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1   **Title:** Estimating settlements due to TBM tunnelling

2   **Abstract**

3   Soft-ground Tunnel Boring Machines (TBM) are the preferred solution for construction of long tunnels  
4   and linear infrastructure assets, especially in urban areas. TBMs allow the control of tunnel face stability,  
5   minimizing effects on the surrounding ground. Unfortunately, existing methods for the assessment of  
6   ground surface movements due to TBM tunnelling either utilise complex and computationally expensive  
7   numerical analyses or rely on simplistic volume loss theories, which do not consider the characteristics  
8   of the ground and TBM operation. This paper presents a simple formulation to estimate the immediate  
9   surface settlement due to the applied TBM support pressure, based on an analogy with the hyperbolic  
10   behaviour of stress-strain curves of soils. The maximum surface settlement and volume loss were the  
11   variables chosen to describe the ground movement while the TBM face support pressure describes the  
12   tunnel internal support pressure. Uncertainties due to the inherent variability of geotechnical parameters  
13   were also considered, resulting in definition of lower and upper boundaries. Data from a series of  
14   centrifuge test results, with and without tunnel face reinforcement by forepoles and a real scale TBM  
15   case study were used to validate the proposed model. Presented analyses show that the proposed  
16   model adequately represented observed settlement data.

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18   **Keywords chosen from ICE Publishing list**

19   Settlement, Tunnels & Tunnelling, Centrifuge Modelling.

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## 1. Introduction

Tunnel Boring Machines (TBMs) for soft ground have become the preferred option for construction of long tunnels in urban areas. Despite the careful operation of TBMs, ground disturbance is inevitable. Leca and New (2007) show that ground movements are induced by tunnelling as a consequence of the development of plastic zone of the groundmass, which is initiated at the tunnel face and propagates into the ground. Even settlements of low magnitude might cause serviceability problems on nearby structures or pipelines (Vorster et al., 2005). Therefore, the estimation of ground movements due to tunnelling is of paramount importance.

Several approaches that do not consider the specific conditions of TBM excavations have been proposed to estimate ground movements, such as empirical methods (Attewell and Woodman, 1982; Celestino et al., 2000; Franza and Marshall, 2019; Jacobsz et al., 2004; New, 1991; Peck, 1969; Vorster et al., 2005), analytical solutions (Litwyszyn, 1957; Sagaseta, 1987; Pinto and Whittle, 2014; Verruijt and Booker, 1996), numerical methods (Avgerinos et al., 2018; Fagnoli et al., 2015; Komiya et al., 1999; Lee and Rowe, 1990; Wongsaroj et al., 2013) or physical modelling (Atkinson and Potts, 1977; Franza et al., 2019; Marshall et al., 2012; Meguid et al., 2008; Schofield, 1980).

Ground movements due to TBM tunnelling are largely associated with plastic behaviour of the groundmass. Therefore, the most common procedures to minimize ground movement are based on methods to stabilize the tunnel face against groundmass instability by applying internal support pressure in the excavation chamber (Mair and Taylor, 1997). The design approach based on controlling ground movements through tunnel face support has led to the development of several methods for the evaluation of excavation stability. These methods, however, do not provide estimations of ground movement. It is simply assumed that a stable excavation would not produce significant settlements. According to Guglielmetti et al. (2008), the main analytical approaches for assessing tunnel face stability are those proposed by: Anagnostou and Kovári (1994, 1996), based on the limit equilibrium method (LEM); Carranza-Torres (2004), based on the Caquot's lower-bound solution of cavity collapse for an elastoplastic Mohr-Coulomb material; and Leca and Dormieux (1990), which is based on the upper-bound solution of plasticity theory. Numerical analysis of TBMs, based mainly on the Finite Element Method, is also employed for evaluating the effect of TBM support pressure in controlling tunnel face stability (Kavvadas et al., 2017).

Despite the large number of methods available for evaluating tunnel face stability, there is a

limited number of methods for the quantitative estimation of ground surface movements due to TBM tunnelling. The short-term analysis of ground response is generally expressed in terms of the maximum surface settlement ( $S_{max}$ ) and the volume loss ( $V_L$ ) variables. Ground movement has been empirically related to the stability ratio ( $N$ ), defined by Broms and Bennermark (1967). Attewell et al. (1986) presented a direct correlation between  $V_L$  and  $N$ . Macklin (1999) proposed a relationship to estimate  $V_L$  based on the concept of Load Factor ( $L_F$ ) introduced by Mair et al. (1981) using results of centrifuge tests. Later, Atkinson (2007), also based on centrifuge tests, proposed a relation between  $L_F$ ,  $V_L$ , and the applied support pressure.

Osman et al. (2006) proposed a simplified closed-form solution, based on the upper-bound theorem of plasticity, for the prediction of maximum surface ground settlement considering the applied tunnel support pressure. A series of five centrifuge test analyses on plane-strain unlined tunnels in kaolin clay was conducted to validate this formulation. They observed a close correspondence between experimental observations and theoretical predictions for deep tunnels ( $C/D > 3$ ) but poor correlations for shallow tunnels ( $C/D < 3$ ), with  $C$  and  $D$  defined as in Figure 1.

This brief literature background indicates that there is a need for the development of methods for estimating ground movements due to TBM excavation. In this context, a simplified method based on the general approach presented by Osman et al. (2006) is presented herein. The proposed method relates maximum settlement and volume loss with support pressures using an analogy with the hyperbolic behaviour of stress-strain curves of soils. The proposed approach considers both drained and undrained conditions, but the validation analyses presented herein are limited to centrifuge test under undrained conditions. Furthermore, the definition of lower and upper-bound are proposed to address the inherent variability of soil properties.

## 2. Proposed model for ground surface settlement

Figure 1 shows a representation of a typical transverse surface settlement curve,  $S$  (mm), due to excavation, at a sufficient distance behind the advancing tunnel face. Peck (1969) and later Attewell and Woodman (1982) approximated this behaviour to that of a Gaussian probability density function, as follows:

$$S = S_{max} \exp\left(-\frac{y^2}{2i^2}\right) \quad 1.$$

where:  $S_{max}$  is the maximum surface settlement (mm);  $y$  is the transverse distance (m);  $i$  is the point of inflection distance of the settlement trough (m). The value of  $S_{max}$  may be estimated by integrating Eq. 1 from minus to positive infinity, resulting in:

$$S_{max} = \frac{AV_L}{i\sqrt{2\pi}} \quad 2.$$

where:  $V_L$  is the volume loss (%) and  $A$  is the cross-sectional area of the tunnel (m<sup>2</sup>). In general, this approximation has been well accepted for its simplicity.

The groundmass displacement along the longitudinal direction (Figure 2) may be categorized as:

- Face loss (zone “a” in Figure 2): ground movement towards the tunnel face due to stress relief. For TBMs, this is normally associated with a low face pressure;
- Shield loss (zone “b” in Figure 2): ground deformation around the shield due to over-cutting edge combined with a misaligned TBM displacement that may result in radial ground movements and soil shearing;
- Tail void loss and lining loss (zone “c” in Figure 2): the first is due to the gap between the tail of the shield and the final precast lining and the second is associated with the deflection of the lining as the ground pressure increases as a consequence of soil closure on the lining. For tunnels lined with thick pre-cast concrete segments, this is usually considered a minor source of ground displacement; and
- Consolidation (zone “d” in Figure 2): ground displacement due to a new pore-water pressure distribution resulting from changes in the drainage conditions.

When the excavation is made in an uncontrolled manner, larger movements are observed, and their mathematical modelling becomes more difficult due to erratic deformation patterns. However, ground displacements may be minimized when tunnelling is performed in a highly controlled manner. Settlements due to TBM excavation may be controlled by the continuous application of active support pressure given by the TBM face support pressure and grout injection pressure (Guglielmetti et al., 2008; Maidl et al., 2012; Mair, 2008; Mollon et al., 2013).

The first three settlement categories (i.e., zones a, b, and c) result in the “immediate” settlement that occurs as the TBM face moves ahead of the measurement point. This paper deals only with the immediate settlements during TBM tunnelling, in conditions that are predominately considered as undrained but may, in highly permeable materials, occur under drained conditions.

109

## 110 2.1 Immediate surface settlement curve

111 Based on centrifuge test results, Atkinson (2007) presented a conceptual model of groundmass  
112 response due to TBM tunnelling. Figure 3c shows a schematic representation of that model, expressed  
113 in terms of the expected behaviour of immediate surface settlement due to the applied TBM support  
114 pressure. During tunnelling, if the applied TBM support pressure,  $P$ , is equal to the estimated initial  
115 support pressure for tunnel face stability,  $P_0$ , the surface settlement should be negligible. The initial  
116 portion of the settlement curve corresponds to predominantly elastic behaviour. The onset of plastic  
117 behaviour is identified as the settlement curve approaches the asymptote given by  $P_{min}$ . Relatively larger  
118 settlements or even face collapse may occur when the applied TBM support pressure reaches a  
119 minimum value,  $P_{min}$ , which is not necessarily zero.

120 In order to represent mathematically the general behaviour shown by Atkinson (2007), a model  
121 selection analysis has been performed by Franco (2019). The statistical results indicated that a  
122 hyperbolic function, similar to the stress-strain relationship (Figure 3d) proposed by Duncan and Chang  
123 (1970), provides best results among the tested models. This formulation is based on the family of  
124 hyperbolic equations, as follows:

$$125 \quad (\sigma_1 - \sigma_3) = \frac{\varepsilon}{a + b\varepsilon} \quad 3.$$

126 where:  $\sigma_1$  and  $\sigma_3$  are the major and minor principal stresses,  $\varepsilon$  is the axial strain, and  $a$  and  $b$  are best-  
127 fit parameters. The hyperbolic equation was used to express the relationship between the tunnel  
128 pressure support variables shown in Figure 3c, as follows:

$$129 \quad \left( \frac{S_{max}}{D} \right) = \frac{a_s (P_0 - P)}{b_s (P_0 - P) - 1} \quad 4.$$

130 where:  $S_{max}$  is the maximum surface settlement (mm);  $D$  is the tunnel diameter (mm);  $P$  is the applied  
131 TBM support pressure (kPa);  $P_0$  is the estimated initial TBM support pressure for face stability (kPa),  
132 corresponding to null displacements, and  $a_s$  and  $b_s$  are best-fit parameters.

133 The value of  $P_0$ , applied along the tunnel axis, may be estimated based on the limit equilibrium  
134 method (Anagnostou and Kovári, 1994, 1996) or based on limit analysis approaches (Carranza-Torres,  
135 2004; Davis et al., 1980), among other methods reviewed by Guglielmetti et al. (2008). Note that,  
136 depending on the adopted approach,  $P_0$  is estimated by considering different parameters, such as the

tunnel geometry, the unit weight of the material, the coefficient of lateral earth pressure at rest ( $k_0$ ); and the shear strength parameters. Regarding the parameter  $k_0$ , Franzius et al. (2005) indicated that a higher value of  $k_0 = 1.5$  leads to generate widest settlement trough with too small maximum settlement while a lower value of  $k_0 = 0.5$  generates a narrower settlement trough with increased vertical settlement. This analysis indicated that adopting extreme values of  $k_0$  produce minor impact on the estimation of the surface settlement magnitudes and profile. Note also that the tunnel diameter is considered by means of a normalized variable used in Eq. 4.

The initial slope of the proposed settlement curve is obtained by taking the limit of the curve derivative as  $P$  approaches  $P_0$ :

$$\left. \frac{\partial}{\partial P} \left( \frac{S_{\max}}{D} \right) \right|_{P \rightarrow P_0} = a_s \quad 5.$$

The asymptotic value of the ultimate stress difference  $(P_0 - P)_{ult}$  may be determined by rearranging Equation 4 and taking the following limit of  $S_{\max}$ :

$$\lim_{S_{\max} \rightarrow \infty} \left( \frac{S_{\max}}{b_s S_{\max} - a_s D} \right) = (P_0 - P)_{ult} = \frac{1}{b_s} \quad 6.$$

## 2.2 Relationships between model parameters and geotechnical properties

Based on Equation 5, the following relationships are proposed for the estimation of the parameter  $a_s$ , in the drained and undrained conditions in Equations 7 and 8, respectively:

$$a_s = 1/E'_{ur} \quad 7.$$

$$a_s = 1/E_{ur} \quad 8.$$

where:  $E'_{ur}$  and  $E_{ur}$  are the unloading-reloading elastic moduli (kPa) for drained and undrained conditions, respectively.

Figure 3 presents an analogy between a triaxial loading test and the stress path due to TBM tunnelling. Tunnel construction using a TBM often produces a reduced triaxial extension path, which is the reverse form of a conventional triaxial compression. The groundmass may be brought to a state of development of plastic zone by keeping the grout pressure constant, equal to  $P_0$ , and decreasing the face pressure to a value equal to  $P_{min}$ , as shown in Figure 3e. The asymptotic value  $(P_0 - P)_{ult}$  may be related to the stress difference at failure  $(P_0 - P_{min})$  using a constant failure ratio  $R_f$  inspired in the ratio



164 proposed by Duncan and Chang (1970):

$$165 \quad (P_0 - P_{\min}) = R_f^* (P_0 - P)_{ult} \quad 9.$$

166 where:  $R_f^* = R_f / (C/D)$ . This definition of  $R_f^*$  allows the consideration of the influence of the ratio between  
167 tunnel cover and diameter ( $C/D$ ).

168 Assuming that  $P_{\min}$  and  $P_0$  are principal stresses and considering a limit state defined by the  
169 Mohr-Coulomb envelope, the following expressions for  $(P_0 - P_{\min})$  are obtained for drained and  
170 undrained conditions in Equations 10 and 11, respectively:

$$171 \quad (P_0 - P_{\min}) = \frac{2c' \cos \varphi' + 2(P_0 - u_{w0}) \sin \varphi'}{1 + \sin \varphi'} \quad 10.$$

$$172 \quad (P_0 - P_{\min}) = 2S_u \quad 11.$$

173 where:  $c'$  is the effective cohesion (kPa);  $\varphi'$  is the effective friction angle (deg.);  $u_{w0}$  is the pore-water  
174 pressure at the tunnel axis (kPa); and  $S_u$  is the undrained shear strength (kPa).

175 Combining Equations 6, 9, 10, and 11, the following expressions are obtained for the parameter  
176  $b_s$  in the drained and undrained conditions, in Equations 12 and 13, respectively:

$$177 \quad b_s = \frac{1 + \sin \varphi'}{2c' \cos \varphi' + 2(P_0 - u_{w0}) \sin \varphi'} R_f^* \quad 12.$$

$$178 \quad b_s = \frac{1}{2S_u} R_f^* \quad 13.$$

179 The proposed simplified approach may also be used in terms of volume loss ( $V_L$ ). According to  
180 Atkinson (2007),  $V_L$  is defined as the ratio between the volume of over-excavated material and the  
181 tunnel volume per unit distance. Similar to volumetric strain, volume loss is a dimensionless variable.  
182 No relation is assumed between these two parameters, since in undrained conditions volumetric strain  
183 is null while volume loss is not. The hyperbolic equation may be presented, in terms of volume loss  $V_L$ ,  
184 as follows:

$$185 \quad V_L = \frac{a_v (P_0 - P)}{b_v (P_0 - P) - 1} \quad 14.$$

186 In a similar manner, the parameters  $a_v$  and  $b_v$  may be determined based on the elastic modulus  
187 and on the limit state, for both drained and undrained conditions, as shown in Eqs. 6, 7, 12, and 13.

The equations in terms of  $V_L$  will not be used herein and only the model for  $S_{max}$  will be evaluated, exclusively for the undrained condition. It is important to note that the proposed formulation relies on a simplified representation of the complex groundmass stress distribution near the tunnel. Therefore, the procedure proposed herein must be considered semi-empirical.

### 2.3 Dealing with the variability of input parameters

Some attention has been directed in the past towards the evaluation of how inherent groundmass variability results in scattered ground displacements (Suwansawat and Einstein, 2006; Fagnoli et al., 2013). The variability of geotechnical parameters and ground profile stratigraphy constitute a major source of uncertainty for the assessment of ground movements in TBM tunnelling projects. Thus, an appropriate description of these uncertainties is necessary (Kulhawy, 1992; Phoon and Kulhawy, 1999).

This section presents a simplified approach for the evaluation of the uncertainty of the settlement curve model proposed herein. The indicated procedure is based on the approach proposed by Zhai and Rahardjo (2013), using lower and upper-bound settlement curves. According to Kool et al. (1987), the bounds of a model are directly correlated to the confidence limits of the input parameters. For this study, the parameters  $a_S$  and  $b_S$  are assumed to be represented by the log-normal probability density function. The lower and upper-bounds are defined by estimating the 10<sup>th</sup> and 90<sup>th</sup> percentiles of the probability density function of each variable.

The physical meanings of the parameters  $a_S$  and  $b_S$  have been clearly defined and their behaviour with respect to  $S_{max}$  is exemplified in Figure 4. If each variable is analysed separately, the higher the values of  $a_S$  and  $b_S$ , the higher the absolute value of  $S_{max}$ . Therefore, the lower and upper bounds of the settlement curve should be defined by specific combinations of  $a_S$  and  $b_S$ , as follows:

$$\left( \frac{S_{max}}{D} \right)_{upper-bound} = \frac{a_{S90} (P_0 - P)}{b_{S90} (P_0 - P) - 1} \quad 15.$$

$$\left( \frac{S_{max}}{D} \right)_{lower-bound} = \frac{a_{S10} (P_0 - P)}{b_{S10} (P_0 - P) - 1} \quad 16.$$

where  $a_{S90}$  and  $b_{S90}$  correspond to the 90<sup>th</sup> percentile and  $a_{S10}$  and  $b_{S10}$  correspond to the 10<sup>th</sup> percentile.

From a practical point of view in the tunnelling industry, the above approach might be considered as complementary tool to be used in the protocol of tunnel excavation for defining the attention and

alarm limits of support pressure likely to occur during tunnelling as well as the immediate settlements that the support pressure might induced.

### 3. Analysis of centrifuge tests

The following section presents the analysis of previously published results of centrifuge tests carried out in undrained conditions, with and without the reinforcement of the tunnel face by forepoles. The hyperbolic model (Eq. 4) is used to evaluate surface settlements as a function of support pressure. Table 1 summarizes the features of each reference centrifuge test result collected from the literature. Basic input information regarding the geometry of each centrifuge model and the geotechnical properties are indicated. Unfortunately, only one reference presents information regarding the unloading-reloading total elastic modulus,  $E_{ur}$ .

Figures 5 and 6 show experimental and modelling results of the centrifuge tests carried out by Lee and Rowe (1989) and Osman et al. (2006), all without tunnel face reinforcement. A value of  $P_0$  of 130 kPa was considered for each test. The tests involved different values of overburden depth ( $C$ ) and tunnel diameter ratio ( $C/D$ ). Table 2 presents the best-fit values of  $a_s$  and  $b_s$ , obtained from nonlinear regression analyses. The values of number of data points ( $n$ ) and standard error (SE) for each variable are also presented for each test. The values of coefficient of determination ( $R^2$ ) and of Root Mean Square Error (RMSE) indicate excellent agreement between the experimental data and the model, with  $R^2$  values ranging between 0.942 and 0.995.

Figure 7 shows a series of eight two-dimensional plane strain centrifuge model tests performed by Divall et al. (2016). These tests were designed to investigate how forepoles affect the plastic collapse mechanism surrounding a tunnel excavation in stiff clay. These results allow the evaluation, using the proposed model, of how different forepole arrangements may artificially improve the soil around tunnel and might affect the surface settlement behaviour. However, a detailed analysis of the behaviour of the forepoles themselves is beyond the scope of this paper.

Divall et al. (2016) simulated the excavation by reducing the pressure, starting from an average initial support pressure of 211 kPa. However, the test results indicated negligible ground response up to a support pressure of 160 kPa, probably because  $P_0$  was estimated as a function of the original soil condition (i.e., without the influence of forepoles). To address this inconsistency, the formulation proposed by Broms and Bennermark (1967) was employed:

$$N = \frac{\gamma(C + D/2) + \sigma_s - \sigma_T}{S_u} \quad 17.$$

where:  $\gamma = 17.5 \text{ kN/m}^3$  (Divall, 2013);  $\sigma_s = 0$  is the surface surcharge pressure;  $S_u = 30 \text{ kPa}$ ; and  $\sigma_T = P_0$ .

Sensitivity analyses showed that values of  $N = 2$  and  $P_0 = 160 \text{ kPa}$  represented adequately the centrifuge data. Therefore, a value of  $P_0 = 160 \text{ kPa}$  was assumed in the modelling exercises presented herein. Figure 7 shows, for all centrifuge arrangements, that the proposed model agrees with the test results. The obtained coefficients of determination were higher than 0.99 for five out of eight tests.

Table 2 presents a comparison between the geotechnical parameters reported by the original references and the respective values estimated using Eqs. 8 and 13 and the best-fit parameters for Eq. 4. The adopted value of  $R_f$  was 0.9 for all the tests with clays. Lee and Rowe (1989) are the only reference that presents the value of  $E_{ur}$ , which is in close agreement with the model prediction. Regarding  $S_u$ , most measured values were adequately predicted, with a maximum relative error of 15%. The lower agreement observed for tests FP4, FP5 and FP7 from Divall et al. (2016) may be explained by the higher values of surface settlement as collapse approaches, with a support pressure below 20 kPa. This is an obvious indication that the arrangements of forepoles may contribute to reinforce the soil around the excavation. A Pearson correlation analysis of measured and predicted values of  $E_{ur}$  and  $S_u$ , especially from the tests results performed by Divall et al. (2016), showed a correlation of  $r = 0.6149$ , which indicates a moderate tendency for correlation. The lack of a strong correlation might be attributed to the fact that the soil was artificially improved by the addition of forepoles.

The new formulation provided an accurate fitting of the ground surface movement with the applied TBM support pressure as well as a consistent estimation of geotechnical parameters. Even though the analyses with the tunnel face reinforced by forepoles are mainly used in practice with open face tunnelling and not for TBMs, the formulation also demonstrates, in terms of the predicted values of equivalent  $S_u$ , the effectiveness of the forepoles as soil reinforcement around a tunnel heading.

#### 4. Case study – Line 5 of São Paulo Metro

The proposed procedure for incorporating the uncertainty of input parameters in the evaluation of settlement curves has been applied to a case study. The tunnel project corresponds to a 11.5 km long new extension of Line 5 of Sao Paulo Metro, located in the densely populated south region of the city

of Sao Paulo, Brazil (Figure 8). The new extension involves the construction of eleven stations and thirteen ventilation shafts, among other structures and facilities. The line extension was excavated by three Earth Pressure Balance (EPB) machines, two small EPB machines of 6.90 m in diameter, for two single track tunnels between Adolfo Pinheiro and Eucalipto stations, and one large EPB machine of 10.60 m in diameter, for a double track tunnel between Eucalipto and Chacara Klabin stations. The case study presented herein concerns the tunnel excavation by the larger EPB machine, specifically, in a 670 m stretch of the tunnel line, located between Hospital Sao Paulo (HSP) and Santa Cruz (SCR) stations. The tunnel cover depth in this section is of 24.35 m.

In terms of site geology, the line in this section crosses the Resende Formation, which comprises basal and sedimentary units of the Taubaté Group from the Eocene Period. It consists of a system of alluvial beds associated with the fluvial plain of intertwined rivers. This formation comprises two main lithofacies. The first lithofacy corresponds to the proximal alluvial beds, located in the vicinity of the contact with the basement, composed of polymitic conglomerates, interdigitated with sandstones and sandy mudstones. The second lithofacy corresponds to the alluvial beds in distal position associated to intertwined rivers, with occurrence of sandstones intercalated with mudstones. Detrital smectites (argillomineral of the expansive type) are present, which are considered as indicators of climatic semi-aridity and ineffective drainage.

The cover to diameter ratio ( $C=D$ ) is constant along the tunnel stretch, with a value of 2.30. Further details about this case study are presented by Franco et al. (2019).

Table 3 shows the observed maximum surface settlements ( $S_{max}$ ) and applied TBM support pressures ( $P$ ) for each of the nineteen monitoring cross-sections. A relatively high variability is observed for  $S_{max}$ , which was expressed in terms of the coefficient of variation (CoV). Franco (2019) performed an analysis for the estimation of  $P_0$  by following the limit equilibrium procedures proposed by Anagnostou and Kovári (1994) and considering drained conditions. The groundmass has four different soil types forming six layers, each layer with variable thickness. The values of  $C$  and  $D$  are 24.35 m and 10.60 m, respectively. The estimated value of  $P_0$ , in terms of total stress, was 308 kPa. Figure 9 and Table 4 show the tunnel model geometry, and the mean soil property values, respectively, considered in the case study for the estimation of  $P_0$ .

Figure 10 shows the best-fit results using the proposed model. The best-fit values for parameters  $D.a_s$  and  $b_s$ , obtained based on the monitored data, were equal to 0.02550 mm/kPa and 0.00285 1/kPa,

respectively. Figure 10 also shows the lower and upper-bound curves of the proposed model, expressed in terms of the 10<sup>th</sup> and 90<sup>th</sup> percentiles, as proposed in Equation 18. Values of CoV between 10% and 46% were used to illustrate the variability of the model according to the variability of  $S_{max}$  presented in Table 3. A value of CoV of 46% provides an adequate estimation of the lower and upper bounds of the observed values. Therefore, the proposed model may be an acceptable indicator for defining the limits in which soil variability affects the development of ground surface response during TBM tunnelling.

## 5. Concluding remarks

In this paper a simple and practical model for the estimation of ground surface settlements due to TBM tunnelling has been proposed, for both drained and undrained conditions. A series of centrifuge test analyses was used to validate the proposed model. Furthermore, the case study of the new extension of Line 5 of Sao Paulo metro was used to exemplify the determination of the settlement curve in statistical terms, using lower and upper bounds.

The physical meaning of the model parameters,  $a_s$  and  $b_s$ , was demonstrated. In addition, an alternative procedure for the estimation of these parameters was proposed, based on the soil stiffness, shear strength, and initial tunnel support pressure. This semi-empirical estimation procedure is based on an analogy between the stress states in the tunnel cavity and in triaxial tests. The parameter estimation procedure depends on the tunnel cross-section that is under analysis. Therefore, to consider  $P_0$  along a tunnel stretch, the soil stratification must be constant, and the mean values of geotechnical parameter should be considered along the tunnel path, for the ease of calculation.

The proposed approach was verified for geometrical conditions in which  $C/D < 3$ . Centrifuge tests performed by Lee and Rowe (1989) and later by Osman et al. (2006) for  $C/D > 3$  show that the settlement curve presents a second inflection point, which may not be adequately represented by the hyperbolic curves. Therefore, the formulation proposed herein should be applied with greater care for deeper tunnels, with  $C/D > 3$ .

The proposed model offers a valuable tool for TBM tunnelling projects incorporating the support pressure in the calculation of the tunnelling impact. In addition, the input parameters are based on relatively simple standard tests. Finally, it is important to note that the proposed approach can be used to derive lower and upper limits in order to consider the complexity and large number of variables that

affect groundmass response.

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454 **Notation list**

455	$A$	: is the cross-sectional area of the tunnel.
456	$a_s, b_s$	: are best-fit parameters for the surface settlement curve.
457	$a_{S90}, b_{S90}$	: are best-fit parameters of 90 <sup>th</sup> percentile for the surface settlement curve.
458	$a_{S10}, b_{S10}$	: are best-fit parameters of 10 <sup>th</sup> percentile for the surface settlement curve.
459	$a_v, b_v$	: are best-fit parameters for the volume loss curve.
460	$C$	: is the tunnel cover depth.
461	$CoV$	: is the coefficient of variation.
462	$c'$	: is the effective cohesion.
463	$D$	: is the tunnel diameter.
464	$E'_{ur}$	: is the unloading-reloading elastic modulus for drained condition.
465	$E_{ur}$	: is the unloading-reloading elastic modulus for undrained condition.
466	$I$	: is the point of inflection distance of the settlement trough.
467	$k_0$	: is the coefficient of lateral earth pressure at rest.
468	$L_F$	: is the load factor.
469	$N$	: is the stability ratio.
470	$P$	: is the applied TBM support pressure.
471	$P_0$	: is the estimated initial TBM support pressure for face stability.
472	$P_{min}$	: is the minimum applied TBM support pressure before face collapse may occur.
473	$(P_0 - P)_{ult}$	: is the ultimate stress difference.
474	$R_f$	: is the constant failure ratio proposed by Duncan and Chang (1970).
475	$R^*_f$	: is a modification of constant failure ratio.
476	$S$	: is the transverse settlement trough curve.
477	$S_{max}$	: is the maximum surface settlement.
478	$S_u$	: is the undrained shear strength.
479	$V_L$	: is the volume loss.
480	$\gamma$	: is the specific weight.
481	$\varepsilon$	: is the axial strain.
482	$\sigma_1$	: is the major principal stress.
483	$\sigma_3$	: is the minor principal stress.

484      $\sigma_s$                 : is the surcharged load.

485      $\sigma_T$                 : is the tunnel pressure.

486      $\varphi'$                     : is the effective friction angle.

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## Table captions

Table 1. Data selected from the literature on centrifuge geotechnical tests and reported geotechnical parameters under undrained condition.

Table 2. Best-fit and geotechnical parameters under undrained condition, estimated based on the proposed approach.

Table 3. Mean and CoV values of maximum surface settlement and applied TBM support pressure between HSP and SCR stations.

Table 4. Input geotechnical parameters between HSP and SCR stations (after Franco et al., 2019).

## Figure captions

Figure 1. Typical representation of transverse surface settlement.

Figure 2. Sources of longitudinal ground movements due to TBM tunnelling.

Figure 3. Comparison of stress paths: a) tunnel excavation producing reduced triaxial extension; b) conventional triaxial compression; c) settlement curve caused by tunneling; d) triaxial loading curve; and e) shear strength envelope.

Figure 4. Relationships between maximum surface settlement,  $S_{max}$ , and the fitting parameters: a)  $a_s$ ; and b)  $b_s$ .

Figure 5. Surface settlement data from Lee and Rowe (1989) and corresponding best-fit modelling.

Figure 6. Surface settlement data from Osman et al. (2006) and corresponding best-fit modelling.

Figure 7. Surface settlement data for the different forepoling arrangements in centrifuge tests from Divall et al. (2016) and corresponding best-fit modelling: a) FP4 and FP8; b) FP2 and FP6; c) FP5 and FP7; d) FP3 and FP9.

Figure 8. Metro stations layout of Line 5.

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545 **Tables**

546 Table 1. Data selected from the literature on centrifuge geotechnical tests and reported geotechnical parameters under undrained condition.

Reference	Test ID	(C/D)	D (mm) [m]*	Scale Factor N	Geotechnical parameters	
					$E_{ur}$ (kPa)	$S_u$ (kPa)
Lee and Rowe (1989)	2DP	1.67	36 [4.5]	125	3640	25.3
	2DH	1.80	60 [4.5]	75	-	26.0
Osman <i>et al.</i> , (2006)	2DP	1.67	60 [4.5]	75	-	22.6
	2DT	1.67	36[4.5]	125	-	22.6
Divall <i>et al.</i> , (2016)	FP2	2.00	50 [5.0]	100	-	33.7
	FP3				-	30.7
	FP4				-	35.0
	FP5				-	34.3
	FP6				-	32.8
	FP7				-	33.1
	FP8				-	32.1
	FP9				-	35.3

\* The values in brackets correspond to the full-scale diameter, in meters.

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554 Table 2. Best-fit and geotechnical parameters under undrained condition, estimated based on the proposed approach.

Reference	Test ID	$R_f^*$	Best-fit parameters		n	Standard Error (SE)		$R^2$	RMSE	Geotechnical parameters	
			$a_s D$	$b_s$		$P$ (kPa)	$S_{max}$ (mm)			$E_{ur}$ (kPa)	$S_u$ (kPa)
Lee and Rowe (1989)	2DP	0.54	0.01040	0.01180	21	4.5934	0.3751	0.993	0.142	3462	22.8
	2DH	0.50	0.01690	0.01050	8	7.9040	0.5666	0.988	0.151	3550	23.8
Osman <i>et al.</i> (2006)	2DP	0.54	0.01740	0.01190	20	4.7783	0.6407	0.995	0.198	3448	22.6
	2DT	0.54	0.00890	0.01355	18	4.4887	0.3796	0.988	0.171	4045	19.9
Divall <i>et al.</i> (2016)	FP2	0.45	0.00422	0.00665	115	3.4845	0.0877	0.996	0.056	11848	33.8
	FP3		0.00525	0.00699	94	3.6095	0.1039	0.994	0.079	4762	32.2
	FP4		0.00395	0.00715	65	4.6069	0.1523	0.833	0.497	12658	31.5
	FP5		0.00199	0.00568	141	4.8731	0.1676	0.915	0.577	25126	39.6
	FP6		0.00525	0.00722	74	4.2731	0.1440	0.993	0.102	9524	31.2
	FP7		0.00118	0.00596	155	3.6571	0.0320	0.966	0.074	42373	37.1
	FP8		0.00655	0.00687	112	3.3305	0.0942	0.994	0.076	7634	32.8
	FP9		0.00545	0.00602	70	4.8642	0.1302	0.995	0.074	9174	37.4

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563     Table 3. Mean and CoV values of maximum surface settlement and applied TBM support pressure between HSP and SCR stations.

Section number	Monitoring sections	S <sub>max</sub> (mm)	P (kPa)
1	SC_19+138	1.6	224.00
2	SC_19+162	1.6	237.00
3	SC_19+187	2.3	239.00
4	SC_19+210	1.9	265.00
5	SC_19+234	0.6	260.00
6	SC_19+260	0.7	246.00
7	SC_19+336	3.5	211.00
8	SC_19+400	4.7	199.00
9	SC_19+415	3.5	199.00
10	SC_19+438	3.0	203.00
11	SC_19+461	2.6	207.00
12	SC_19+486	2.7	215.00
13	SC_19+512	3.5	227.00
14	SC_19+560	1.4	238.00
15	SC_19+581	1.6	235.00
16	SC_19+634	3.4	249.00
17	SC_19+658	4.0	239.00
18	SC_19+682	4.8	240.00
19	SC_19+708	3.7	232.00
$\mu$		2.7	229.74
$\sigma$		1.3	19.66
CoV	(%)	48.15	8.56

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567 Table 4. Input geotechnical parameters between HSP and SCR stations (after Franco et al., 2019).

Geotechnical parameters		3A <sub>gp1</sub>	3A <sub>g1.2</sub>	3A <sub>r1.2</sub>	4A <sub>g1</sub>
$\gamma$	kN/m <sup>3</sup>	16.6	18.5	19.5	20.2
$c'$	kPa	18	40	7	80
$j'$	deg	24	24	32	26
$E$	MPa	20	120	185	230
$n$	-	0.26	0.30	0.31	0.28
$k_0$	-	0.67	0.93	0.82	0.90

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## Figures

Figure 1. Typical representation of transverse surface settlement.

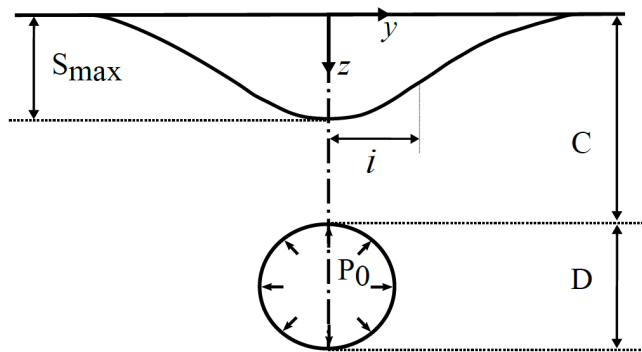


Figure 2. Sources of longitudinal ground movements due to TBM tunnelling.

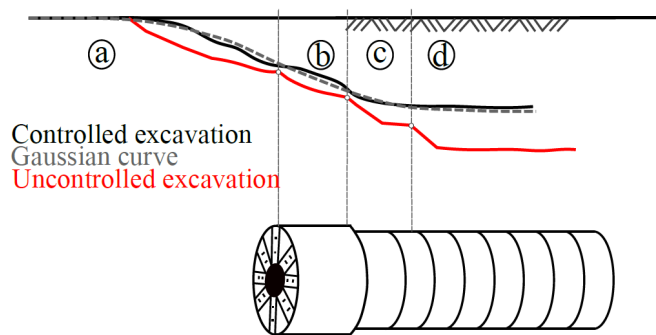


Figure 3. Comparison of stress paths: a) tunnel excavation producing reduced triaxial extension; b) conventional triaxial compression; c) settlement curve caused by tunneling; d) triaxial loading curve; and e) shear strength envelope.

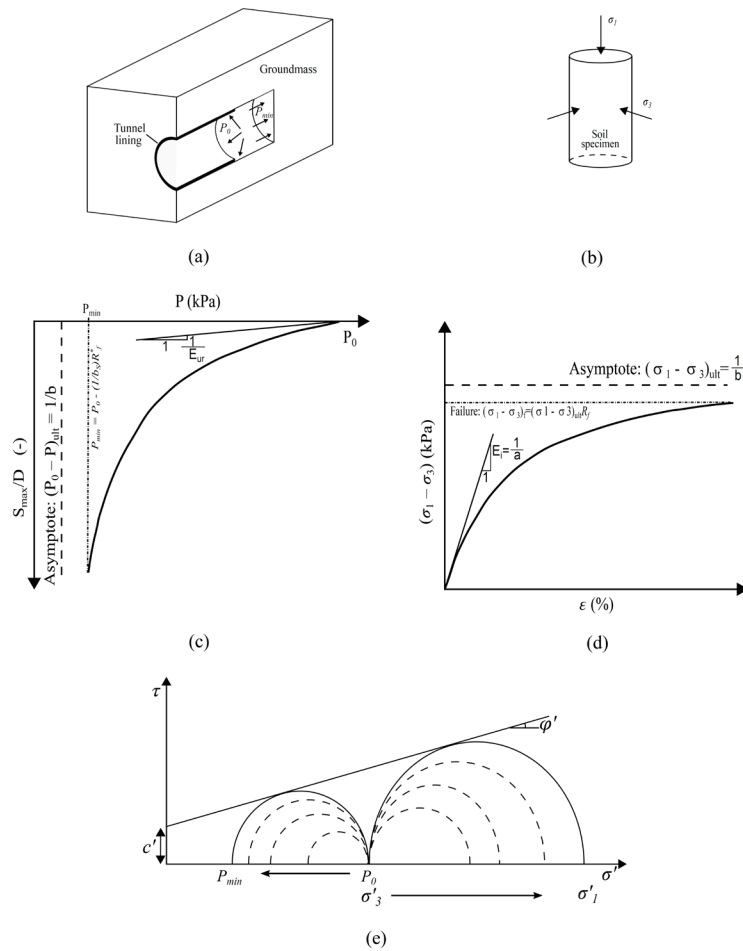


Figure 4. Relationships between maximum surface settlement,  $S_{max}$ , and the fitting parameters: a)  $a_S$ ; and b)  $b_S$ .

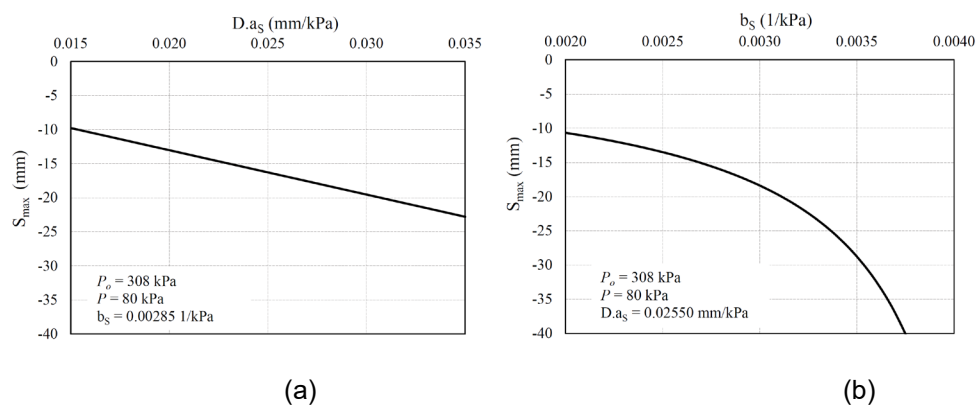


Figure 5. Surface settlement data from Lee and Rowe (1989) and corresponding best-fit modelling.

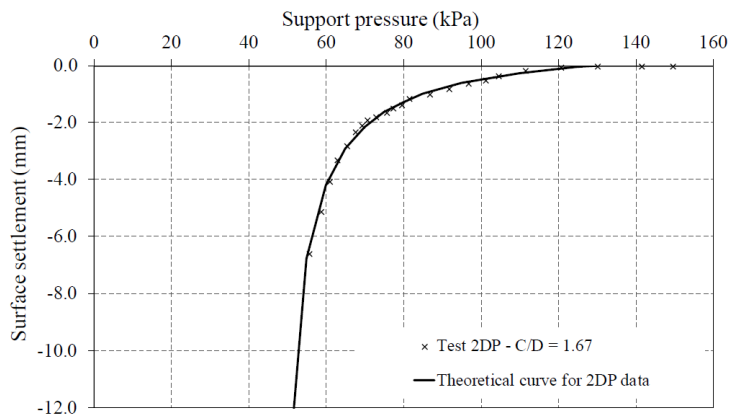


Figure 6. Surface settlement data from Osman et al. (2006) and corresponding best-fit modelling.

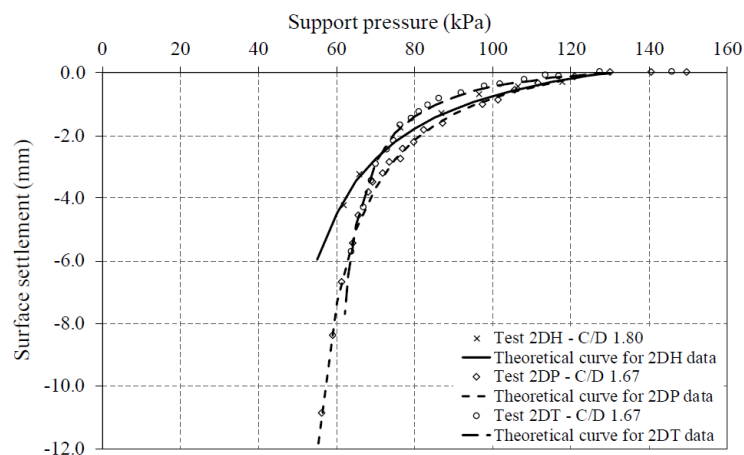


Figure 7. Surface settlement data for the different forepoling arrangements in centrifuge tests from Divall et al. (2016) and corresponding best-fit modelling: a) FP4 and FP8; b) FP2 and FP6; c) FP5 and FP7; d) FP3 and FP9.

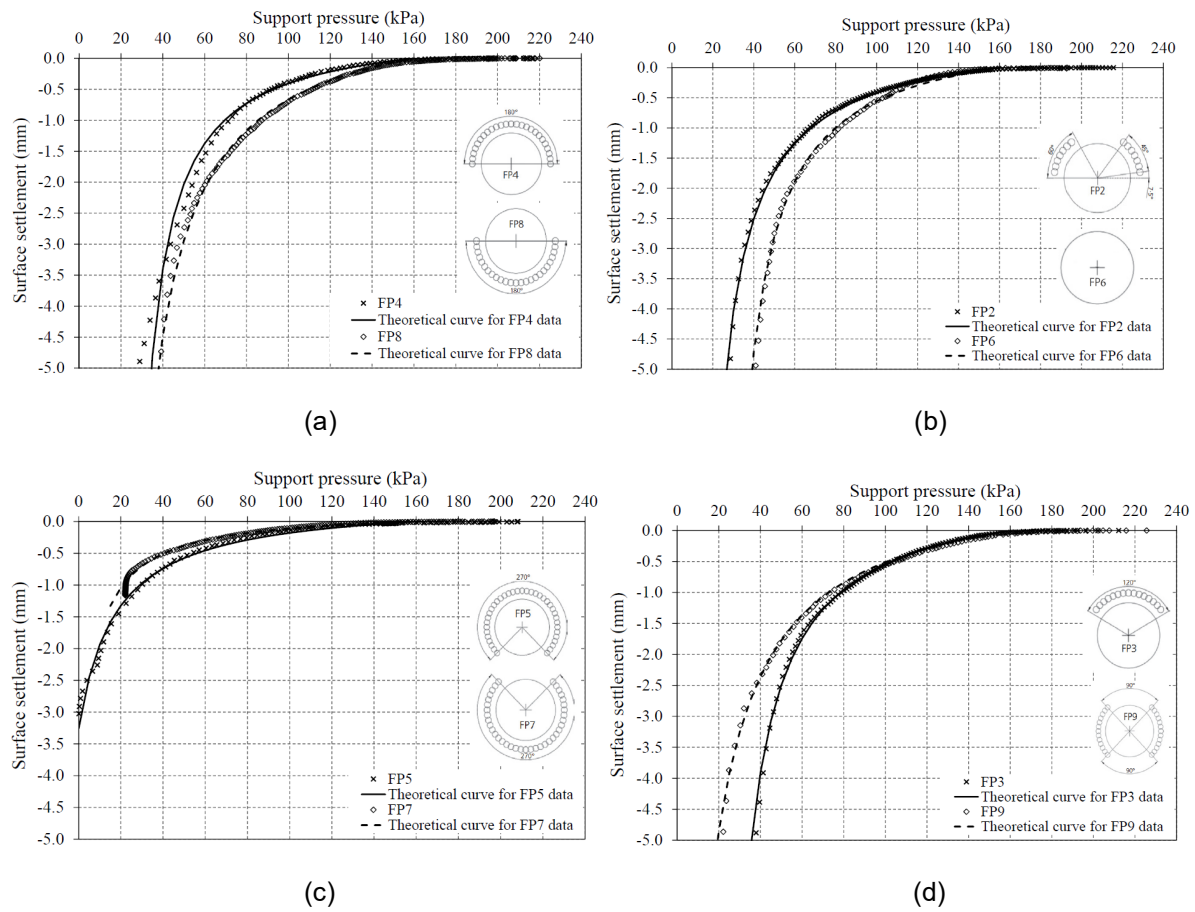


Figure 8. Metro stations layout of Line 5.

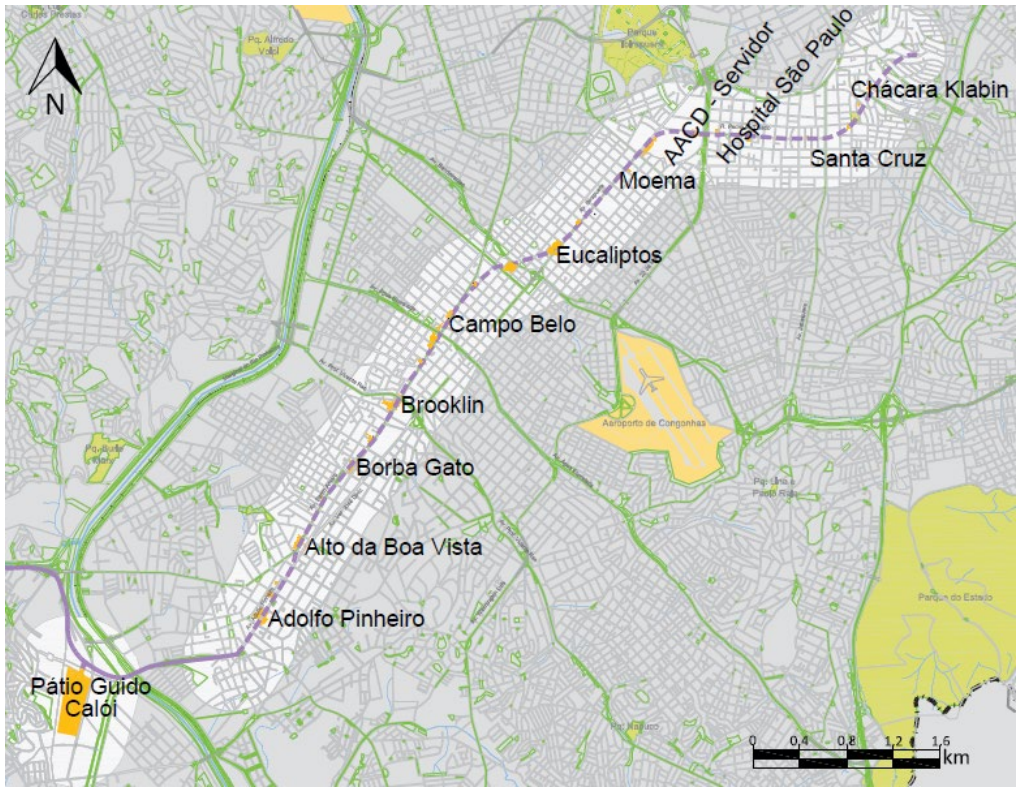
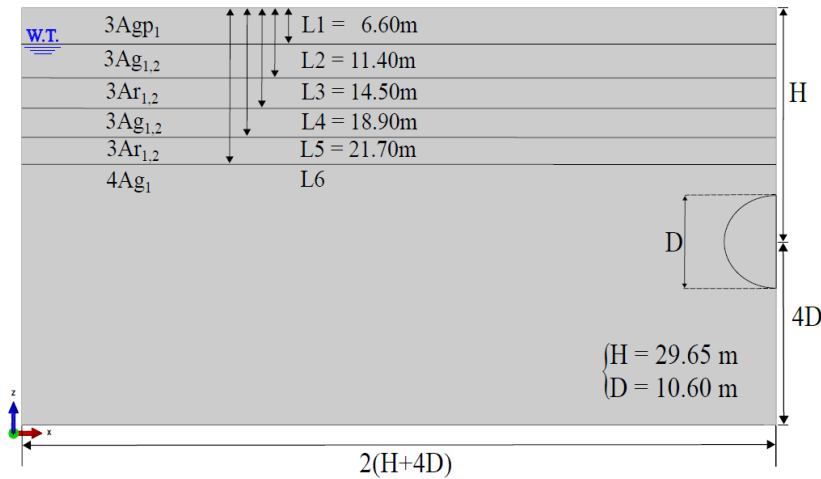
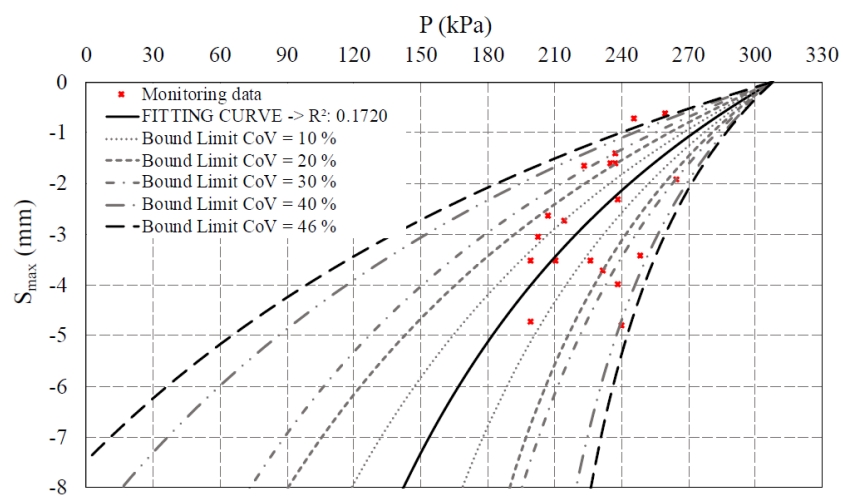


Figure 9. Tunnel model geometry (modified from Franco et al., 2019).



652 Figure 10. Upper and lower bounds of  $S_{max}$  between stations HSP and SCR.



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