s, v) &= \sum_{n=0}^{\infty} (v+n)^{-s} z^n, \quad |z| < 1, \quad v \neq 0, -1, -2, \dots \\ &= \frac{1}{\Gamma(s)} \int_0^{\infty} dt \frac{t^{s-1} e^{-(v-1)t}}{e^t - z}, \end{aligned} \quad (2.19)$$

and the last equation in (2.18) follows from the integral representation of Φ given in (2.19). The gamma function in (2.18) can be rewritten by using the formula

$$\frac{1}{\Gamma(-s-1/2)} = \frac{1}{2\pi i} \int_C dz e^z z^{s+1/2} \quad (2.20)$$

where C is the path drawn in figure 1.

Thus, the integral over s in (2.18) can be explicitly performed,

$$\int_{\gamma-i\infty}^{\gamma+i\infty} ds \left(\frac{4z \log \lambda}{t^2} \right)^s = i\pi \delta \left[\log t - \log \left(2\sqrt{z \log \lambda} \right) \right]. \quad (2.21)$$

In turn, integration of the δ -function leads to the expression

$$T(\log \lambda, x^0 < 0) = \frac{3}{i\sqrt{\pi \log \lambda}} \int_C dz \frac{e^z}{1 + e^{2\sqrt{z \log \lambda} - x^0}}. \quad (2.22)$$

It is easily realized that the contribution to the integral (2.22) given by the semicircle around the origin vanishes. The lower and upper branches of the path C are parametrized, according to the notation of figure 1, as

$$z = e^{-i\pi} t - i\epsilon, \quad t \in (\infty, 0),$$

³Another possibility would be that the odd derivatives of eq. (2.16) are discontinuous at the origin. This is indeed what happens with (2.16). Clearly this is unacceptable as the resulting functions would not belong to the definition domain of the operator $\lambda^{-\partial_0^2}$.

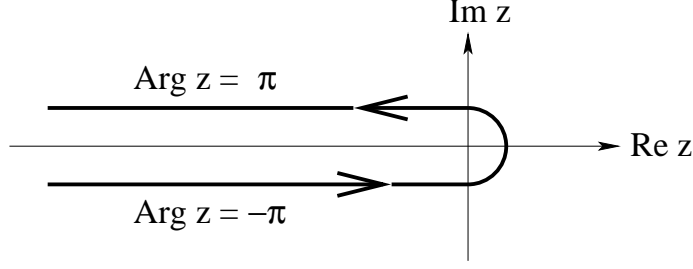


Figure 1: Contour C .

$$z = e^{i\pi}t + i\epsilon, \quad t \in (0, \infty), \quad (2.23)$$

respectively. Then, by changing variable $\tau = \sqrt{t}$, the integral (2.22) can be rewritten as

$$T(\log \lambda, x^0 < 0) = \frac{6}{\sqrt{\pi \log \lambda}} \int_0^\infty d\tau e^{-\tau^2} \frac{\tau \sin(2\tau\sqrt{\log \lambda})}{\cosh(x^0 - \epsilon) + \cos(2\tau\sqrt{\log \lambda})}, \quad \lambda > 1. \quad (2.24)$$

Note that the hyperbolic cosine in (2.24) is always greater than one ($x^0 \leq 0$ and $\epsilon > 0$), preventing any singularity in the integrand. Analogously, if we consider the case $x^0 > 0$ in (2.14), we obtain for $T(\log \lambda, x^0 > 0)$ an expression similar to (2.24) with $x^0 - \epsilon$ replaced by $x^0 + \epsilon$. Therefore, in any case no singularities arise and a representation for the tachyon field valid for any value of x^0 can be conveniently written as

$$T(\log \lambda, x^0) = \frac{6}{\sqrt{\pi \log \lambda}} \int_0^\infty d\tau e^{-\tau^2} \frac{\tau \sin(2\tau\sqrt{\log \lambda})}{e^\epsilon \cosh(x^0) + \cos(2\tau\sqrt{\log \lambda})}, \quad \lambda > 1. \quad (2.25)$$

Eq. (2.25) provides the required analytical continuation of (2.11) to positive values of $\log \lambda$. The regulator ϵ is immaterial for any point $x^0 \neq 0$ but it is crucial to prescribe the behavior at the origin. It guarantees that $T(\log \lambda, x^0) \in C^\infty$ in a neighbour of the origin and that all the odd derivatives of (2.25) vanish at $x^0 = 0$. To understand the mechanism, we can integrate by parts eq. (2.25) keeping $\epsilon \neq 0$. After integration by parts, the singularities of the denominator that would appear at $x^0 = 0$ in the $\epsilon \rightarrow 0$ limit become logarithmic (integrable) singularities. Then the regulator ϵ can be removed, obtaining

$$T(\log \lambda, x^0) = \frac{3}{\sqrt{\pi \log \lambda}} \int_0^\infty d\tau \frac{d}{d\tau} \left(\tau e^{-\tau^2} \right) \log[\cosh x^0 + \cos(2\sqrt{\log \lambda} \tau)]. \quad (2.26)$$

Iterating the procedure, any derivative of T can be written in a manifestly regular way. Note that, since ϵ can be eventually removed, it works as a prescription to define the integral (2.26) with all its derivatives. For example, the formula for the even derivatives of T reads

$$\frac{d^{2n}T(\log \lambda, x^0)}{d(x^0)^{2n}} = \frac{3(-1)^n}{2^{2n}\sqrt{\pi}(\log \lambda)^{n+1}} \int_0^\infty d\tau \frac{d^{2n+1}}{d\tau^{2n+1}} \left(\tau e^{-\tau^2} \right) \log[\cosh x^0 + \cos(2\sqrt{\log \lambda} \tau)]. \quad (2.27)$$

The representation (2.26) is defined for *any* real value of $\log \lambda$. For $\lambda > 1$ it provides the analytical continuation of (2.11), for $\lambda < 1$ it is still well defined and coincides with (2.11).

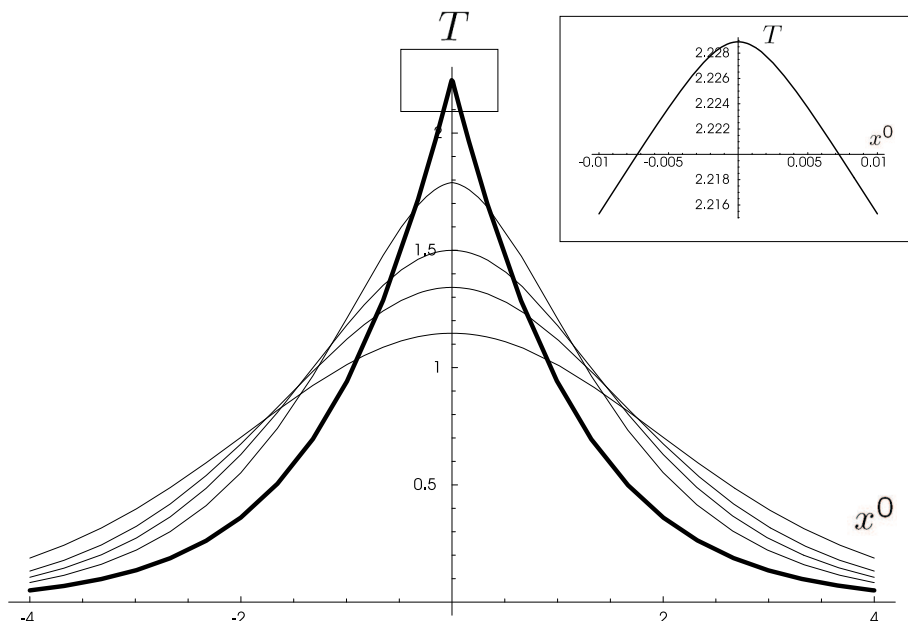


Figure 2: Different profiles of the solution $T(\log \lambda, x^0)$. The bold profile refers to $\lambda = \lambda_c$, the remaining ones to $\lambda_c^{1/3}, 1, \lambda_c^{-1/3}, \lambda_c^{-1}$. As seen in the box, the behavior of the solution with $\lambda = \lambda_c$ is smooth at the origin.

The solutions (2.26) have the form of bounces, for any value of λ . In figure 2 are drawn some profiles of the solution T for different values of λ . The bold profile refers to the physically relevant value $\lambda = \lambda_c$, the remaining ones correspond to $\lambda_c^{1/3}, 1, \lambda_c^{-1/3}, \lambda_c^{-1}$. Note the manifest continuity in λ exhibited in figure 2 passing from positive to negative values of $\log \lambda$.

To check the level of accuracy of the approximate solution (2.26) we must study the action of operators of the form $q^{\partial_0^2}$ on it. At first sight, this is a non trivial problem, as the x^0 -dependence in (2.26) is not through eigenfunctions of ∂_0^2 . Fortunately, eq. (2.26) still satisfies the diffusion equation (2.13), as can be checked by direct inspection. Therefore, the action of the operator $q^{\partial_0^2}$ on $T(\log \lambda, x^0)$ can be simply represented as a translation of $\log \lambda$

$$q^{\partial_0^2} T(\log \lambda, x^0) = e^{\log q \partial_0^2} T(\log \lambda, x^0) = e^{-\log q \frac{\partial}{\partial \log \lambda}} T(\log \lambda, x^0) = T(\log \lambda - \log q, x^0). \quad (2.28)$$

This remarkable property can only be used thanks to the fact that we have treated the quantity λ as a generic variable. In particular we shall have often to make use of the following operator

$$\begin{aligned} \lambda^{a\partial_0^2} T(\log \lambda, x^0) &= \sum_{n=0}^{\infty} a^n \frac{(\log \lambda)^n}{n!} \frac{\partial^{2n}}{\partial x^{02n}} T(\log \lambda, x^0) \\ &= \sum_{n=0}^{\infty} (-a)^n \frac{(\log \lambda)^n}{n!} \frac{\partial^n}{\partial (\log \lambda)^n} T(\log \lambda, x^0) \\ &= T((1-a) \log \lambda, x^0). \end{aligned} \quad (2.29)$$

where in the second equality we have used the diffusion equation (2.13).

A quantitative estimate of the accuracy of (2.26) can be obtained by calculating the L_2 norm of the left hand side ($LHS(\log \lambda, x^0)$) of eq. (2.6) evaluated on the approximate solution (2.26). If the solution of the equation was exact the value of this norm would be zero. Let us consider the physically relevant case $\lambda = \lambda_c$. In this case the L_2 norm of LHS gives $\|LHS\|^2 = 4.636 \cdot 10^{-8}$.

This value should be compared with a typical scale of the problem, for instance with the L_2 norm of T , which is $\|T\|^2 = 2.019$. This shows the impressive level of accuracy of the solution (2.26) ⁴

$$\left(\frac{\|LHS\|^2}{\|T\|^2}\right)_{\lambda=\lambda_c} \sim 2.3 \cdot 10^{-8}. \tag{2.30}$$

3. Energy-momentum tensor

The tachyon field $t(x^0)$ appearing in the original form of the level truncated CSFT (1.1) is obtained by the field redefinition (2.5) applied to (2.26) with $\lambda = \lambda_c$. Using (2.29), one has $t(x^0) = \lambda_c^{-5/3} T(\frac{4}{3} \log \lambda_c, x^0)$, namely

$$t(x^0) = \frac{9\lambda_c^{-5/3}}{4\sqrt{\pi} \log \lambda_c} \int_0^\infty \frac{d}{d\tau} \left(\tau e^{-\tau^2} \right) \log[\cosh x^0 + \cos(4\tau \sqrt{\log \lambda_c/3})]. \tag{3.1}$$

Eq. (3.1) is the analytic solution of our problem. It has the extremely good degree of accuracy (2.30) and it does not depend on *any* free parameter. In principle, one could try to improve the solution by introducing some external parameter in (3.1), but we have checked that this does not improve its accuracy.

Since we have at hand an action for the tachyon field, the energy-momentum tensor can be calculated as usual, by first including a metric tensor $g_{\mu\nu}$ in the action (1.1), varying the action S with respect to $g_{\mu\nu}$ and setting afterwards the metric to be flat, $g_{\mu\nu} = \eta_{\mu\nu}$.

It is also possible to add a constant term $-\alpha$ to the action (1.1). This is the only free constant we have and its choice can be dictated by physical considerations. In this way the tachyon potential reads

$$V[t] = -\frac{1}{2} t^2 + \frac{\lambda_c}{3} t^3 + \alpha. \tag{3.2}$$

Thus, we consider the action

$$S = \frac{1}{g_0^2} \int d^{26}x \sqrt{-g} \left(\frac{1}{2} t^2 - \frac{1}{2} g^{\mu\nu} \partial_\mu t \partial_\nu t - \frac{1}{3} \lambda_c \tilde{t}^3 - \alpha \right), \tag{3.3}$$

where $\tilde{t} = \lambda_c^{\frac{1}{3}} t$. The stress tensor then reads

$$T_{\alpha\beta} = -\frac{2}{\sqrt{-g}} \frac{\delta S}{\delta g^{\alpha\beta}}. \tag{3.4}$$

⁴Another possible check of the approximation would be to write eq. (2.6) as $LHS = RHS$, where $LHS = (\partial_0^2 - 1)T$, and to consider the quantity $\|LHS - RHS\|^2 / \|LHS\|^2$. The order of magnitude of this ratio is as in (2.30).

In varying (3.3) with respect to the metric tensor, one has to consider the covariant form of the D'Alembertian operator

$$\square = \frac{1}{\sqrt{-g}} \partial_\mu \sqrt{-g} g^{\mu\nu} \partial_\nu. \quad (3.5)$$

The variation of the operator $\lambda_c^{\frac{1}{3}\square}$ with respect to the metric can be performed by using the following identity

$$\frac{\delta \lambda_c^{\frac{1}{3}\square}}{\delta g^{\alpha\beta}} = \frac{1}{3} \log \lambda_c \int_0^1 ds \lambda_c^{\frac{1}{3}s\square} \frac{\delta \square}{\delta g^{\alpha\beta}} \lambda_c^{\frac{1}{3}(1-s)\square}. \quad (3.6)$$

An alternative way to get the variation of the infinitely many derivatives operator $\lambda_c^{\frac{1}{3}\square}$ would be through a power series [15, 16] representation of the type (2.4). However, the remarkable property (2.29) of our solution is particularly well suited to deal with operators of the type $\lambda_c^{\frac{1}{3}s\square}$. In fact, their action on $T(\log \lambda_c, x^0)$ consists in a trivial translation $\log \lambda_c \rightarrow (1 + \frac{1}{3}s) \log \lambda_c$. This will permit to write the energy momentum tensor in a simple and closed form. Most importantly, it will be written as a bilinear in the fields $T(\log \lambda_c, x^0)$ containing only *finite* derivatives. Substituting infinite derivative operators on the field $T(x^0, \log \lambda_c)$ with the field itself, but with the parameter λ_c traslated, allows to write the energy momentum tensor in a form analogous to that of an ordinary (finite derivatives) field theory.

Taking the equation of motion (1.3) and eqs. (2.5), (2.29), (3.3)-(3.6) into account, after some integrations by parts we get the following expression for the energy-momentum tensor

$$\begin{aligned} T_{\alpha\beta} = \lambda_c^{-10/3} \left\{ \delta_{\alpha 0} \delta_{\beta 0} \left(\partial_0 T \left(\frac{4}{3} \log \lambda_c, x^0 \right) \right)^2 + \right. \\ + g_{\alpha\beta} \left[\frac{1}{2} \left(\partial_0 T \left(\frac{4}{3} \log \lambda_c, x^0 \right) \right)^2 + \frac{1}{2} \left(T \left(\frac{4}{3} \log \lambda_c, x^0 \right) \right)^2 - \right. \\ \left. - \frac{1}{3} T \left(\frac{5}{3} \log \lambda_c, x^0 \right) (1 - \partial_0^2) T(\log \lambda_c, x^0) - \alpha \lambda_c^{10/3} \right] - \\ - \frac{1}{3} \log \lambda_c \int_0^1 ds \left[g_{\alpha\beta} (1 - \partial_0^2) T \left(\frac{4-s}{3} \log \lambda_c, x^0 \right) \partial_0^2 T \left(\frac{4+s}{3} \log \lambda_c, x^0 \right) + \right. \\ \left. + g_{\alpha\beta} (1 - \partial_0^2) \partial_0 T \left(\frac{4-s}{3} \log \lambda_c, x^0 \right) \times \right. \\ \left. \times \partial_0 T \left(\frac{4+s}{3} \log \lambda_c, x^0 \right) \right] + \\ \left. + 2 \delta_{\alpha 0} \delta_{\beta 0} (1 - \partial_0^2) \partial_0 T \left(\frac{4-s}{3} \log \lambda_c, x^0 \right) \partial_0 T \left(\frac{4+s}{3} \log \lambda_c, x^0 \right) \right\}. \quad (3.7) \end{aligned}$$

From (3.7) the explicit form of the energy density $\mathcal{E}(x^0) = T_{00}$ and the pressure $p(x^0) = T_{11}$ can be obtained

$$\mathcal{E}(x^0) = \lambda_c^{-10/3} \left\{ \frac{1}{2} \left(\partial_0 T \left(\frac{4}{3} \log \lambda_c, x^0 \right) \right)^2 - \frac{1}{2} \left(T \left(\frac{4}{3} \log \lambda_c, x^0 \right) \right)^2 \right.$$

$$\begin{aligned}
 & + \frac{1}{3}T\left(\frac{5}{3}\log\lambda_c, x^0\right)(1 - \partial_0^2)T(\log\lambda_c, x^0) + \alpha\lambda_c^{10/3} - \\
 & - \frac{1}{3}\log\lambda_c \int_0^1 ds \left[(1 - \partial_0^2)T\left(\frac{4-s}{3}\log\lambda_c, x^0\right) \partial_0^2 T\left(\frac{4+s}{3}\log\lambda_c, x^0\right) - \right. \\
 & \quad \left. - (1 - \partial_0^2)\partial_0 T\left(\frac{4-s}{3}\log\lambda_c, x^0\right) \times \right. \\
 & \quad \left. \times \partial_0 T\left(\frac{4+s}{3}\log\lambda_c, x^0\right) \right] \Bigg\}, \tag{3.8}
 \end{aligned}$$

$$\begin{aligned}
 p(x^0) = \lambda_c^{-10/3} \Bigg\{ & \frac{1}{2}\left(\partial_0 T\left(\frac{4}{3}\log\lambda_c, x^0\right)\right)^2 + \frac{1}{2}\left(T\left(\frac{4}{3}\log\lambda_c, x^0\right)\right)^2 - \\
 & - \frac{1}{3}T\left(\frac{5}{3}\log\lambda_c, x^0\right)(1 - \partial_0^2)T(\log\lambda_c, x^0) - \alpha\lambda_c^{10/3} - \\
 & - \frac{1}{3}\log\lambda_c \int_0^1 ds \left[(1 - \partial_0^2)T\left(\frac{4-s}{3}\log\lambda_c, x^0\right) \partial_0^2 T\left(\frac{4+s}{3}\log\lambda_c, x^0\right) + \right. \\
 & \quad \left. + (1 - \partial_0^2)\partial_0 T\left(\frac{4-s}{3}\log\lambda_c, x^0\right) \times \right. \\
 & \quad \left. \times \partial_0 T\left(\frac{4+s}{3}\log\lambda_c, x^0\right) \right] \Bigg\}. \tag{3.9}
 \end{aligned}$$

Even if from (3.8) the energy density seems to depend strongly on time, its plot will show that $\mathcal{E}(x^0)$ is actually a constant. The energy density is conserved and is always identical to the chosen height of the maximum of the potential, $\mathcal{E} = \alpha$. The pressure $p(x^0)$ is an even function of x^0 , it has the shape of a bounce in time asymptotically reaching the value $-\alpha$. Thus, increasing the value of α in (3.2), the energy grows and the pressure lowers of the same amount.

The choice of α can strongly influence the physical picture described by the solution (3.1). However, there are some features that are independent on this choice, namely the qualitative description of the tachyon motion and the asymptotic equation of state, which is always $p \sim -\mathcal{E}$ at $x^0 \rightarrow \pm\infty$.

Consider the time evolution of the solution, eq. (1.3) (or (2.6)) only admits even solutions and therefore the asymptotical states at $x^0 \rightarrow \pm\infty$ must coincide. The motion is shown in figure 3. At $x^0 = -\infty$ the tachyon stays on the maximum A of the potential $V[t]$ (unstable vacuum). Since it has no kinetic energy, its energy density - that will be conserved during all its time evolution - is just $V[0] = \alpha$. The pressure is negative ($p = -\alpha$), forcing the tachyon to roll towards the minimum. As time evolves, the tachyon rolls and at $x_M^0 = -0.144576$ reaches the minimum M of the potential taking the value $t(x_M^0) = 1/\lambda_c$. Here the kinetic energy is maximal. Since \mathcal{E} is conserved and the system is *classical*, the tachyon cannot stop its motion and proceeds to an inversion point. This happens at $x^0 = 0$, that corresponds to B in figure 3. Note that the value of the potential at the inversion point B is lower than the value taken in A , still the energy being conserved. This is because the interaction felt by the tachyon is not described by $V[t]$, as the cubic term in the interaction is “dressed” by the kinematical factor $\lambda_c^{-\partial_0^2/3}$ (see (1.1)). This

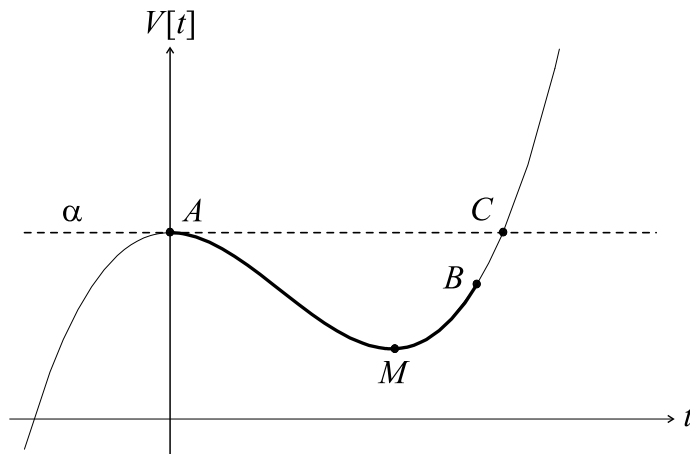


Figure 3: The tachyon potential $V[t]$. The bold part of $V[t]$ refers to the motion $A \rightarrow M \rightarrow B \rightarrow M \rightarrow A$ of the classical solution $t(x^0)$.

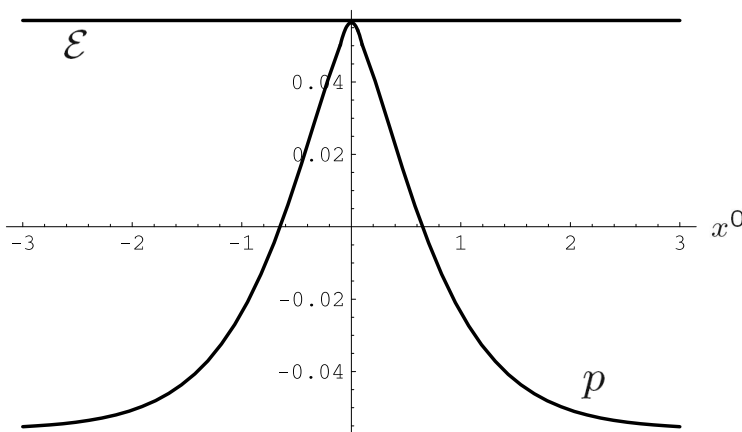


Figure 4: Energy density and pressure. The value of $\alpha = 0.056$ is the minimum required to guarantee the DEC for any value of x^0 .

“dressing” is most significant when the acceleration is maximal, that is precisely at the inversion point B . This is the reason why the tachyon does not reach the point C in figure 3. For $x^0 > 0$ the tachyon inverts its motion, passing again through the minimum and asymptotically reaching the unstable maximum A at $x^0 \rightarrow +\infty$, where again $p \sim -\mathcal{E} = -\alpha$. As already mentioned, different choices of $\alpha = \mathcal{E}$ simply raise or lower the profile of the pressure, that maintains the shape of a bounce. However, different values of α can describe different physical scenarios. Among all the possible choices, at least three deserve consideration.

We can fix α in such a way the Dominant Energy Condition (DEC) $\mathcal{E} \geq |p(x^0)|$ holds for any value of x^0 . This can be realized by choosing $\alpha \geq 0.056$. In the limiting case $\alpha = 0.056$ the energy density is tangent to the pressure at the origin $x^0 = 0$. At this time the equation of state $\mathcal{E} \sim |p(x^0)|$ describes *stiff* matter. This is the case displayed in figure 4.

Other interesting choices can be obtained by fixing the physical properties of the matter distribution at the minimum M of the potential. One could require that the tachyon describes *dust* when reaches M . Thus, by imposing $p(x_M^0) = 0$, one gets $\alpha = 0.103$. With this choice the DEC obviously holds and the tachyon matter has the interesting equation of state $p(x^0) = w\mathcal{E}$, with w that smoothly interpolates between -1 and 0 while the tachyon moves from the maximum to the minimum of its potential. Precisely as in the tachyon matter considered by Sen. The motion however continues passed the minimum of the potential and the pressure becomes positive. This form of tachyon matter is thus different to the one described in [18, 8, 19].

Another interesting scenario is realized by requiring that the DEC, $\mathcal{E} \geq |p(x^0)|$, holds in $x^0 \in (-\infty, -x_M^0)$, i.e. during the rolling $A \rightarrow M$ from the unstable maximum to the stable minimum of the potential. This is obtained by requiring that $\mathcal{E} = |p(x_M^0)|$, which gives $\alpha = 0.051$. Remarkably, the choice $\alpha = 0.051$ reproduces the brane tension (that in these units is $1/(2\pi^2)$) within the 99% of accuracy. This might be an indication that the solution we found might be the exact solution of the tachyon equation obtained by keeping into account also higher level fields. The equation we studied is certainly approximated, we wonder if the solution might be exact. In fact, since α just gives the height of the maximum of the potential, a natural choice for it would be the one that sets to zero the minimum of the potential. In this case, when coupled to gravity, the potential would not produce a cosmological constant term when the tachyon is at the minimum. At the $(0,0)$ level truncation we are considering, such a constant is $1/(6\lambda_c^2)$ (which is the 68% of the brane tension). When all the higher level fields are taken into account, the depth of the “effective” potential increases and the constant that sets to zero the minimum of the potential should reproduce the D -brane tension $1/(2\pi^2)$. Thus, the DEC request naturally selects the correct depth of the potential when all levels are included.

4. Conclusions

In this paper we have shown that Cubic String Field Theory (CSFT) at the lowest order in the level truncation scheme has a classical rolling tachyon solution. This form of tachyon matter could have cosmological consequences. Having proven its existence directly from cubic string field theory, at least at this level of approximation, seems to provide a solid theoretical basis to tachyon driven cosmology.

Some interesting questions are raised by the CSFT rolling tachyon solution.

- What will happen to the rolling solution if we include higher level fields and higher powers of the tachyon field effective action? This problem should certainly be studied since the level $(0,0)$ is quite a crude approximation that does not keep into account interactions of the tachyon with higher string modes. At least at the classical level this analysis is doable and interesting. The profile we found is an extremely good approximation of the level $(0,0)$ equations of motion, and one wonders if the inclusion of higher level fields might just lead to an improvement of this approximation. The equation we studied is certainly approximated, we wonder if the solution might be exact. Would the diffusion equation (2.13) still hold?

- It would be interesting to consider the coupling of the decaying D-brane, described by the rolling solution, to closed strings and study the emission of closed string from it. It would in particular be interesting to see if this would cause damped oscillations around the minimum or it might lead to a friction term that would just stop the rolling tachyon at the stable minimum of the potential.
- In order to provide a possible cosmological model it would be inconsistent not to take into account effects of gravity during the decaying process. The coupling of the cubic string field theory action to a Friedman-Robertson-Walker type metric is a formidable task because of the D’Alambertian operators in curved space that would appear in the action. If one could still assume the validity of the diffusion equation (2.13), this task could be, however, extremely simplified. This might provide an alternative to the Born-Infeld type effective action that has been so extensively used in the study of tachyon driven cosmology [3, 23, 25, 4, 26]. Cubic string field theory certainly provides a tachyon effective action that correctly describes tachyon physics [27, 28] and it is derived from first principles. In any case it should be at least possible to study the gravitational effects generated by the energy-momentum tensor of the rolling tachyon solution we have computed here, and see what kind of equations for the scale factor this will produce.
- The relationship between the rolling solution found here and the known solution in Boundary String Field Theory (BSFT) and vacuum string field theory [29, 30] is worth investigating [31]. The former is also related to the boundary conformal field theory approach, so that if a link could be established between the CSFT solution and the BSFT one, it should be possible to determine also the boundary state associated to the solution found here. This should shed some more light on the relations between the two approaches to string field theory [22]. It would be interesting to investigate also here the spatial inhomogeneous decay [6, 32].
- The solution found here does not contain free parameters, thus it should be compared with the half-S-brane case [6, 14] where the only parameter present can be set to 1 by a time translation. The full S-brane case [2, 33–35] contains instead a parameter whose sign provides a prescription for which side of the tachyon potential maximum the tachyon would roll. The CSFT solution we found does not present this possibility, the tachyon always rolls to the “right side”, i.e. to the side where the tachyon potential is bounded below.

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