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Lateral-torsional buckling resistance prediction model for steel cellular beams generated by Artificial Neural Networks

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Abstract

The present paper aims to develop an Artificial Neural Network (ANN) formula to predict the LTB resistance of steel cellular beams. A finite element model is developed and validated through experimental tests. A parametric study is then conducted. 768 models are employed to train the ANN. The results are compared with the analytical models, as well as the equation predicted by ANN. The ANN model with seven neurons can accurately predict the LTB resistance of cellular beams as well the LTB combined with web-post buckling or web distortional buckling modes. Hence, the ANN-based formula can be adopted as design tool.

Keywords: Artificial neural network; Machine learning; Steel cellular beams; Lateral-torsional buckling; Finite element method.

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32 **Notation**

33 The following symbols are used in this paper:

A_f	the flange area;	l_e	the effective length ($k_1 k_2 L$);
A_w	the web area;	L	the length;
b_f	the flange width;	M_A, M_B, M_C	the moments located at $L_b/4$, $L_b/2$ and $3L_b/4$, respectively;
b_w	the web post width;	M_{pl}	the plastification moment;
b_{we}	the width end post;	p	the length between the opening diameter centers;
C_1 and C_2	the coefficients associated to the bending moment diagram and the load at cross-section position	t_f	the flange thickness;
C_b	the modifying factor for the non-uniform bending moment diagram;	t_w	the web thickness;
C_w	the warping constant;	z_g	the distance from the point of load application to the shear center;
D_o	the opening diameter	W_y	the plastic modulus about the strong axis;
d	the parent section height;	$W_{el,y}$	the elastic modulus about the strong axis;
d_g	the cellular beam height;	$W_{el,z}$	the elastic modulus about the weak axis;
E	the modulus of elasticity;	α_{LT}	the imperfection factor;
G	the shear modulus;	α_m	the bending moment diagram modifying factor;
I_z	the moment of inertia about the weak axis;	α_s	the slenderness reduction factor;
J	the torsional constant;	χ_{LT}	the reduction factor;
k_t	the torsional restraint factor;	λ_{LT}	the non-dimensional slenderness, considering LTB resistance;
k_l	the factor that considers the position of the load;	λ_z	the non-dimensional slenderness about weak axis, considering normal resistance;
k_r	the factor that leads to the restriction of rotation		

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39 **1. INTRODUCTION**

40 Steel cellular beams are those with periodical circular web openings. Such beams are manufactured from a parent section
 41 in three stages: two thermal cutting lines, separating of the tee sections and welding. The final result is a cross-section with greater
 42 bending stiffness than the parent section. Advantages in the use of steel cellular beams in structural design can be highlighted, such
 43 as the reduction of the structural system's own weight, the presence of openings favoring the air flow, as well as the passage of ducts

44 for the integration of services which results to the reduction of the structural depth per floor, thus the reduction of the floor to ceiling
45 height.

46 Authors, such as Ellobody [1], El-Sawy et al. [2] and Ferreira et al. [3], observed that the cellular steel beams are more
47 susceptible to global and local buckling modes, such as the lateral-torsional (LTB), lateral-distortional (LDB) and the web-post
48 (WPB), or even the combination of these failure modes. The LTB occurs in steel cellular beams, which are subject to bending about
49 the strong axis, due to the lack of lateral restraint. The main parameter that favors this type of buckling is the ratio between the
50 unrestrained length of the beam and the radius of gyration about the weak axis (L_b/r). According to studies carried out by Bradford
51 [4–7] the LDB is a phenomenon that takes place for slender web sections, a factor that reduces the torsional stiffness. The hypothesis
52 that the plane section remains plane after deformation, in this case, is not valid. References, such as Kerdal and Nethercot [8],
53 Tsavdaridis and D’Mello [9], Erdal and Saka [10], Panedpojaman et al. [11] and Grilo et al. [12], verified that the WPB, which is
54 characterized by lateral displacement combined with torsion, occurs for steel cellular beams with reduced web-post width and web
55 thickness. Several projects investigated the LTB resistance of cellular steel beams in compared to analytical models, such as EC3
56 [13], AS 4100-1998 [14], Panedpojaman et al. [15] and Taras and Greiner [16] with Sonck [17].

57 In the recent years, researchers have utilized artificial intelligence methods such as fuzzy logic, genetic algorithm and
58 artificial neural network (ANN) to solve complex engineering problems. Each method has its advantages; however, it has been
59 stated that ANN is able to provide more accurate predictions [18,19]. ANN is an effective tool that can be used to define nonlinear
60 relations between the inputs and the corresponding outputs and consists of 3 layers. The input layer and output layer are
61 interconnected through the hidden layer, which consists of neurons that are dependent on the set up of the model and each neuron
62 develops a weighted connection between the input and output parameter to define relationships. ANN has been successfully
63 employed to accurately obtain the plastic buckling resistance of steel structures.

64 More recently, Limbachiya and Shamass [20] predicted the web-post bucking resistance of cellular beams employing ANN.
65 A variation in input parameters and the number of neurons in the hidden layer was reviewed to develop the most accurate model.
66 The experimental and finite element results were used to train the ANN models. It was concluded that ANN provides results that
67 are more in line with test results than those predicted from SCI P355 [21]. Nguyen et al. [22] used ANN to predict the load-bearing
68 capacity of castellated steel beams CSB and they concluded that ANN model with 1 hidden layer and 1 neuron was sufficient to
69 predict the load-carrying capacity of CSB with excellent accuracy in comparison with the experimental results. Hosseinpour et al.
70 [23] developed reliable ANN model that predicted the ultimate moment capacity of castellated beams subjected to lateral-distortional
71 buckling mode. Sharifi et al. [24] tested different ANN training algorithms, and several neurons in the hidden layer to predict the
72 LTB of simply supported cellular steel beams subjected to four-point bending. The authors found that Levenberg–Marquardt training
73 algorithm provided the best performance. Abambres et al. [25] proposed an ANN-based formula that precisely predicted the elastic
74 buckling resistance of simply supported cellular beams subjected to uniformly distributed load. They found that ANN accurately
75 predicted the capacity with maximum and average relative errors of 3.7% and 0.4%, respectively. Sharifi et al. [26] used 99 finite

76 element models to train an ANN model that predict the LTB of cellular beam. In this context, the cellular steel beams were
77 considered to be simply supported and subjected to four-point bending. The predictions of the LTB resistance of steel cellular beams
78 were compared with the AS 4100-1998 [14]. The results showed that the ANN-based equation proposed by the authors was able to
79 estimate the behavior of cellular steel beams subjected to LTB. Tohidi and Sharifi [27] employed ANN to predict the inelastic
80 lateral-torsional buckling capacity of corroded web opening steel beams. The input and output parameters were defined based on
81 the numerical results from the validated FEM and the data was used for training, validation and testing was 60%, 20% and 20%
82 respectively. The study concluded that even with a small amount of data, ANN was able to predict the target values to an acceptable
83 level of accuracy and provided an assessment method that would provide a fast and reliable decision regarding the future of corrosion
84 damaged I-beam. Gholizadeh et al. [28] developed a back propagation neural network using data from 140 FE models to assess the
85 load carrying capacity of castellated steel beams. Geometric parameters of the beam were used as the input parameters, and when
86 altering the number of neurons within the hidden layer, it was stated that best results were obtained by employing 4 neurons. FE
87 models were also used to develop 140 models that could be used to predict the inelastic distortional buckling capacity assessment
88 of steel I-beams using ANN [29]. 10 models with 6 input parameters, 1 output parameter, 1-10 neurons in the hidden layer were all
89 trained using the Levenberg-Marquardt back propagation algorithm. In a comparison between current design rules (AISC/AISC
90 360-16 [30], AS 4100-1998 [14] and EC3 [13]), the proposed ANN equation and experimental results, it was concluded that the
91 proposed equation provided more reliable predictions in comparison to the codes. Overall, ANN has many advantages, not only
92 does it provide reliable and accurate results in comparison to the current codes, but it is also providing a simple method which is
93 easier and practical for engineers to use and apply when compared to FE modeling. The data is also crucial, as the statistical accuracy
94 of the model will improve with a greater database and a variability in the input parameters.

95 As shown so far, there is no application of ANN in post-buckling analysis of steel cellular beams, considering the variation
96 of the type of loading (neutral and destabilizing effect), as well as the combination of LTB with other buckling modes, such as
97 LTB+WPB and LTB+WDB. This paper aims to apply an ANN to predict the LTB resistance of steel cellular beams under combined
98 buckling modes. For this task, a finite element model based on experimental results was developed. A parametric study is carried
99 out considering three steel profiles for the parent section. Geometric parameters such as unrestrained length (L_b), ratio of web-post
100 width to opening diameter (p/D_o), ratio of opening diameter to parent section height (D_o/d), and expansion factor (d_g/d) were varied.
101 Cellular steel beams are usually designed as and herein considered as simply supported and subjected to neutral and destabilizing
102 effects of loading. Three loading conditions were also considered, pure bending, mid-span concentrated load, and uniformly
103 distributed load. From the results, 768 models that had the failure mode governed by LTB, LTB+WDB and LTB+WPB were selected
104 for the development of the ANN model. For the ANN model, the input parameters were defined based on the geometric parameters
105 of the cellular beams, the hidden layer reviewed several neurons within it to define the most accurate and efficient model that could
106 be easily used in real practice while the output parameter was the LTB moment resistance. Finally, the resistance prediction model

developed by ANN is compared with finite element models and analytical procedures to assess the accuracy and define the impact of input parameters on the output.

2. BACKGROUND

In this section, the studies, that were developed to investigate the LTB of steel cellular beams, will be presented. In this context, few experimental studies [17,31–33] and many numerical studies based on the finite element method [1,2,35–41,3,15,24,26,31–34] were published.

Regarding experimental studies, Nseir et al. [33] and Boissonnade et al. [32] presented two tests to evaluate the LTB resistance. The cellular beams were simply supported and subjected to four-point bending. The cellular sections were fabricated from HEA340 and IPE330 parent sections, and with total length of 7.5m, and 11m, respectively. Both specimens governed by the LTB, and their peak load was 1977kN and 176.9kN, for HEA340 and IPE330, respectively. Sonck [17] and Sonck and Belis [31] conducted three tests, also considering four-point bending. Three lengths were considered, that of 3.15m, 3.99m and 6.09m. All specimens governed by the LTB, and the maximum peak load was 23.6kN.

Regarding finite element studies, Sweedan [34] performed elastic analyses to investigate the moment-gradient factor, which is a coefficient that takes into account the non-uniform distribution of bending moment along the beam unrestrained length [42]. After evaluating three types of loads on the elastic analyses, a new coefficient that takes into account the bending moment distribution in the unrestrained length was proposed, as well as the geometric parameters of the steel cellular beam. The LTB phenomenon in elastic regime is written according to **Eq. (1)** [43]:

$$M_{cr,0} = \frac{\pi}{L} \sqrt{EI_z GJ + \left(\frac{\pi}{L}\right)^2 EI_z EC_w} \quad (1)$$

Later, El-Sawy et al. [2] presented the inelastic analyses. In this study, the numerical model responses were evaluated as a function of a coefficient, the dimensionless lateral-torsional stiffness, and the LTB combined with WDB and WPB. According to the results, LTB was obtained for $k_e < 0.5$, since the smaller the value of k_e , the greater will be the ratio between the radius of gyration about the weak axis and the unrestrained length. Sonck et al. [35] performed a parametric study to investigate the effects of plastic behavior on steel cellular beams employing finite element method. It was concluded that for short steel cellular beams, the failure mode was governed by the plastic behavior, that was, no buckling phenomenon was observed such as LTB. In Ellobody [1] a parametric analysis were developed to study the behavior of steel cellular beams, considering the combination of buckling modes. In this study, the numerical models results were compared with the AS 4100-1998 [14] specification (**Eqs. 2-5**) and it concluded that such specification underestimated the LTB-resistance of steel cellular beams.

$$M_{Rk} = \alpha_m \alpha_s M_{pl} \leq M_{pl} \quad (2)$$

$$\alpha_m = \frac{\sqrt{3}M_{\max}}{\sqrt{[(M_A)^2 + (M_B)^2 + (M_C)^2]}} \leq 2.5 \quad (3)$$

$$\alpha_s = 0.6 \left\{ \sqrt{\left[\left(\frac{M_{pl}}{M_o} \right)^2 + 3 \right]} - \left(\frac{M_{pl}}{M_o} \right) \right\} \quad (4)$$

$$M_o = \sqrt{\left\{ \left[\left(\frac{\pi^2 EI_y}{l_e^2} \right) \right] \left[GJ + \left(\frac{\pi^2 EC_w}{l_e^2} \right) \right] \right\}} \quad (5)$$

134 Boissonnade et al. [32] carried out a parametric study to investigate the design recommendations to LTB provided by
 135 ArcelorMittal ACB+ [44]. Such procedure underestimates the resistance of steel cellular beams under LTB, since it only considers
 136 the stiffness of the upper tee. In this context, the authors recommended the EC3 [45] procedure (Eqs. 6-10), using the buckling
 137 curve c to calculate the LTB resistance.

$$M_{Rd} = \frac{\chi_{LT} W_y f_y}{\gamma_{M1}} \quad (6)$$

$$\chi_{LT} = \frac{1}{\phi_{LT} + \sqrt{\phi_{LT}^2 - \lambda_{LT}^2}} \leq 1.0 \quad (7)$$

$$\phi_{LT} = 0.5 \left[1 + \alpha_{LT} (\lambda_{LT} - 0.2) + \lambda_{LT}^2 \right] \quad (8)$$

$$\lambda_{LT} = \sqrt{\frac{W_y f_y}{M_{cr}}} \quad (9)$$

$$M_{cr} = C_b M_{cr,0} \quad (10)$$

138 In Sonck and Belis [31], the effect of residual stresses on LTB resistance was investigated. The authors observed that
 139 calculation recommendations that do not consider such effect on the structural behavior of steel cellular beam under LTB may be
 140 unsafe. In this scenario, Sonck [17] based on EC3 [45] proposed a new imperfection factor for the calculation of resistance to LTB.
 141 The use of $\alpha_{LT}=0.6$ was proposed based on EC3 [45], and according to the formulations of Taras and Greiner [16], two coefficients
 142 were proposed, considering the relations $d_g/b_f > 1.2$ (Eq. 11) and $d_g/b_f \leq$ (Eq. 12).

$$\alpha_{LT} = 0.18 \sqrt{\frac{W_{el,y}}{W_{el,y}}} \leq 0.64 \quad (11)$$

$$\alpha_{LT} = 0.25 \sqrt{\frac{W_{el,y}}{W_{el,y}}} \leq 0.64 \quad (12)$$

In Panedpojaman et al. [15] inelastic analyses were developed to investigate the LTB resistance of steel cellular beams. The authors highlighted the influence of shear stresses for short spans, models for which the resistance can be characterized as WPB or some plastic mechanism. In this context, the authors proposed a correction coefficient to calculate the LTB resistance, according to the methodology described in EC3 [45], using the buckling curve *b*. Eqs. (8-9) present the calculations of the coefficients, considering the absence and presence of shear loads, respectively.

$$M_{Rd} = k_{LB} \frac{\chi_{LT} W_y f_y}{\gamma_{M1}} \quad (13)$$

$$k_{LB} = \frac{1}{-0.01\lambda_{LT} + 1.05} \quad (14)$$

$$k_{LB} = \frac{\min \left[\left(0.16 \frac{A_f}{A_w} + 0.66 \right), (1.0) \right]}{\max \left[(-0.1\lambda_{LT} + 1.13), (0.9) \right]} \quad (15)$$

Ferreira et al. [3] developed a parametric study to investigate the LTB resistance, considering the effect of loading applied at the upper flange (destabilizing effect) as well as at the shear centre (neutral effect). The results of this study were compared with calculation models existing in the literature [14–16,31,45]. The work highlighted that the combination of the Taras and Greiner [16] model with the Sonck factor [17] is a good approximation for the LTB resistance of steel cellular beams. The equations combined between Taras and Greiner [16] with the Sonck factor [17], considering loads applied at shear centre are described below (Eqs. 16-18). For loads applied at the upper flange, the equation of the three factors (C_1 , C_2 and C_3) is used to calculate the critical moment [46] (Eq. 19).

$$\phi_{LT} = 0.5 \left[1 + \left(\frac{\lambda_{LT}^2}{\lambda_z^2} \right) \alpha_{LT} (\lambda_z - 0.2) + \lambda_{LT}^2 \right] \quad (16)$$

$$\lambda_{LT} = \sqrt{\frac{W_y f_y}{M_{cr}}} \quad (17)$$

$$\lambda_z = \sqrt{\frac{A f_y}{N_{cr}}} \quad (18)$$

$$M_{cr} = C_1 \frac{\pi^2 E I_z}{L^2} \left[\sqrt{\frac{C_w}{I_z} + \frac{L^2 G J}{\pi^2 E I_z} + (C_2 z_g)^2} - C_2 z_g \right] \quad (19)$$

Later, Ferreira et al. [37] investigated the Load and Resistance Factor Design (LRFD), which is based on the ANSI/AISC 360-16 [30] design procedure, for steel cellular beams under LTB. The authors observed that for intermediate spans, the American standard overestimates the LTB resistance, since the LRFD value is equal to 0.9. In this context, the average LRFD value calculated

by the authors was 0.83. Komal et al. [36] presented an extensive parametric study of steel cellular beams in which buckling and post-buckling analyses were performed. The authors showed that the unrestrained length is an important parameter, since the lateral displacement is directly influenced by the compressed flange, thus causing LTB. Khatri et al. [39] investigated the effect of the load position on the cross-section by carrying out elastic analyses, considering the effect of stabilizing, neutral and destabilizing on the moment-gradient factor. In this study, the authors observed the moment-gradient factor variation as a function of the buckling modes that were governed by the combination of LTB+WDB and for short spans. Bhat and Gupta [40] carried out a parametric study, considering simply supported cellular beams subjected to four-point bending. The results of this study were compared with the recommendation of the Indian standard IS 800:2007 [47], that is applied to common steel beams. The authors showed that the Indian standard was conservative for cellular steel beams with a yield strength of 250 MPa. However, for cellular steel beams with yield strengths of 350MPa and 450MPa, this comparison was unconservative. Recently, Faria et al. [41] investigated the LTB resistance in fire situations by performing finite element analyses. The authors presented a procedure to predict the LTB resistance of cellular steel beams, considering fire and room ambient temperature (Eq. 20) situations. Such calculation methodology is a modification of the equations presented in EC3 [45].

$$\phi_{LT} = 0.5 \left[1 + 0.25 (\lambda_{LT} - 0.2) + \lambda_{LT}^{1.9} \right] \quad (20)$$

As presented so far, few researchers have conducted experimental studies, whereas most of them presented numerical studies and sought alternatives to calculate the LTB resistance of steel cellular beams. In this case, revisions were made to LTB-resistance calculations for steel beams without web openings. It is important to highlight that the procedures for calculating the LTB resistance of steel profiles without web openings are very well consolidated. As an example, studies that made EC3 [45] revisions were highlighted, in order to accurately present the numerical response with the calculation procedures. Finally, although many alternatives were presented to calculate the LTB resistance of steel cellular beams, it is a complex procedure, since these perforated beams can fail due to the interaction of buckling modes. Consequently, the present study employs the power of artificial neural network algorithms, seeking the calculation of LTB resistance while considering the interaction between the buckling modes.

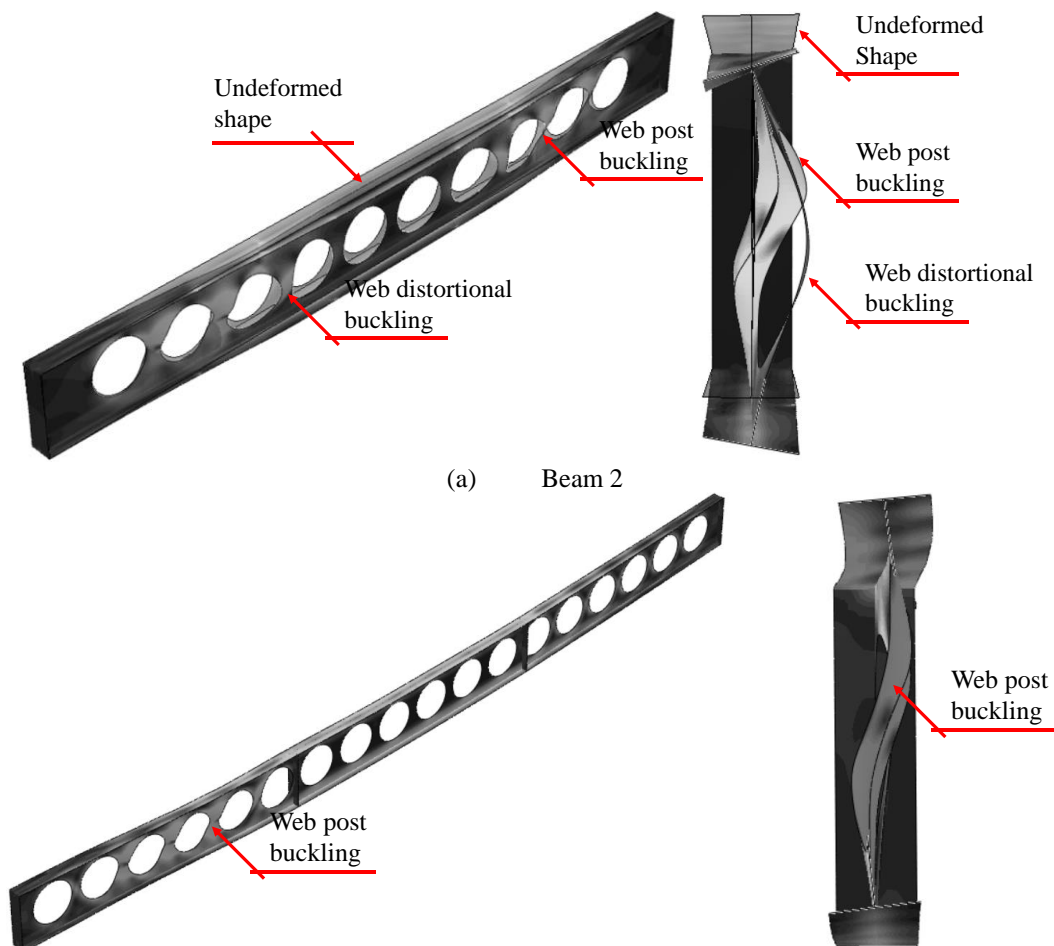
3. FINITE ELEMENT MODEL: VALIDATION AND PARAMETRIC STUDIES

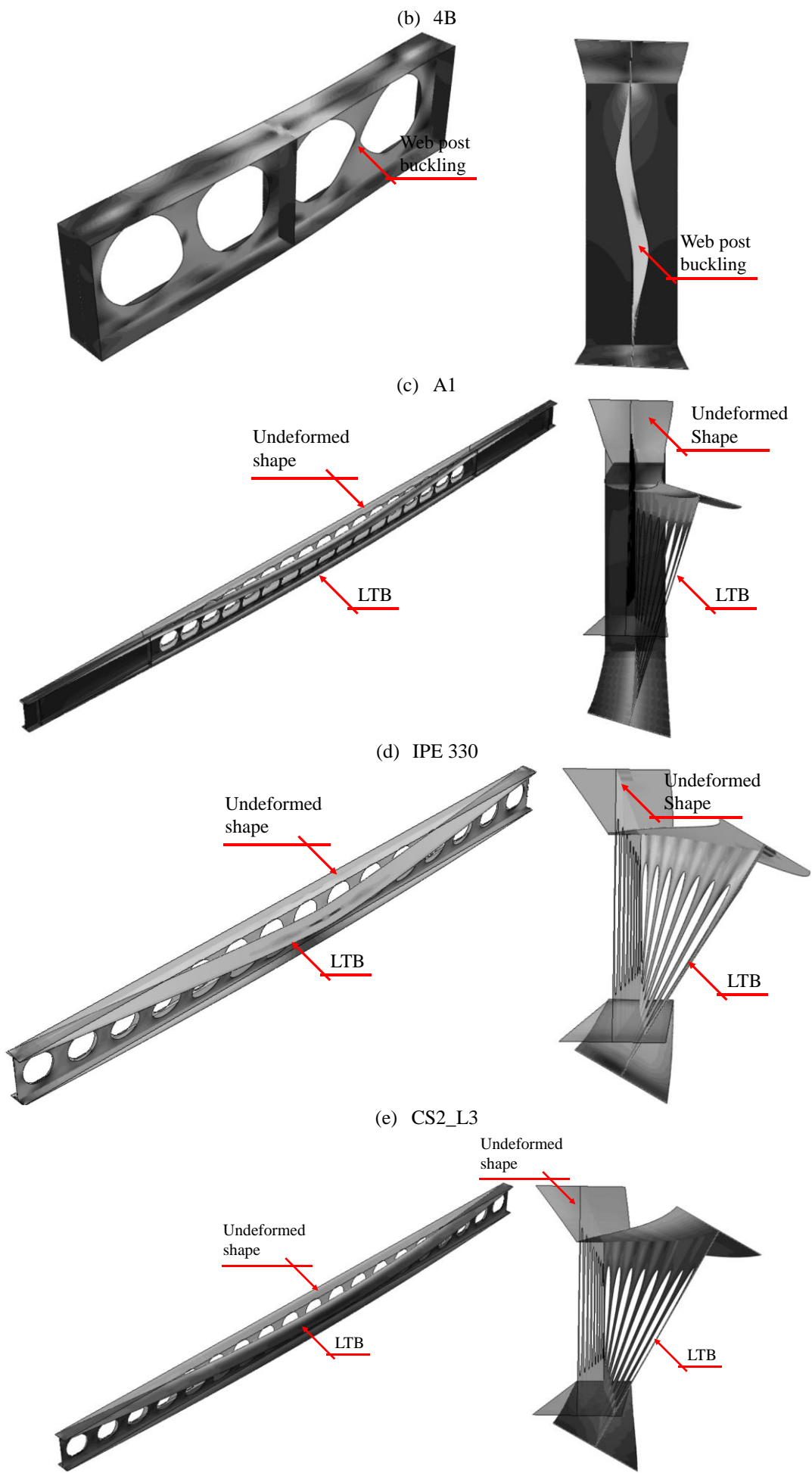
In this section, the validation results will be briefly presented, as well as the geometric parameters that were considered in the parametric study. This is because the paper focuses on the artificial neural network.

For the validation study, eight experimental models of steel cellular beams [9,31,32,48,49] were considered. All steel cellular beams are simply supported. Elastic-perfectly plastic material behavior was considered in the numerical models, and the cellular beams were modeled with 10mm S4R shell elements, according to the ABAQUS® software library [50]. The models were processed in two stages: buckling and post-buckling analyses. Many researchers have used this procedure to analyze buckling problems in steel cellular beams [36,51]. The buckling analysis predict the critical buckling load and its respective buckling mode.

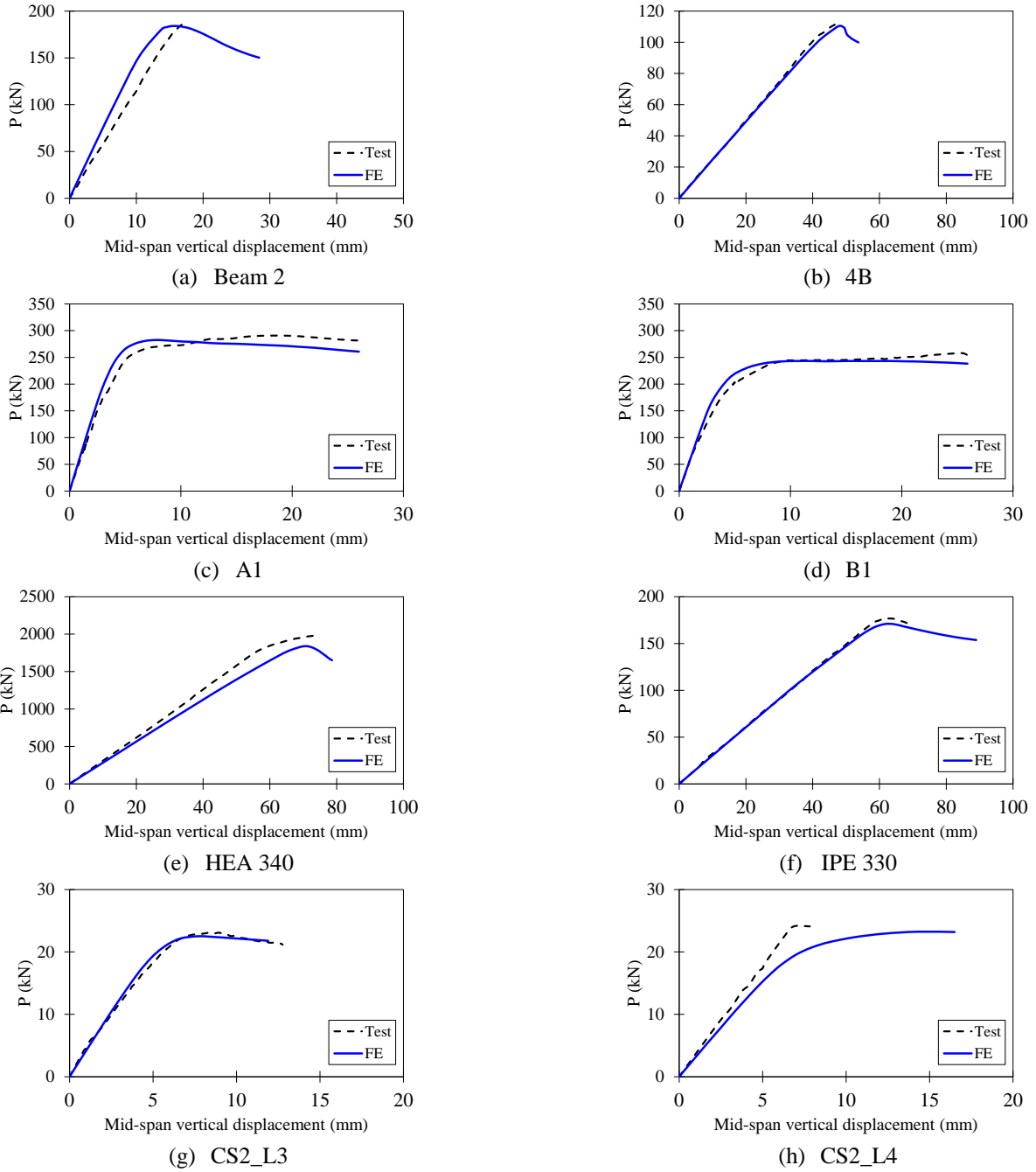
It is noteworthy that no initial imperfections are considered here. Subsequently, the buckling mode response from the analysis performed in the first stage is used as an initial geometric imperfection for the subsequent post-buckling analysis ($d_g/100$ if $L/d_g < 10$ and $L/1000$ if $L/d_g \geq 10$) [3]. Residual stresses were considered [52]. The imperfections are inserted with the commands *IMPERFECTION and *INITIAL CONDITIONS, TYPE=STRESS for initial geometric imperfection and residual stresses, respectively. The post-buckling analysis is performed by *Static Riks*, which uses the arc length method.

Regarding the validation results, the numerical results obtained showed the same failure mode as the experimental models. In **Fig. 1**, key examples of the failure modes are presented. Beam 2 test also performed by Surtees and Liu [48] failed by WDB+WPB. These modes were verified in the final configuration of the numerical model, as shown in **Fig. 1a**. 4B test, which was carried out by Warren [49], governed by WPB. This mode was observed in the finite element model presented in **Fig. 1b**. Tests A1 and B1, which were conducted by Tsavdaridis and D’Mello [9], failed by WPB. **Fig. 1c**, in the same way, depict the failure modes of the developed finite element models. Boissonnade et al. [32] and Sonck and Belis [31] performed LTB tests; **Fig. 1d**, **Fig. 1e** and **Fig. 1f** depict the final mode shape of these finite element models for IPE 330, CS2_L3 and CS2_L4, respectively. It is concluded that the finite element models developed for the validation study were in agreement with the failure modes of the tests. Also, the force against mid-span vertical displacement relationships were made to compare with the tests (**Fig 2**), and the results are summarized in **Table 1**.





(f) CS2_L4

Fig. 1: Final configuration of finite element models**Fig. 2: Finite element models vs. experimental results****Table 1: Validation results**

Test	Reference	Test		Finite element model		$1 - P_{Test}/P_{FE}$ (%)
		P_{Test} (kN)	Failure mode	P_{FE} (kN)	Failure mode	
Beam 2	Surtees and Liu [48]	188.5	WDB+WPB	184.0	WDB+WPB	-2.4
4B	Warren [49]	114.0	WPB	110.5	WPB	-3.2
A1	Tsavdaridis and D'Mello [9]	288.7	WPB	282.5	WPB	-2.2
B1	Tsavdaridis and D'Mello [9]	255.0	WPB	243.1	WPB	-4.9
HEA 340	Boissonnade et al. [32]	1,977.0	LTB	1,838.4	LTB	-7.5
IPE 330	Boissonnade et al. [32]	176.9	LTB	170.7	LTB	-3.6
CS2_L3	Sonck and Belis [31]	22.3	LTB	22.5	LTB	0.9
CS2_L4	Sonck and Belis [31]	23.6	LTB	23.2	LTB	-1.7

In the parametric study, the ASTM A572 Grade 50 steel is considered. **Fig. 3** presents the geometrical parameters that were varied (**Table 2**). Cellular beams are considered as simply supported and subjected to three types of loadings applied to the shear centre (i.e., uniform bending, mid-span concentrated load and uniformly distributed loads) considering the neutral effect, and two types of loading applied to the upper flange (i.e., mid-span concentrated load and uniformly distributed loads) to simulate the destabilizing effect.

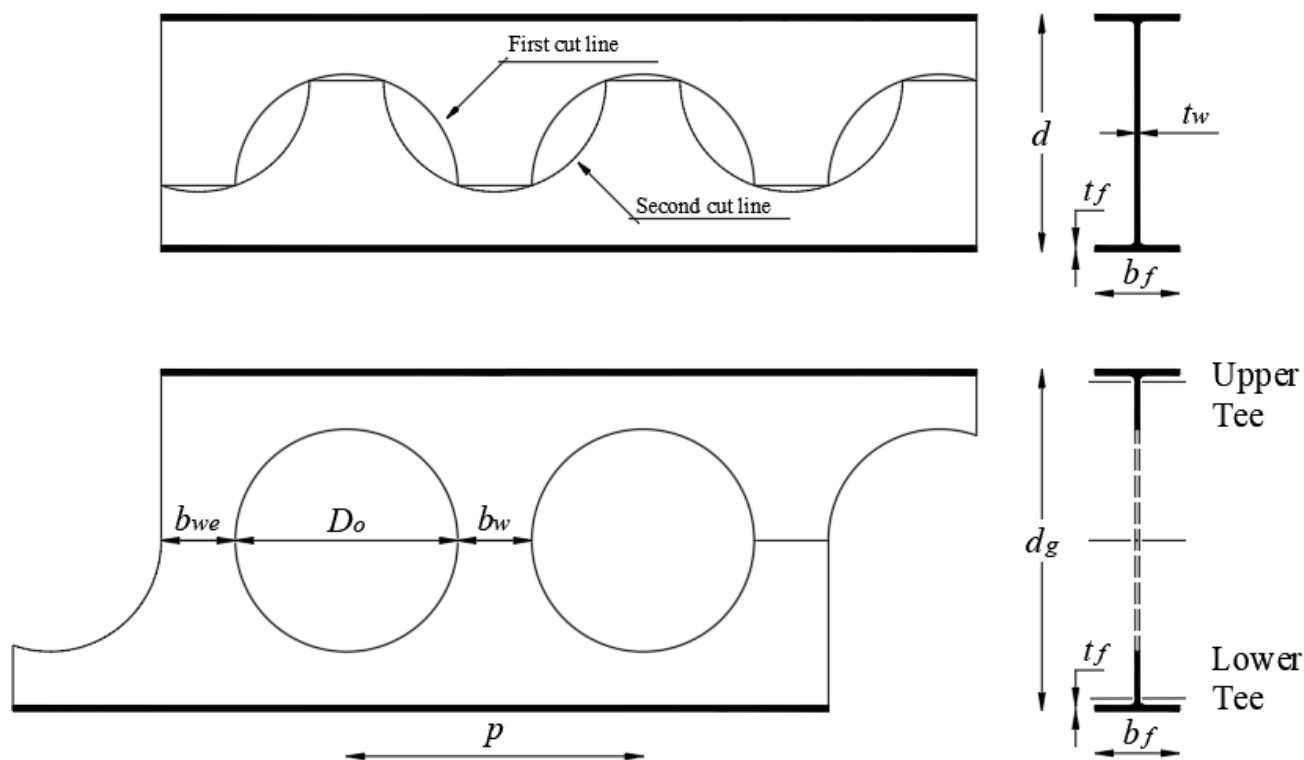
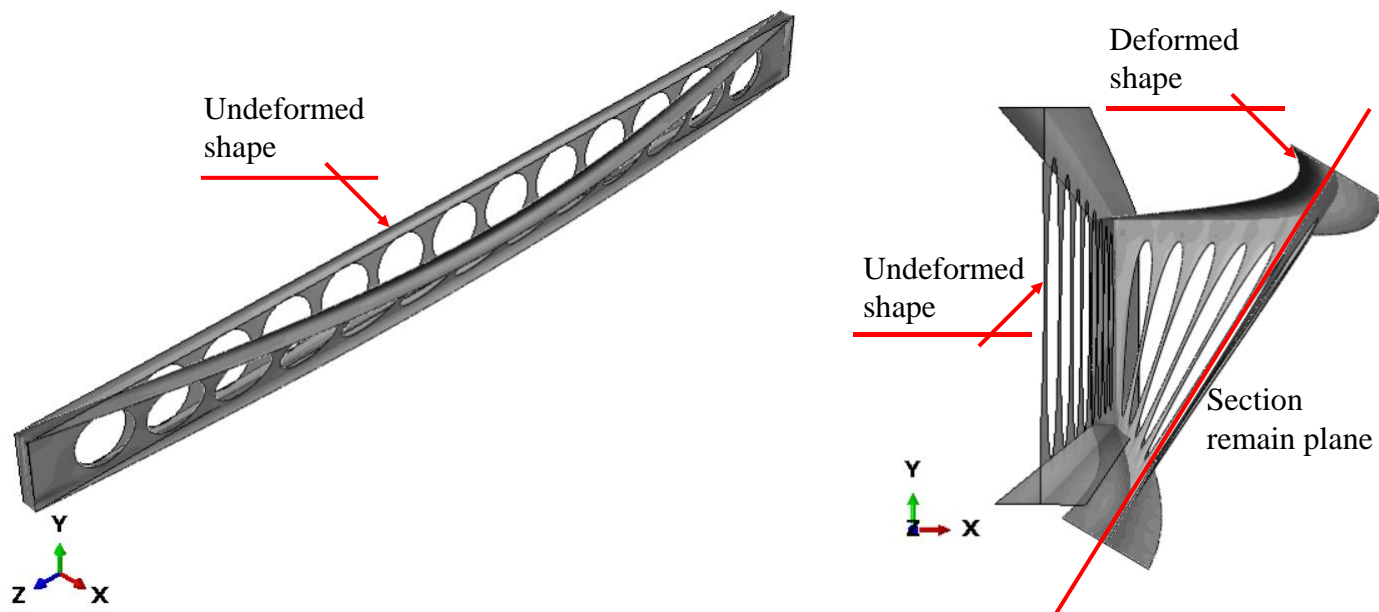


Fig. 3: Geometrical parameters, adapted from [53]

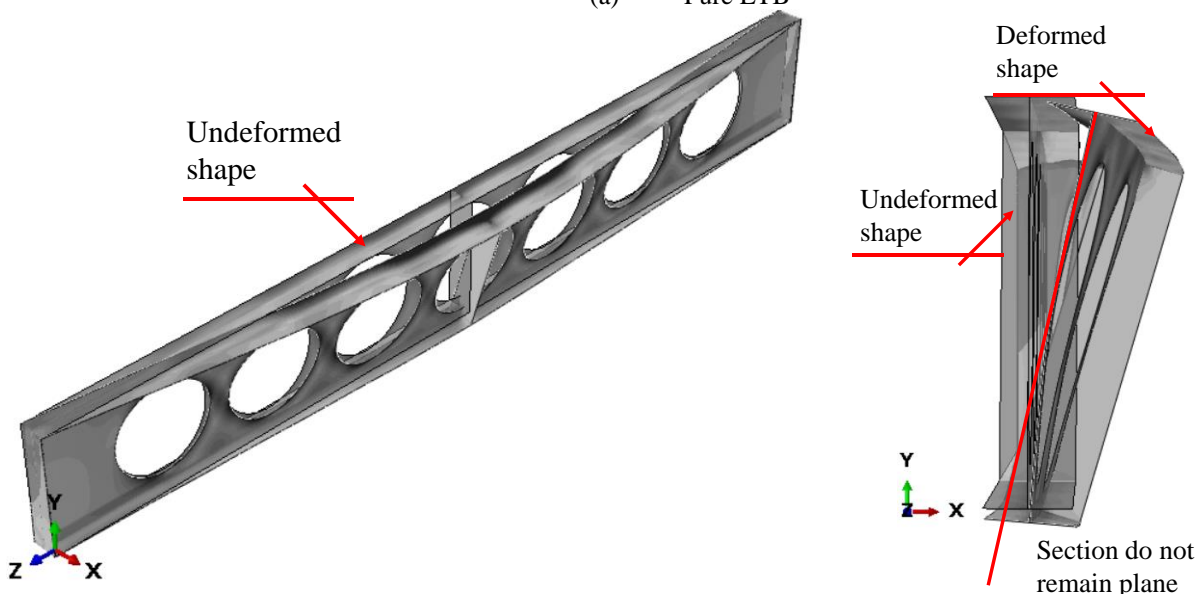
Table 2: Parameters

Parameter	Variation
p/D_o	1.2 and 1.45
D_o/d	0.95 and 1.15
d_g/d	1.3, 1.35, 1.4, 1.45 and 1.5
Steel sections	W200x22.5, W310x32.7 and W530x85
Loading type	Neutral effect: uniform bending, mid-span concentrated load and uniformly distributed loads Destabilizing effect: mid-span concentrated load and uniformly distributed loads

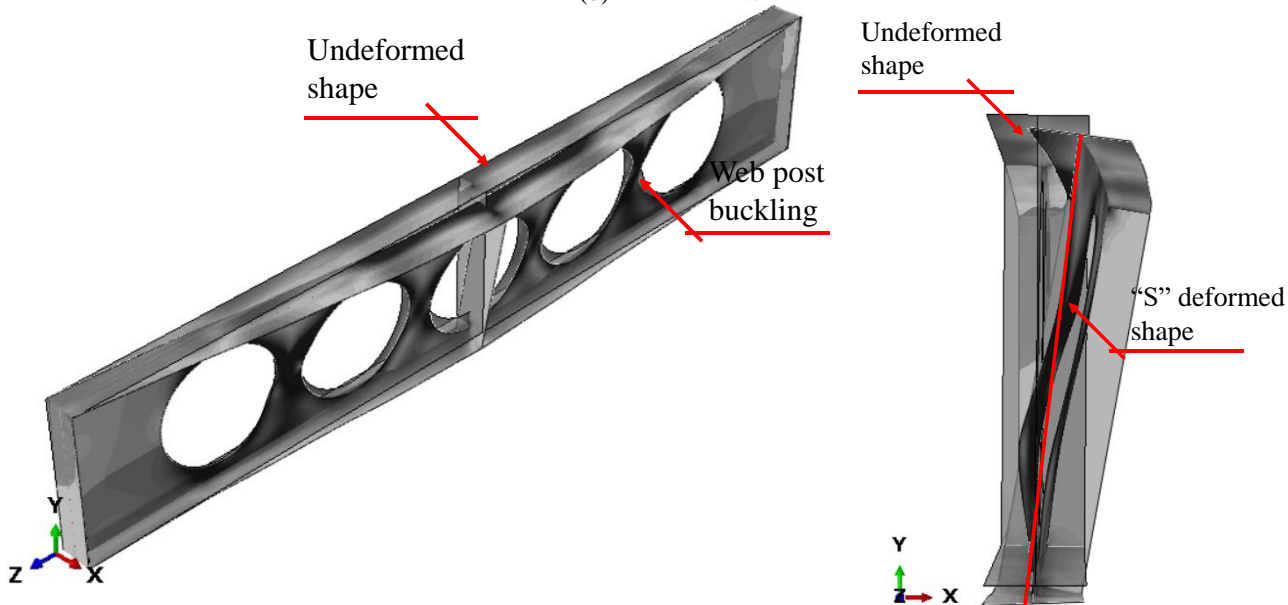
The parametric study in 768 models allowed to identify the failure mode governed either by LTB (**Fig. 4a**) or the combination of this failure mode with other buckling modes, such as LTB+WDB (**Fig. 4b**) and LTB+WPB (**Fig. 4c**). The results of the 768 models are used for the development of a robust ANN formula as described below.



(a) Pure LTB



(b) LTB+WDB



(c) LTB+WPB

Fig. 4: Failure modes

4. DEVELOPMENT OF THE ARTIFICIAL NEURAL NETWORK (ANN)

In this section, the development of the artificial neural network is presented.

4.1 NEURAL NETWORK ARCHITECTURE

The general architecture of an ANN includes the input layer, hidden layer, and output layer. The normalized input values are connected to the hidden layer, which consists of neurons that are dependent on the analysis that is conducted. The connection between each input and neuron in the hidden layer is weighted and also consists of constant bias value. The hidden layer is thereafter connected to the output layer. Again, each connection from the hidden layer to the output layer is weighted with a value, a transfer function and a constant bias value. As input values are normalized, the output value will also be normalized and will require denormalization to obtain predicted values that can be compared to the target values. To then assess the accuracy of the model, the errors between the predicted and target values are calculated.

The errors should be minimized by adjusting the weights and bias values of the ANN. This can be achieved by transferring the information (errors) from the output layer towards the input layer of the ANN [54]. This process is called Back-Propagation of Multilayer Feed Forward ANN. In addition, the final weights and bias values between the different layers can be used to quantify the impact of input parameters on the output parameter. The network architecture used in this paper is a Multi-Layer Perceptron Network (MLPN). The neural network toolbox within MATLAB [55] solves a data fitting problem with a two-layer feedforward neural network and is the method that has been adopted in this study.

To derive the ANN model, a number of parameters need to be introduced, herein noted as input parameters as well as the number of neurons within the hidden layer, the activation function, and the output parameter. The input parameters in this study represent the variable geometric characteristics of cellular beam, including the length (L), overall height of the beam (d_g), opening diameter (D_o), distance between opening (b_w), flange width (b_f), flange thickness (t_f), web thickness (t_w), distance from the point of the load application to the shear centre of the section (z_g), and the moment-gradient factor (C_b). In this study, the C_b is taken as presented in DD ENV 1993-1-1 (2002) [46]. For uniformly distributed loading, C_b is equal to 1.132. Considering mid-span concentrated load, C_b is equal to 1.365 while beams with uniform bending the value C_b is equal to 1.0. The output parameter to be predicted is the LTB moment resistance (M).

The number of neurons in the hidden layer has influence on the accuracy of the ANN model. The optimal number of neurons in the hidden layer can be defined by modelling several networks with a different number of the neurons and comparing the differences in the results. In this paper, the ANN network was modelled with 3, 5, 7, 9 and 11 neurons in the hidden layer. **Fig. 5** illustrates an example of an ANN structure consisting of 9 input parameters, 3 neurons in the hidden layer, and 1 output parameter.

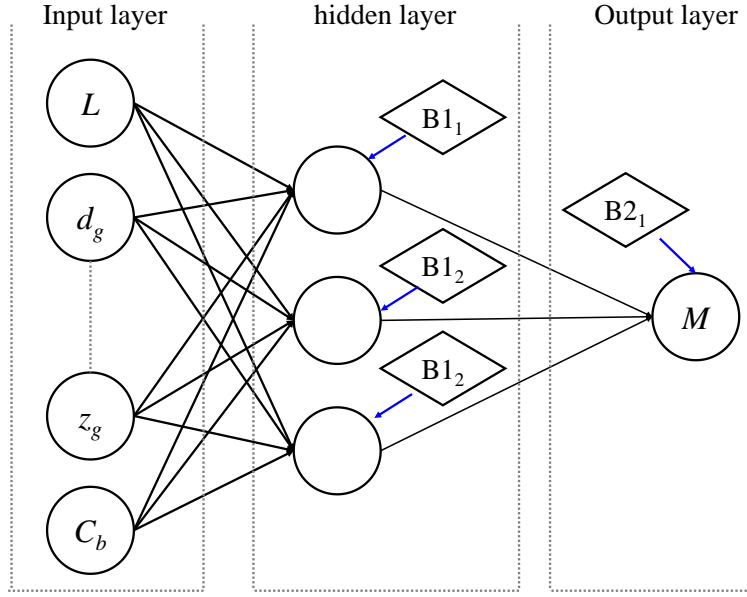


Fig. 5: ANN Model with 3 neurons in the hidden layer

4.2 INPUT AND OUTPUT NORMALIZATION

The progress of training can be reduced if training data define a region that is relatively narrow in some dimensions and elongated in others [25]. Therefore, normalization for variables across all data patterns should be implemented to improve the learning speed, performance, accuracy, and stability of the training process. Both input and target parameters can be normalized using **Eq. (21)** [56], where Y^{act} is the actual value of the input/output, X^{norm} is the value, X_{min} and X_{max} are the minimum and maximum values of the input/output parameters, respectively (**Table 3**). Y_{min} is the minimum value for each row of X (default is -1) and Y_{max} is the maximum value for each row of X (default is $+1$).

$$X^{norm} = \frac{(Y_{max} - Y_{min})(X^{act} - X_{min})}{(X_{max} - X_{min})} + Y_{min} \quad (21)$$

Table 3: Parameters used to normalize input and target values

Input/Target Parameter	X_{min}	X_{max}	Y_{min}	Y_{max}
L (mm)	1500	15000	-1	1
d_g (mm)	268	803	-1	1
D_o (mm)	196	616	-1	1
b_w (mm)	47.6	228.6	-1	1
b_f (mm)	102	166	-1	1
t_f (mm)	8	16.5	-1	1
t_w (mm)	6.2	10.3	-1	1
z_g (mm)	0	401.5	-1	1
C_b	1	1.365	-1	1
M (kN.m)	16.71	470.34	-1	1

4.3 LEARNING (TRAINING) ALGORITHM AND TRANSFER FUNCTION

The total number of data sets used in the ANN model was 768. To avoid overfitting the ANN model, the data points are randomly divided into training set, validation set and testing set, with 70%, 15% and 15% of the data, respectively. While the training set is used to compute the gradient and update the weights and biases, a process of cross validation takes place using the validation data set so the performance of the network can be generalized. When the optimum network parameters are defined, the test data set is used to assess the ANN accuracy. The Levenberg-Marquardt back propagation training algorithm is adopted in this study as this algorithm is fast, has stable convergence and is suitable for training small- and medium-sized problems. **Eqs. (22-23)** show the hyperbolic tangent transfer function that is required to determine the normalized output value based on the inputs provided [57].

$$O_s = B1_s + \sum_{k=1}^r \left(w_{k,l}^{ho} \frac{2}{1 + e^{-2H_k}} - 1 \right) \quad (22)$$

$$H_k = B2_k + \sum_{j=1}^q w_{j,k}^{ih} \cdot I_j \quad (23)$$

Where, O_s represents the normalized output value, q is the number of input parameters; r is the number of hidden neurons; s is the number of output parameters; $B1_s$ and $B2_k$ are the biases of s^{th} output neuron and k^{th} hidden neuron (H_k), respectively; $w_{j,k}^{ih}$ is the weights of the connection between I_j and H_k ; $w_{k,l}^{oh}$ are the weights of the connection between H_k and O_s .

4.4 ASSESSING THE ACCURACY OF NEURAL NETWORK

To assess the accuracy of the output the Regression values (R2), Root Mean Square Error (RMSE) and Mean Absolute Error (MAE) are calculated using **Eq. (24)**, **Eq. (25)** and **Eq. (26)** respectively, where t_i and O_i are the actual and predicted LTB moment resistance of steel cellular beam, and N is the total number of data points in each set of data. \bar{O}_i and \bar{t}_i are the average of the predicted and actual LTB moment resistance.

$$R = \frac{\sum_{i=1}^N (O_i - \bar{O}_i)(t_i - \bar{t}_i)}{\sqrt{\sum_{i=1}^N (O_i - \bar{O}_i)^2 \sum_{i=1}^N (t_i - \bar{t}_i)^2}} \quad (24)$$

$$RMSE = \sqrt{\frac{\sum_{i=1}^N (O_i - t_i)^2}{N}} \quad (25)$$

$$MAE = \frac{1}{N} \sum_{i=1}^N |O_i - t_i| \quad (26)$$

4.5 QUANTIFYING INPUT VARIABLE CONTRIBUTIONS IN ANN

In this section, the methodology for evaluating the contribution of each variable to LTB resistance of steel cellular beams is presented.

4.5.1 Connection Weight Approach

Olden and Jackson [58] proposed the connection weigh approach that estimates the rank importance of each individual input in the neural network. The magnitude and sign of the weights between neurons identify the effect of the input parameters on the output. The advantage with this approach is that it not only provides the impact of each input parameter, but it also shows whether an increase in the input parameter will increase or decrease the value of the output parameter. A positive value will dictate that an increase in the input parameter will increase the value of the output parameter and vice versa for a negative value. The impact of an input (S_x) can be calculated by the product of raw input-hidden and hidden-output connection weights and sum the products across all hidden neuron [58] as illustrated in the following **Eq. (27)** [59]:

$$Input_X = \sum_{Y=A}^E Hidden_{XY} \quad (27)$$

4.5.2 Garson's Algorithm

Garson [60] proposed a method to determine the relative importance of each input variable in the network. This approach has been used in previous studies [57,61–63]. It is important to note that Garson's algorithm uses the absolute values of the connection weights when calculating variable contributions, and hence does not provide the direction of the relationship between the input and output variables [58]. The relative importance of the j^{th} input parameter on the output is presented in **Eq. (28)**, in which N_i and N_h are the numbers of neurons in the input and hidden layers, respectively; w is connection weights; the subscripts k , m , and n refer to input, hidden, and output neurons, respectively, and the superscripts i , h , and o refer to input, hidden, and output layers, respectively.

$$I_j = \frac{\sum_{m=1}^{m=Nh} \left(\frac{W_{jm}^{ih}}{\sum_{k=1}^{Ni} W_{km}^{ih}} W_{mn}^{ho} \right)}{\sum_{k=1}^{k=Ni} \left[\sum_{m=1}^{m=Nh} \left(\frac{W_{km}^{ih}}{\sum_{k=1}^{Ni} W_{km}^{ih}} W_{mn}^{ho} \right) \right]} \quad (28)$$

5. RESULTS AND DISCUSSION

As stated previously, the number of neurons in the hidden layer will have an influence on the ANN accuracy. Although utilizing many neurons in the hidden layers increases the accuracy of the ANN prediction, the model gives more complicated explicit formulas which in practical application create more space for error. Additionally, an increase in the number of neurons may lead to overtraining [61]. **Table 4** provides the R2 and MSE values of the training, validation and testing data that was determined for the different models. As the number of neurons increase there is a direct correlation with the accuracy of the model. However, it can be seen that the model with a low number of neurons still has an exceptionally high level of accuracy. As the models with fewer neurons provide this level of accuracy and will result in a more user-friendly formula for industrial application, it is acceptable that these can be used instead of those models with a higher level of neurons.

Table 4: Comparison of statistical values to evaluate the accuracy of the ANN models with different neurons

Number of neurons	R^2			MSE			All data		
	Training	Validation	Testing	Training	Validation	Testing	RMSE	MAE	R^2
3	0.99974	0.99966	0.99973	8.71×10^{-5}	9×10^{-5}	1.41×10^{-4}	2.220	1.510	0.9994
5	0.99985	0.99985	0.99967	5.01×10^{-5}	7.11×10^{-5}	1.14×10^{-4}	2.037	1.382	0.9996
7	0.99987	0.99990	0.99842	4.17×10^{-5}	3.67×10^{-5}	6.14×10^{-5}	1.678	1.075	0.9997
9	0.99990	0.99987	0.99989	2.79×10^{-5}	3.31×10^{-5}	3.37×10^{-5}	1.232	0.839	0.9998
11	0.999996	0.99883	0.99992	1.25×10^{-5}	4.39×10^{-5}	3.51×10^{-5}	1.030	0.604	0.9999

After reviewing the statistical data of the ANN model, the accuracy of the model was assessed based on the overall predicted values of the ANN model and the actual values. The statistical parameters R2, RMSE and MAE of the network with different neuron can be seen in **Table 4**. **Fig. 6a** and **Fig. 6b** are examples of the actual against predicted lateral torsional buckling moment for ANN models with 7 and 9 neurons, respectively. As expected, that as the number of neurons increase the RMSE and MAE reduced and there is a slight change in the regression value. For instance, as the number of neurons increase from 7 to 9 the RMSE decreases from 1.678 to 1.232 and MAE decrease from 1.075 to 0.839 while the regression value slightly improved. Based on these results it

was concluded that an ANN network model with 7 neurons provides a high level of accuracy, as well as a more practical equation and this ANN model will be used for further analysis in the following sections.

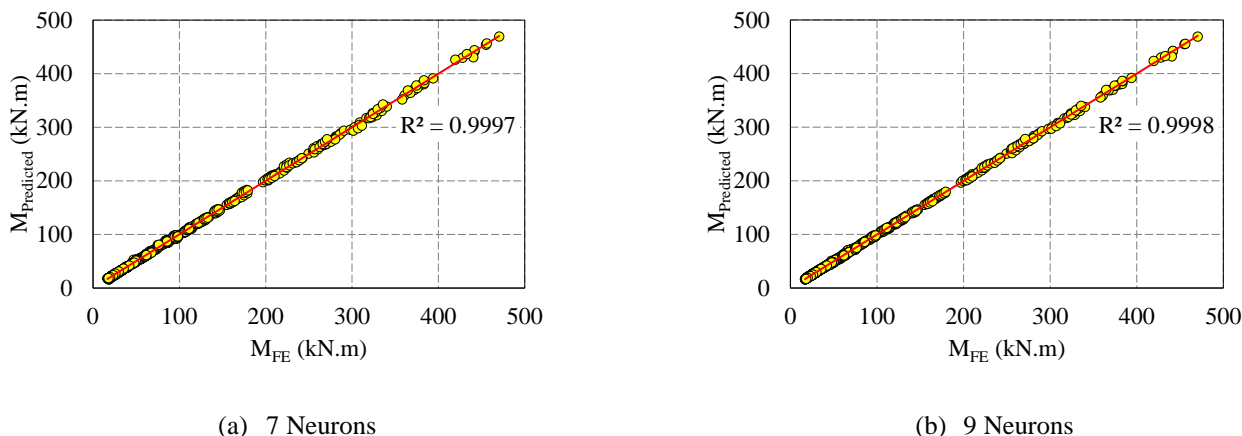


Fig. 6: Actual vs. predicted bending moment

In order to further validate the ANN predictions, the impact of input parameters was assessed using the connection weight approach and Garsons algorithm. **Fig. 7** provides the impact that each input parameter within the ANN model has on the lateral torsional moment capacity of a cellular beam. The connection weight approach shows that input parameters d_g , b_w , b_f , t_f , t_w and C_b have direct impact on the strength – increasing in these parameters results in an increase in bending moment capacity. This agrees with what would have been expected as the greater the height, web-thickness, flange thickness and width and spacing between openings of cellular beam, the greater the lateral torsional buckling resistance. On the other hand, input parameters L , D_o and z_g have negative impact on the resistance as it was anticipated, as increasing the length, and opening diameter, and leads to a decrease in strength and the destabilizing effect reduces the buckling resistance. **Fig. 7** also illustrates the relative importance (S values) of the nine input parameters. The most important input corresponds to highest absolute S value. It can be observed that the length, flange width and web thickness of the cellular beams are the significant factors with detrimental effect on the resistance, while the spacing between opening and opening diameter have less effect on the resistance. It is worth noting that these results do not correlate to the accuracy of the ANN predictions, and it is providing another form of validation for the ANN model. **Fig. 8** shows the contribution (%) of each input parameter (L , d_g , D_o , b_w , b_f , t_f , t_w , z_g , C_b) to output parameter M calculated using Garson algorithm as explained in section 4.5.2. The contribution of these input parameters is 25.22%, 9.79%, 9.62%, 6.48%, 9.40%, 6.85%, 14.26%, 9.43% and 8.94%, respectively, indicating, again, that the length, and web thickness have significant contribution to the resistance. In conclusion, as the ANN model with seven neurons provides predictions with high level of accuracy and the impact of the inputs on the resistance is as physically expected, it will be used in the following sections.

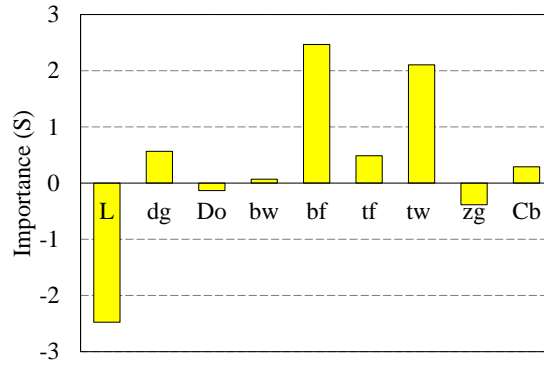


Fig. 7: Impact of input parameters on the resistance

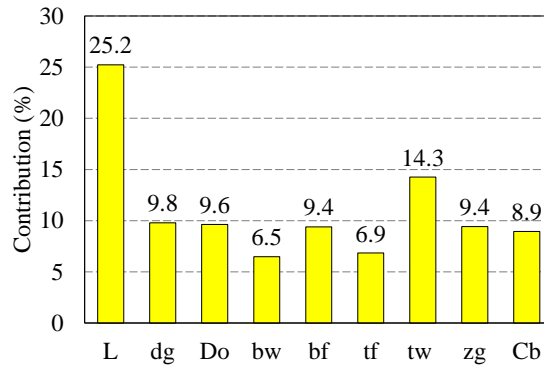


Fig. 8: Contribution (%) of input parameters to the resistance

6. ANN-BASED FORMULA AND COMPARATIVE ANALYSES

In this section the resistance prediction results developed by ANN are compared with analytical procedures. ANN-based formula to predict the normalized LTB moment resistance is illustrated in the Eq. (29). The input parameters, which would have to fall within X_{\max} and X_{\min} range stated in Table 3, should be normalized using Eq. (21). In order to calculate the normalized LTB moment resistance $(M)_n$, the values $H_1, H_2 \dots H_7$ should be calculated using Eq. (30) and substituted into Eq. (29). In the equations, $(M)_n$ represent the normalised value of the input parameter, $w1(i,j)$ are the connection weights between neuron in the hidden layer (i) and input (j), as seen in the Table 5, $w2(i)$ are the connection weights between the neuron in the hidden layer (i) and the output, as seen in the Table 5. $B1(i)$ are the bias for each neuron (i) in the hidden layer, as seen in the Table 5, $B2$ is the output bias and is equal to 1.96889. To determine the LTB moment resistance to its original format (i.e., without normalisation), denormalization need to be conducted.

$$(M)_n = B2 + \sum_{i=1}^{n=7} w2(i) \left(\frac{2}{1 + e^{-2H_i}} - 1 \right) \quad (29)$$

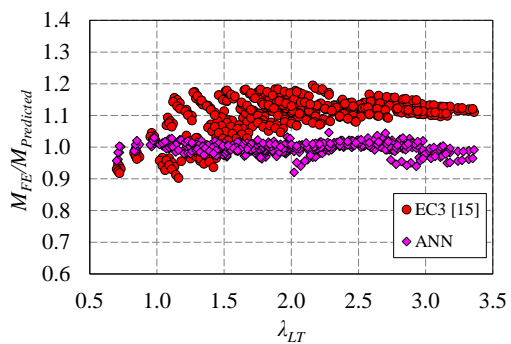
$$H_i = B1(i) + W1(i,1)(L)_n + w1(i,2)(d_g)_n + w1(i,3)(D_o)_n + w1(i,4)(b_w)_n + w1(i,5)(b_f)_n + w1(i,6)(t_f)_n + w1(i,7)(t_w)_n + w1(i,8)(z_g)_n + w1(i,9)(C_b)_n \quad (30)$$

Table 5: The connection weight and the bias values

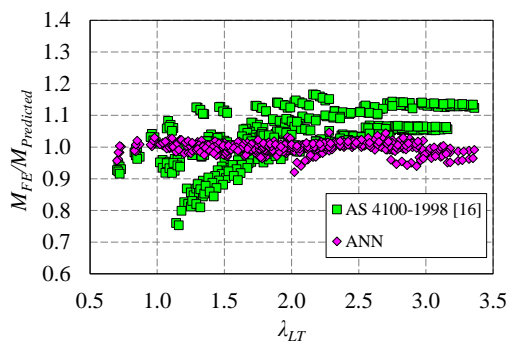
Neuron	$w1(i,j)$							$w2(i)$		$BI(i)$	
	L	d_g	D_o	b_w	b_f	t_f	t_w	z_g	C_b		M
1	-0.2669	0.1919	0.0195	-0.0464	-0.3124	-0.6813	0.9791	1.5399	-0.9908	-0.0504	1.4748
2	-1.7443	0.2162	-0.6503	-0.3029	-0.7204	-0.1041	-1.2666	-0.1281	-0.3717	-2.1171	-3.2841
3	0.6228	-0.7600	-0.5885	-0.3327	0.1577	-0.1627	-0.6824	-0.0555	0.1633	-0.1882	-1.1741
4	-1.0510	0.7635	-0.4885	1.2044	0.0841	-0.1215	0.7132	-1.2802	-1.0535	-0.0020	1.3307
5	0.8900	-0.2046	0.0635	0.0006	0.1224	-0.3040	-0.2837	0.1261	-0.1031	-2.8734	1.8707
6	-1.5960	0.2017	-0.6648	-0.3083	0.3822	-0.3031	-0.6035	-0.1166	-0.3515	2.4490	-1.6562
7	1.2305	-0.5902	0.5826	0.2080	1.1378	0.2109	0.0242	0.1690	0.1394	0.3250	1.5917

6.1. LOADS APPLIED AT SHEAR CENTRE

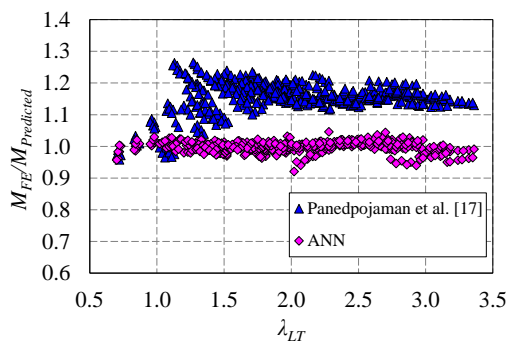
The equation developed by ANN is compared with the EC3 [13], AS 4100-1998 [14], Panedpojaman et al. [15], EC3 [13] and Sonck [17], Taras and Greiner [16] with Sonck [17] and Faria et al. [41] procedures, considering loads applied at shear center. It is important to highlight that of the 768 models that were selected for the application of the ANN, 458 models were subjected to loading applied at shear centre. The comparison results are presented in Fig. 9.



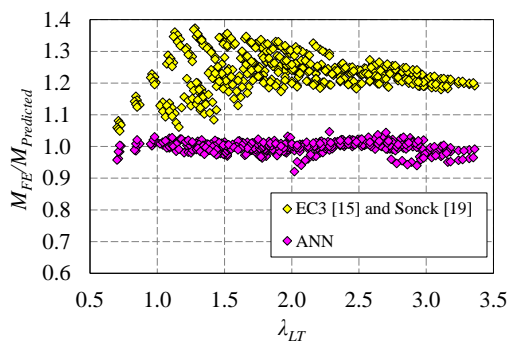
(a) ANN vs. EC3 [13]



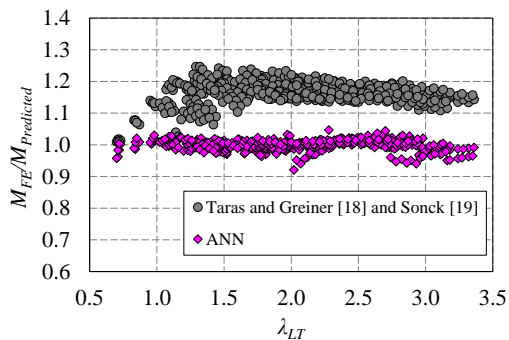
(b) ANN vs. AS 4100-1998 [14]



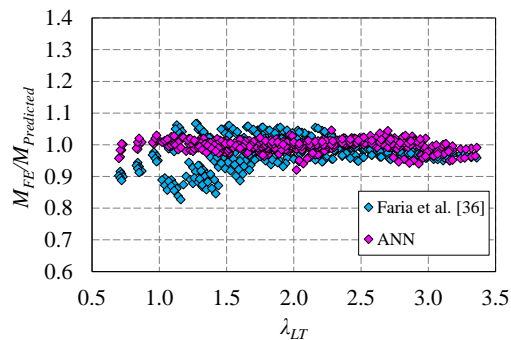
(c) ANN vs. Panedpojaman et al. [15]



(d) ANN vs. EC3 [13] and Sonck [17]



(e) ANN vs. Taras and Greiner [16] with Sonck [17]



(f) ANN vs. Faria et al. [41]

Fig. 9: Loads applied at shear centre

According to **Fig. 9a**, it is possible to notice that most finite element models presented higher moment values ($M_{FE}/M_{Predicted} > 1.0$) when compared to the EC3 prediction [13]. The maximum and minimum difference ($M_{FE} - M_{Predicted}$) between the models in this comparison were 10.74 kN.m and -16.32 kN.m, respectively. It is noteworthy that to calculate the moment, according to EC3 [13] requirements, for values $d_g/b_f > 1.2$, the buckling curve b must be used. In this context, EC3 [13] recommendations may underestimate the LTB resistance of steel cellular beams. One way to reduce these differences is to use the buckling curve c , as presented in Ferreira et al. [37].

Regarding the AS 4100-1998 [14], as shown in **Fig. 9b**, for $\lambda_{LT} \leq 2.0$, values of the ratio $M_{FE}/M_{Predicted} < 1.0$ were obtained. This was due to the drop in resistance of the cellular steel beams as a result of the combination of the LTB with some local buckling mode, such as web-post buckling or web distortional buckling. On the other hand, for $\lambda_{LT} > 2.0$, the values of the ratio $M_{FE}/M_{Predicted}$ increase, situation in which the models presented LTB failure. According to Ellobody [1], the Australian standard underestimates the LTB resistance of steel cellular beams, which is in fact consistent with the analyses carried out in the present study. The maximum and minimum differences ($M_{FE} - M_{Predicted}$) between the models, in this case were 32.74 kN.m and -14.26 kN.m, respectively.

The proposal by Panedpojaman et al. [15], which is based on EC3, underestimates the LTB resistance of steel cellular beams (**Fig. 9c**). However, this occurred for $\lambda_{LT} > 1.5$, models in which ratio values were $M_{FE}/M_{Predicted} > 1.1$, were verified. It is noteworthy that the authors' proposal takes into account a correction factor due to the absence (uniform bending), or the presence (mid-span and uniformly distributed loads) of the shear effect. The minimum and maximum values calculated through the difference between the numerical model and the predicted one were -20.93 kN.m and 4.38 kN.m, respectively.

The comparison of finite element models with the predictions of EC3 [13] and Sonck [17], Taras and Greiner [16] with Sonck [17] are presented in **Figs. 9d-e**, respectively. These models, developed in accord with EC3, consist of modifying the imperfection factor which is calculated in function of the ratio between the elastic section modulus in both main strong and weak axis. Both methods underestimated the LTB resistance of steel cellular beams. In the case of the EC3 [13] with Sonck [17] procedure, the $M_{FE}/M_{Predicted}$ ratio reached the value of approximately 1.4, while in the proposal by Taras and Greiner [16] with Sonck [17], this value reached 1.25, approximately. The maximum and minimum differences ($M_{FE} - M_{Predicted}$), respectively, between the models were

-4.66 kN.m and -27.16kN.m, for EC3 [13] with Sonck [17], and for Taras and Greiner [16] with Sonck [17] these values were -
0.82 kN.m and -19.78kN.m.

Fig. 9f shows the comparison between finite element models with a proposal developed by por Faria et al. [41]. This model was the one that least underestimated the LTB resistance of steel cellular beams. However, for values of $\lambda_{LT} \leq 2.0$, the predictions overestimated the resistance of steel cellular beams, especially for the models in which LTB was verified accompanied by local buckling modes. The minimum and maximum values calculated through the difference between the numerical model and the predicted one were -20.88 kN.m and -6.33 kN.m, respectively. **Table 5** presents the summary of statistical analyses. **Fig. 10** shows the relative error between the 458 models that were compared.

Table 5: Comparison of statistical values to evaluate the accuracy of the ANN models with different procedures for loads applied at shear centre

Reference	[13]	[14]	[15]	[13] and [17]	[16] and [17]	[41]	ANN
Average	1.099	1.028	1.153	1.233	1.164	0.979	0.998
S.D.	6.04%	7.57%	5.41%	5.94%	3.86%	4.51%	1.70%
Var.	0.36%	0.57%	0.29%	0.35%	0.15%	0.20%	0.03%
Max.	1.195	1.166	1.265	1.373	1.247	1.068	1.046
Min.	0.903	0.753	0.958	1.049	1.008	0.827	0.921
R²	0.9935	0.9858	0.9922	0.9964	0.9968	0.9958	0.9998
RMSE	10.0913	16.7249	16.9338	22.6819	19.1778	14.1996	1.4816
MAE	7.6783	7.3541	12.1673	17.0621	13.6899	5.9913	0.9703

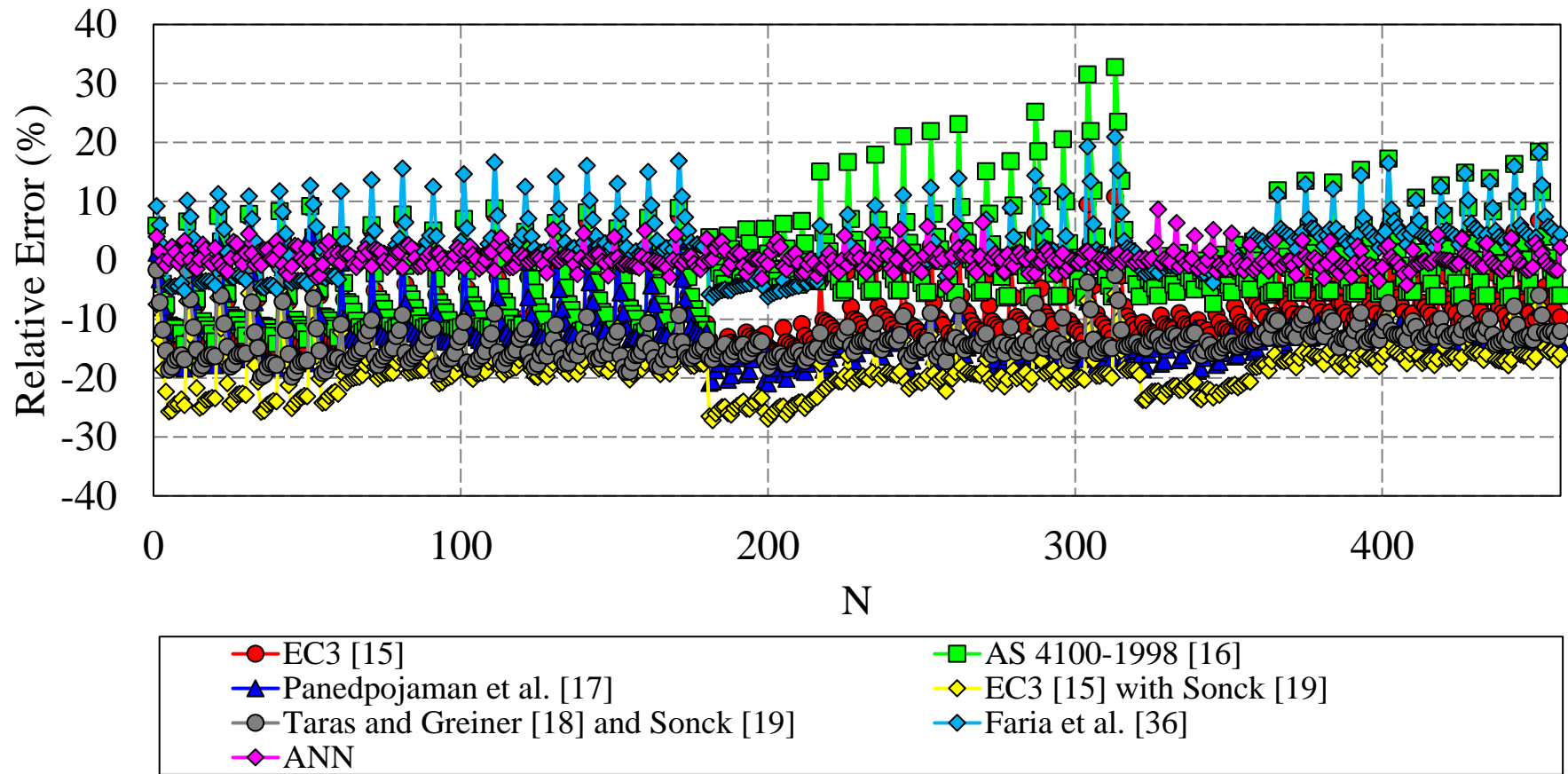


Fig. 10: Relative error (%) between the models considering loads applied at shear centre

6.2. LOADS APPLIED AT UPPER FLANGE

For loads applied at upper flange, the ANN formula is compared with EC3 [46], AS 4100-1998 [14] and Taras and Greiner [16] with Sonck [17]. In the latter case, the equation of the three factors (C_1 , C_2 and C_3) is used to calculate the critical moment [46]. In this scenario, in total of 768 selected models, 310 models were subjected to loading applied at upper flange. The comparison results are shown in Fig. 11.

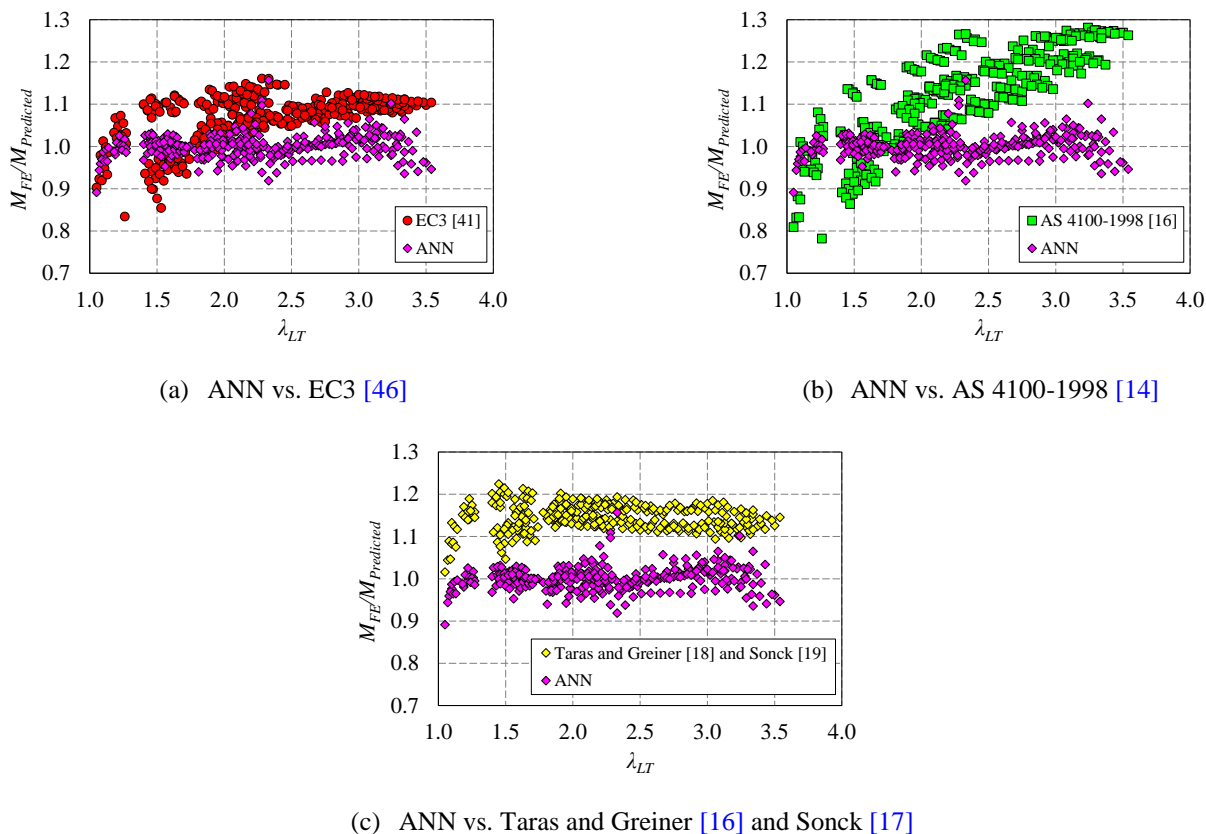


Fig. 11: Loads applied at upper flange

When comparing the finite models with the EC3 [46] (Fig. 11a), for $\lambda_{LT} \leq 1.8$ the procedure overestimates the LTB resistance of steel cellular beams subjected to the destabilizing effect of loading. It is noteworthy that the smaller the value of λ_{LT} , the greater the possibility of the steel cellular beam reaching the LTB mode in the combination with the other buckling modes, such as WPB or WDB. In this context, the minimum and maximum differences between the finite element model and the predicted by EC3 were -13.86 kN.m and 19.84 kN.m, respectively. On the other hand, when the numerical models were compared with the Australian standards [14] (Fig. 11b), it proved to underestimate the resistance of the cellular beams for $\lambda_{LT} > 1.5$, and the difference could reach, approximately, 30% more than the resistance of the finite element model. This procedure showed the minimum and maximum values between the numerical model and the predicted model ($M_{FE} - M_{Predicted}$) equal -21.96 kN.m and 27.83 kN.m, respectively.

Finally, when comparing finite element models with Taras and Greiner [16] with Sonck [17], considering the equation of the three factors (C_1 , C_2 and C_3) [46], the analytical procedure showed results in which the ratio $M_{FE}/M_{Predicted}$ varied between 1.00 and 1.22, demonstrating that all results are in favor of safety, although in some models the LTB resistance of steel cellular beams may be underestimated. In this case, the minimum and maximum values between the numerical model and the predicted were -

18.33 kN.m and 0.22 kN.m, respectively. **Table 6** presents the summary of the statistical analyses, and **Fig. 12** illustrates the relative error between the 310 models that were compared. **Table 6** presents the summary of statistical analyses, and **Fig. 12** illustrates the relative error between the 310 models that were compared.

Table 6: Comparison of statistical values to evaluate the accuracy of the ANN models with different procedures for loads applied at upper flange

Reference	[46]	[14]	[16] with [17]	ANN
Average	1.064	1.116	1.145	1.001
S.D.	5.85%	10.75%	3.31%	2.87%
Var.	0.34%	1.16%	0.11%	0.08%
Max.	1.161	1.281	1.224	1.157
Min.	0.834	0.782	1.002	0.891
R²	0.9921	0.982	0.9973	0.9994
RMSE	8.3819	12.1456	12.2539	1.9315
MAE	5.0446	7.9363	9.1867	1.2298

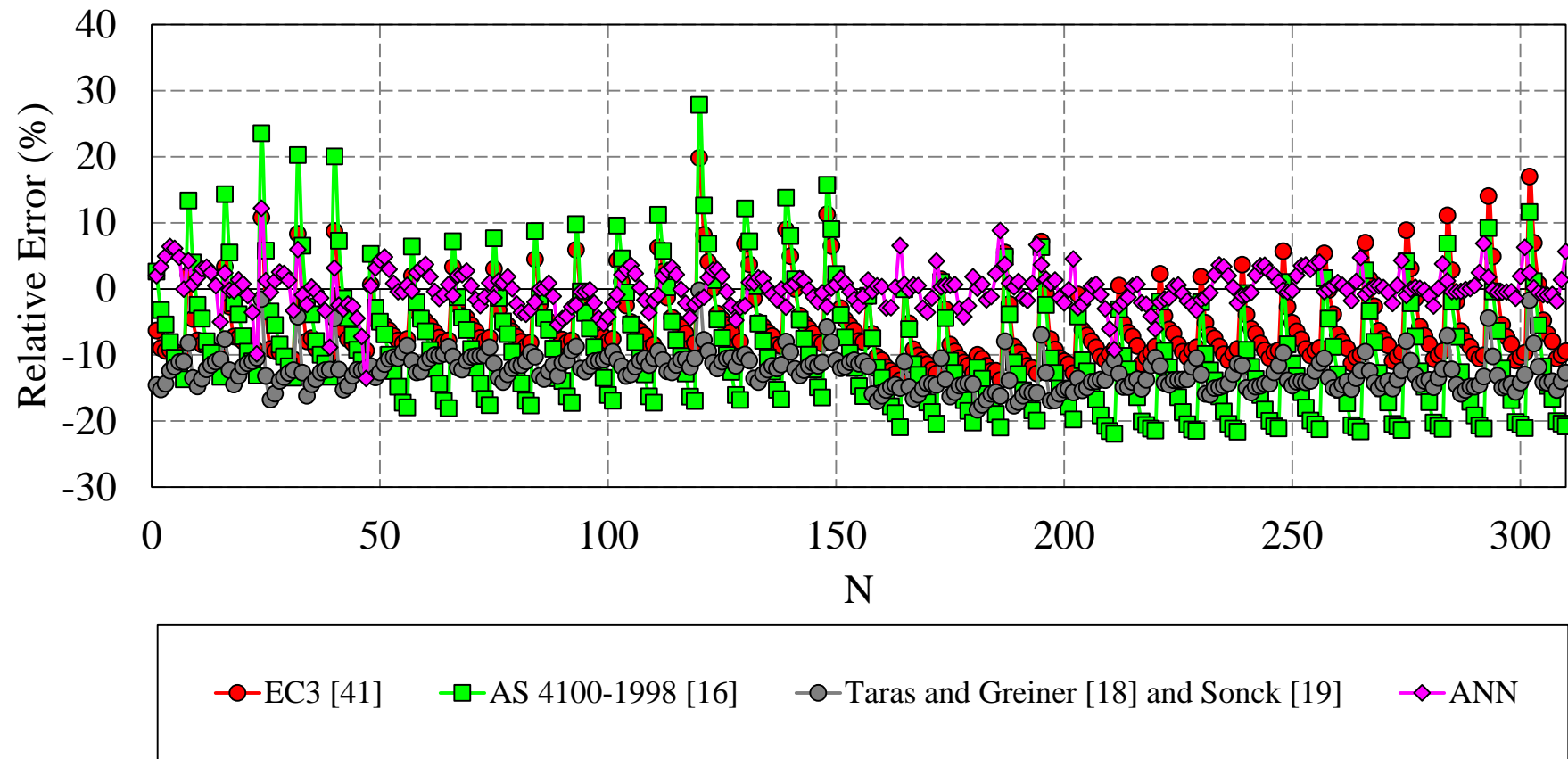


Fig. 12: Relative error (%) between the models considering loads applied at upper flange

CONCLUSION

This paper develops a robust numerical model for predicting the lateral-torsional buckling behavior of steel cellular beams, also considering the interaction of LTB mode with the web post buckling and web distortional buckling. The finite element model was calibrated via tests consolidated in the literature and a parametric study which was carried out through post-buckling analysis, considering physical and geometric imperfections as well as destabilizing loading effects. 768 models were selected to generate the ANN-based formula while the accuracy of this ANN-based model can be further improved by adding more data from future experimental and numerical studies, and makes this ANN model flexible enough to improve overtime. The proposed ANN-based model produces a single output, which is the LTB resistant moment of steel cellular beams, accounting for the length, overall height of the beam, opening diameter, distance between opening, flange width, flange thickness, web thickness, distance from the point of the load application to the shear centre of the section, and the moment-gradient factor. The finite element models were compared with the ANN-based formula and six analytical procedures, considering neutral and destabilizing effects of loads. The Australian standards underestimated the lateral-torsional buckling resistance of steel cellular beams. Regarding the analytical models based on EC3, most of them underestimated the resistance prediction of steel cellular beams. Finally, the ANN-based formula showed agreement with the finite element models. While the entire process of ANN model generation is indeed laborious and requires a level of expertise on numerical computing, its application for the design of real structures is simple. The model can be easily implemented in a spreadsheet or any other programming environment, using the provided weights and biases. Compared to the procedures provided by design guidelines and codes of practices, which often require iterative processes in order to determine the equilibrium of internal forces inside the cross section under conditions of combined axial force and bending moment, the implementation of the ANN model instead, could be straightforward while the computational cost is low.

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